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Multiple phoretic mechanisms in the self-propulsion of a Pt-insulator Janus swimmer

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We present a detailed theoretical study which demonstrates that electrokinetic effects can also play a role in the motion of metallic-insulator spherical Janus particles. Essential to our analysis is the identification of the fact that the reaction rates depend on Pt-coating thickness and that the thickness of coating varies from pole to equator of the coated hemisphere. We find that their motion is due to a combination of neutral and ionic diffusiophoretic as well as electrophoretic effects whose interplay can be changed by varying the ionic properties of the fluid. This has great potential significance for optimising performance of designed synthetic swimmers.

Key ideas: (1.) non-uniform reaction rates due to Pt-coating thickness variation, (2.) charged intermediates in the H₂O₂ catalysis by the Platinum.

Key words: propulsion, micro-/nano-fluid dynamics.

1. Introduction

In recent years there has been a flurry of activity in developing micro- and nanoscale self-propelling devices that are engineered to produce enhanced motion within a fluid environment (Kapral 2013). They are of interest for a number of reasons, including the potential to perform transport tasks (Patra et al. 2013), and exhibit new emergent phenomena (Marchetti et al. 2013; Volpe et al. 2011; Theurkauff et al. 2012; Palacci et al. 2013; Kümmer et al. 2013; Bricard et al. 2013). A variety of subtly different methods, all based on the catalytic decomposition of dissolved fuel molecules, have been shown to produce autonomous motion, or swimming. Commonly studied systems are catalytic bimetallic rod shaped devices (Kline et al. 2005b) and metallic-insulator spherical Janus particles that are half-coated with catalyst (e.g. Platinum) for a non-equilibrium reaction (e.g. the decomposition of Hydrogen Peroxide) (Howse et al. 2007) [see Figure 1 (a)]. The propulsion mechanism is thought to be phoretic in nature (Anderson 1989; Golestanian et al. 2007), but many specific details, such as which type of phoretic mechanism drive propulsion, remain the subject of debate (Golestanian et al. 2007; Gibbs & Zhao 2009; Brady 2011; Moran & Posner 2011). A fundamental understanding of the mechanisms is key for developing the knowledge of how to use and control them in applications, and how to build up a picture of the collective behaviour through implementation of realistic interactions between catalytic colloids.
For bimetallic swimmers, a plausible proposal is that the two metallic segments, usually platinum and gold, electrochemically reduce the dissolved fuel, in a process that results in electron transfer across the rod (Paxton et al. 2005; Kagan et al. 2009). This together with proton movement in the solution (Farniya et al. 2013) and the interaction between the resulting self-generated electric field and the charge density on the rod produces (self-electrophoretic) motion (Moran & Posner 2011). The direction of travel and swimming speed for arbitrary pairs of metals are well understood in the context of this mechanism (Wang et al. 2006), as well as the link between fuel concentration and velocity (Sabass & Seifert 2012). For Pt-insulator Janus particles, the absence of conduction between the two hemispheres suggests a mechanism independent of electrophoresis. Hence, a natural first proposal is that a self-generated gradient of product and reactants can lead to motion via self-diffusiophoresis (Golestanian et al. 2005), provided the colloid is sufficiently small (Gibbs & Zhao 2009). A number of predictions have been made based on this mechanism (Golestanian et al. 2005; Rückner & Kapral 2007; Sabass & Seifert 2010; Valadares et al. 2010; Popescu et al. 2009; Brady 2011; Sharifi-Mood et al. 2013) which have to date shown good agreement with the experimental dependency of swimming velocity on the size of the colloid (Ebbens et al. 2012), and fuel concentration (Howse et al. 2007). It would thus appear that a key difference between the bimetallic and metallic-insulator Janus particles is that the motility in the latter system does not require conduction or electrostatic effects. However recent experiments have raised the possibility that this assumption might not be completely correct (Ebbens et al. 2014; Brown & Poon 2014; Das et al. 2015).

Here we present a detailed theoretical study which demonstrates however that electrokinetic effects (Pagonabarraga et al. 2010) can also play a role in the motion of metallic-insulator spherical Janus particles expanding on our previous analyses briefly presented in (Ebbens et al. 2014). We find that their motion is due to a combination of neutral and ionic diffusiophoretic as well as electrophoretic effects whose interplay can be changed by varying the ionic properties of the fluid (see Fig. 8). This has great potential significance as the effect on the swimming behaviour, of solution properties such as temperature (Balasubramanian et al. 2009), contaminants (Zhao et al. 2013), pH, and salt concentration are of critical importance to potential applications (Patra et al. 2013).

We consider a Janus polystyrene (insulating) spherical colloid of radius \( a \), half coated by a Platinum (conducting) shell. It is known that such colloids are active i.e. self-propel in hydrogen peroxide solution. This is due to gradients generated by the asymmetric decomposition of \( \text{H}_2\text{O}_2 \) on the Pt-coating and the interaction of the reactants and products with the sphere surface. In the rest of the paper we will call this process self-phoresis.

Generically the catalytic decomposition of the hydrogen peroxide by the Platinum catalyst is given by

\[
\text{Pt} + 2\text{H}_2\text{O}_2 \rightarrow \text{Intermediate-complexes} \rightarrow \text{Pt} + 2\text{H}_2\text{O} + \text{O}_2 ,
\]

however there is still some debate about the nature of the intermediate complexes Hall et al. (1998, 1999b,a); Katsoumaros et al. (2012).

In this article, we outline a detailed calculation of the self-phoresis problem. Our approach is guided by the well studied problem of a phoretic motion of a colloid in an externally applied concentration gradient or electric field. To model the effect of the non-equilibrium chemical reaction sketched above on the motion of the Janus particle, we study the concentration fields of all the species involved in the reaction. The half coating of the colloid by catalyst is reflected by inhomogeneous reactive boundary conditions on
its surface. The reaction involves the production of charged intermediates which can also lead to changes in the electric potential on the swimmer surface and hence the possibility of local electric fields. Our flexible calculation framework allows us to study a variety of different schemes for the reaction kinetics of the intermediate complexes. Using this we analyse in detail a scheme with both charged and uncharged pathways (see Appendix A) whose results are consistent with all the behaviour observed in the recent experiments.

2. The model

A Janus sphere of radius \( a \) has the catalytic reaction of hydrogen peroxide decomposition occurring on its Pt coated half. We choose without loss of generality that the normal to the plane splitting the hemispheres is aligned with the \( z \)-axis [see Figure 2]. We propose a theoretical framework based on generally accepted properties of the reaction scheme for Pt catalysis of \( \text{H}_2\text{O}_2 \) degradation to water and \( \text{O}_2 \) (Hall et al. 1998, 1999a,b). A key feature of our analysis of self-propulsion is that it takes account of the existence of charged intermediates within the catalytic reaction scheme, namely protons and that the reaction rates varies with the Pt coating thickness (see Figure 1).

The state of the system is therefore described by the local state of the Pt on the coated hemisphere, the electric potential, \( \Phi(\vec{r}) \), the fluid velocity, \( \vec{v}(\vec{r}) \), the local concentrations, \( \tilde{c}_{\text{hp}}(\vec{r}) \), \( \tilde{c}_o(\vec{r}) \), \( \tilde{c}_h(\vec{r}) \) of \( \text{H}_2\text{O}_2 \), \( \text{O}_2 \) and \( \text{H}^+ \) respectively, i.e. the various reactive species, and the local concentrations, \( \tilde{c}_{\text{oh}}(\vec{r}) \), \( \tilde{c}_s(\vec{r}) \) of hydroxide and salt ions, respectively. The background concentrations (far from the Janus sphere) of the salt, \( \text{H}_2\text{O}_2 \), \( \text{H}^+ \), and \( \text{OH}^- \) are \( c^\infty_s \), \( c^\infty_{\text{hp}} \), \( c^\infty_h \), \( c^\infty_{\text{oh}} \) respectively. Positions outside the Janus sphere (in the bulk) are represented by the vectors \( \vec{r} = (\bar{x}, \bar{y}, \bar{z}) \) (in Cartesian coordinates) while positions on the surface are parametrised by the unit vectors \( \hat{n} = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta) \). We note that the vector \( \vec{r} = (\bar{r}, \theta, \phi) \) and \( \hat{n} = \hat{e}_r \) in spherical polar coordinates. Each of the neutral species interacts non-electrostatically with the surface of the swimmer via a fixed short ranged potential energy \( \tilde{\Psi}_n(\vec{r}) \), that depends on the distance from the Janus sphere surface. The interaction range, \( L_{\text{eff}} \) is taken to be the same for all neutral species.
where we have defined $\bar{c}_q$, and the incompressible Navier-Stokes equations (Lamb 1932) for the fluid velocity $\bar{v}$, and $T$

drift-diffusion equations (Chandrasekhar 1943) for the neutral species, $\bar{c}_n$,

$$
\partial_t \bar{c}_n = -\nabla \cdot \bar{J}_n ; \quad \bar{J}_n = -D_n \nabla \bar{c}_n + \bar{u}_n \bar{c}_n ; \quad \bar{u}_n = \bar{v} - \frac{D_n z_n e}{k_B T} \bar{\nabla} \Psi_n ,
$$

Poisson’s equation (Jackson 1975) for the electric potential

$$
\nabla^2 \Phi = -\sum_q \frac{z_q e \bar{c}_q}{\epsilon} ,
$$

and the incompressible Navier-Stokes equations (Lamb 1932) for the fluid velocity

$$
\rho (\partial_t \bar{v} + \bar{v} \cdot \nabla \bar{v}) = \eta \nabla^2 \bar{v} - \nabla \bar{p} + \bar{f}(\bar{r}) ; \quad \nabla \cdot \bar{v} = 0 ,
$$

where $\bar{p}(\bar{r})$ is the hydrostatic pressure at $\bar{r}$, $\eta$ is the viscosity, $k_B$ Boltzmann constant and $T$ temperature, $D_i$ is the diffusion coefficient of $i$’th solute and $z_i$ its valency if charged. These equations together with the inhomogeneous boundary conditions (BC) on the surface of the Janus sphere and as $\bar{r} \rightarrow \infty$ (see next section) define a boundary value problem whose approximate solution is the subject of this paper.

We consider the system in the steady-state (time derivatives equal to zero), the dynamics of the fluid around the swimmer in the zero Reynolds number (Re= 0) limit of the Navier-Stokes equations for incompressible fluid flow. In this paper we restrict ourselves to zero Peclét number, equivalent to assuming that diffusion of the solutes occurs much faster than their convection by the flows generated by the Janus particle - very reasonable for the experimental systems we attempt to describe. Thus, the fluid velocity given by $\bar{v}(\bar{r}) = \bar{\omega}_r \hat{e}_r + \bar{v}_q \hat{e}_q$ obeys the Stokes equation, while the solute concentration fields $\bar{c}_q$, $\bar{c}_n$ are governed by the steady-state drift-diffusion equations.

$$
0 = \bar{\nabla} \cdot \bar{v} ,
$$

$$
0 = \nabla \cdot \bar{\Pi} + \bar{f} = \eta \nabla^2 \bar{v} - \nabla \bar{p} - \sum_{i \in \text{ions}} e z_i \bar{c}_i \nabla \Phi - \sum_{j \in \text{non-ions}} \bar{c}_j \nabla \Psi_j ,
$$

$$
0 = -\nabla \cdot \bar{J}_q ; \quad \bar{J}_q = -D_q \nabla \bar{c}_q - \frac{D_q z_q e \bar{c}_q}{k_B T} \nabla \Phi ; \quad q \in \text{ions} ,
$$

$$
0 = -\nabla \cdot \bar{J}_n ; \quad \bar{J}_n = -D_n \nabla \bar{c}_n - \frac{D_n \bar{c}_n}{k_B T} \nabla \Psi_n ; \quad n \in \text{non-ions} ,
$$

where we have defined $\bar{\Pi}(\bar{r}) = \eta \left( \nabla \bar{v} + \nabla \bar{v}^T \right) - p \bar{\delta}$, the local hydrodynamic stress tensor.

2.1. Equations of motion

The relevant equations are Nernst-Planck equations (Probstein 2003) for the concentration of charged species, $\bar{c}_q$,

$$
\partial_t \bar{c}_q = -\nabla \cdot \bar{J}_q ; \quad \bar{J}_q = -D_q \nabla \bar{c}_q + \bar{u}_q \bar{c}_q ; \quad \bar{u}_q = \bar{v} - \frac{D_q z_q e}{k_B T} \bar{\nabla} \Phi ,
$$

2.2. Boundary conditions

The hydroxide and the salt ions are not involved directly in the catalytic decomposition of the fuel (1.1) so we impose zero flux boundary conditions for their concentrations on
the surface of the Janus particle,
\[ \hat{n} \cdot \mathbf{J}_{oh}|_{r=a} = 0 = \hat{n} \cdot \mathbf{J}_{s, \pm}|_{r=a} . \] (2.9)

where the unit vector, \( \hat{n} = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta) = \hat{e}_r \) in spherical polar coordinates. We define a catalyst coverage function, \( K(\cos \theta) \) which is 1 on the Platinum hemisphere and zero on the polystyrene hemisphere,
\[ K(\cos \theta) = \begin{cases} 1, & 0 \leq \cos \theta \leq 1 \\ 0, & -1 \leq \cos \theta < 0 \end{cases} . \] (2.10)

The presence of protons as intermediates of the fuel decomposition reaction (1.1) and the the variation of the reaction rates across the Pt-coated hemisphere leads to non-zero flux boundary conditions for the proton concentration on the surface of the Janus sphere
\[ \hat{n} \cdot \mathbf{J}_h|_{r=a} = \mathbf{J}_h(\theta) K(\cos \theta) , \] (2.11)

where the proton current, \( \mathbf{J}_h \), varies with \( \theta \) (position along the Pt-coated hemisphere). The specific form of the proton current \( \mathbf{J}_h \) will depend on the details of the reaction kinetics (see section 2.4 and Appendix A). However, we note that \( \mathbf{J}_h > 0 \) implies a chemical reaction producing protons while \( \mathbf{J}_h < 0 \) implies a proton sink.

The fuel decomposition reaction involves the neutral species, \( \text{H}_2\text{O}_2 \) and \( \text{O}_2 \) giving rise to non-zero flux boundary conditions for their concentrations on the Janus-particle surface,
\[ \hat{n} \cdot \mathbf{J}_o|_{r=a} = \mathbf{J}_o(\theta) K(\cos \theta) , \] (2.12)
\[ \hat{n} \cdot \mathbf{J}_{hp}|_{r=a} = \mathbf{J}_{hp}(\theta) K(\cos \theta) , \] (2.13)

where \( \mathbf{J}_{hp}(\theta) < 0 \) indicates \( \text{H}_2\text{O}_2 \) decomposition while \( \mathbf{J}_o(\theta) > 0 \) indicates production of the \( \text{O}_2 \). Because of the variations in thickness of the Pt-coating, both \( \mathbf{J}_{hp}(\theta), \mathbf{J}_o(\theta) \), defined in Appendix A, are functions of position along the Pt-coated hemisphere.

All the concentrations, \( \bar{c}_i(\bar{r}) \) decay to their background values, \( \bar{c}_i^\infty \) as \( \bar{r} \to \infty \).

We have Dirichlet boundary conditions for the electric potential on the particle surface
\[ \bar{\Phi}(\bar{r} = a) = \bar{\varphi}_s(\theta) , \] (2.14)

where \( \bar{\varphi}_s \) is a possibly varying function over the swimmer surface. The potential, \( \bar{\varphi}_s \) will in general be pH-dependent and will also depend on the particular reaction scheme of catalytic fuel decomposition. For our analysis, it is sufficient to know the average value \( \langle \bar{\varphi}_s \rangle = \frac{1}{2\pi} \int d\cos \theta \bar{\varphi}_s(\theta) \) and in the following we take \( \bar{\varphi}_s \equiv \langle \bar{\varphi}_s \rangle \). The potential \( \bar{\varphi}_s \) can be related to the swimmer surface charge by double-layer models (Russel et al. 1992).

The boundary conditions for the fluid velocity field are
\[ \bar{\mathbf{v}}|_{r=a} = \bar{\mathbf{U}} + \bar{\Omega} \times \bar{r} ; \quad \bar{\mathbf{v}}(\bar{r} \to \infty) = 0 , \] (2.15)

where \( \bar{\mathbf{U}}, \bar{\Omega} \) are respectively the total linear and angular propulsion velocities of the swimmer. These are unknown and their calculation is the goal of this paper

2.3. Constraints

(Quasi-steady state condition) As we study the system in a quasi-steady state, this requires that the average proton current on the swimmer surface vanishes,
\[ \int_{\bar{r}=a} \mathbf{J}_h(\theta) K(\cos \theta) \sin \theta d\theta = 0 , \] (2.16)
and note that this also guarantees conservation of the surface charge (Moran & Posner 2011).

*(Swimming conditions)* We consider a freely swimming Janus particle with no external load on the colloid which requires that there is zero total force and torque on the swimmer:

\[
\mathbf{F} = \oint_{r=a} \mathbf{P} \cdot \hat{n} \, dS_p + \int \mathbf{f} dV_p = 0 ,
\]

\[
\mathbf{T} = \oint_{r=a} \mathbf{r} \times (\mathbf{P} \cdot \hat{n}) \, dS_p + \int \mathbf{r} \times \mathbf{f} dV_p = 0 ,
\]

where \(dS_p (dV_p)\) is the differential surface (volume) element. These two conditions uniquely determine both propulsion velocities \((\mathbf{U}, \Omega)\) (Anderson 1989).

The linearity of the Stokes equation and the limit of vanishing Peclêt number, mean that we can divide the linear and angular velocities into non-electric, i.e. neutral diffusiophoretic, (due to the terms on the rhs of equation (2.6) depending on the \(\tilde{\Psi}_j\)), and electric, i.e. ionic diffusiophoretic and electrophoretic, contributions (due to the terms on the rhs of equation (2.6) depending on \(\tilde{\Phi}\)), which can each be calculated separately,

\[
\mathbf{U} = \mathbf{U}^e + \mathbf{U}^d ,
\]

\[
\tilde{\Omega} = \tilde{\Omega}^e + \tilde{\Omega}^d ,
\]

where \((\mathbf{U}^e, \tilde{\Omega}^e)\) are electric and \((\mathbf{U}^d, \tilde{\Omega}^d)\) are non-electric. We expect (and indeed find) that the neutral diffusiophoretic contribution to the propulsion is much smaller than the electrophoretic contribution. While we will later briefly outline the calculation of the neutral diffusiophoretic contribution to the propulsion velocity in section 3.2, in this article we will focus on the electrophoretic and ionic diffusiophoretic contributions. Detailed calculations of the neutral diffusiophoretic contribution can be found in the literature (Anderson et al. 1982; Golestanian et al. 2005, 2007; Michelin & Lauga 2014).

Due to the axisymmetry of the swimmer and the constraint of zero torque (2.18), the angular velocity \((\tilde{\Omega})\) vanishes identically \((\tilde{\Omega}^e = 0, \tilde{\Omega}^d = 0)\). Therefore in the following we will only consider the swimmer velocity \(\mathbf{U}\).

2.4. Dependence of reaction rate constants on Pt-coating thickness

The cornerstone of our analysis in this paper is the identification of the fact that the reaction rate of \(\text{H}_2\text{O}_2\) decomposition depends on the Pt-coating thickness (Ebbens et al. 2014). A further observation is the well known presence of additional chemical pathways in the decomposition which involve charged intermediates, in particular protons, (Hall et al. 1998, 1999a, b). These charged intermediates, in conjunction with the variation of Pt-coating thickness, allow an electric current to be established in the Pt shell due to varying decomposition rates of the hydrogen peroxide on different parts of the shell. We approximate for simplicity that this thickness variation is linear in \(\cos \theta\), with a peak at the pole and the minimum at the equator,

\[
k_i(\theta) = k_i^{(0)} + \sum_l k_i^{(l)} P_l(\cos \theta) \simeq k_i^{(0)} + k_i^{(1)} \cos \theta ,
\]

where \(k_i(\theta)\) is the reaction rate ‘costant’ for \(i^{th}\) reaction step in reaction (1.1) above and \(P_n(x)\) is the Legendre polynomial of order \(n\). The Legendre moments \(k_i^{(l)} = (l + 1/2) \int_{-1}^{1} k_i(\theta) P_l(\cos \theta) d\cos \theta\). We assume weak variation \((k_i^{(1)} \ll k_i^{(0)})\) allowing us
to work perturbatively in the variation. As long as there is a competition between a neutral pathway and a pathway involving charged intermediates, conservation of charge in the steady-state requires that the varying reaction rates across the Pt-coating lead to establishment of electric currents in the Pt shell. This is described in detail for a particular reaction scheme involving protons in Appendix A, however the qualitative features of our results do not depend on the details of the scheme.

3. Analysis

Guided by current experiments, we analyse the coupled problem of the concentrations, electrostatic potential and fluid flow by considering situations in which the length-scale of the interactions (Debye screening length, $\kappa^{-1}$ for charged species and effective interaction range $L_{\text{eff}}$ for the neutral species) is small compared to the size (radius = $a$) of the swimmer. We verify a posteriori that this is indeed the case. The effective diffusiophoretic interaction range $L_{\text{eff}}$ for all the neutral solutes is defined $L_{\text{eff}}^2 = (\eta/\kappa T)\bar{\mu}_d^\parallel$, where $\bar{\mu}_d^\parallel = \kappa T \int_0^\infty \rho \left(1 - e^{-\bar{\Psi}/k_B T}\right) d\rho > 0$ is the characteristic diffusiophoretic mobility of the Janus particle. Hence the problem can naturally be viewed as one with two very separate length-scales with small parameters $\lambda = 1/(\kappa a), \chi = L_{\text{eff}}/a$ for charged and neutral species respectively. A robust bound for comparison with experiment would be $\lambda \leq 0.1$. A useful approach to multi-scale problems with a small parameter multiplying the differential operator of highest order, is the decomposition of the domain of the solution into a boundary layer, where the fields vary on the small $\mathcal{O}(\lambda)$ length-scale ($\mathcal{O}(\chi)$ for the diffusiophoretic contribution) and an outer domain where the characteristic length-scale is the size of the swimmer ‘$a’. To do this most efficiently, we group the dimensionful quantities into useful dimensionless groups whose variation determines the behaviour of the system.

3.1. Self-electrophoresis and ionic self-diffusiophoresis

In this section, we describe detailed calculations of the electrophoretic and ionic-diffusiophoretic contributions to the swimming velocity which is the main focus of the paper.
3.1.1. Dimensionless equations

We non-dimensionalize the equations as follows. The position vector $\bar{r}$ is measured in units of the swimmer size $a$, concentrations $\bar{c}_i$ in units of the steady-state background values $c_i^\infty$, electric potential $\bar{\Phi}$ in terms of the thermal voltage $(e\beta)^{-1}$ (with $\beta^{-1} = k_B T$, $k_B$ Boltzmann constant and $T$ temperature), ionic solute fluxes, $\bar{J}_i$, in terms of $D_i \sum |z_i|^2 c_i^\infty / a$, with $D_i$ the diffusion coefficient of $i$'th solute and $z_i$ its valency.

The fluid flow velocity $\bar{v}$ is rescaled by $\bar{v} = \epsilon / (e^2 \beta^2 \eta a)$, while the pressure $\bar{p}$ is rescaled by $\bar{p} = \epsilon / (e^2 \beta^2 a^2)$. Hence we express dimensionless quantities (without overbar) in terms of the dimensionful (with overbar):

$r = (x, y, z) = \bar{r} / a, \bar{c}_i = \bar{c}_i / c_i^\infty, \bar{\Phi} = e\beta \bar{\Phi}, \bar{v} = \bar{v} e^2 \beta^2 \eta a / \epsilon, \bar{p} = \bar{p} e^2 \beta^2 a / \epsilon$.

It is useful for us to define the dimensionless deviations of the solute concentrations, $C_i(r) \equiv c_i(r) - 1 = (\bar{c}_i / c_i^\infty) - 1$ from their bulk values. Hence we obtain the following dimensionless equations of motion:

(1) The steady-state equations for concentration differences of the charged species; protons $C_h$, hydroxide ions $C_{oh}$, and the salt $C_{s\pm}$,

$$\nabla \cdot J_i = 0; \quad J_i = -\nabla C_i - z_i (1 + C_i) \nabla \Phi ,$$

where $i \in \{h, oh, s\pm\}$. We consider only monovalent salts $|z_i| = 1$.

(2) The dimensionless Poisson’s equation for the electric potential $\Phi(r)$,

$$-\lambda^2 \nabla^2 \bar{\Phi} = \sum_{i\in\{h, oh, s\pm\}} Z_i C_i ,$$

(3.2)

(3) The dimensionless Stokes equations for the fluid velocity $v(r)$,

$$0 = \nabla \cdot v ,$$

$$0 = \nabla \cdot \Sigma = \nabla^2 v - \nabla p - \lambda^{-2} \sum_{i\in\text{ions}} Z_i C_i \nabla \Phi ,$$

(3.3)

(3.4)

where the dimensionless parameters $\lambda$ and $Z_i$ are defined as

$$\lambda^2 \equiv (\kappa a)^{-2}; \quad \kappa^{-2} = \frac{\epsilon k_B T}{e^2 \sum_j |z_j|^2 c_j^\infty} = \frac{1}{4\pi l_B \sum_j |z_j|^2 c_j^\infty}; \quad Z_i = \frac{z_i c_i^\infty}{\sum_j |z_j|^2 c_j^\infty} ,$$

(3.5)

$\epsilon$ the permittivity of the solvent, and $e$ is the electronic charge. $\kappa^{-1}$ is the Debye screening length and $l_B = e^2 / 4\pi \epsilon k_B T$ is the Bjerrum length (Russel et al. 1992). We note that the stress $\Sigma$ is the sum of the hydrodynamic stress tensor and the Maxwell stress tensor due to the interactions of the charged species with each other and the colloid surface.

The zero total force condition which determines the propulsion velocity $U^e$ becomes

$$F = \oint_{r=1} \Sigma \cdot \hat{n} \sin \theta \, d\theta = 0 .$$

(3.6)

3.1.2. Dimensionless boundary conditions

For the electric potential on the swimmer surface,

$$\Phi(r = 1) = \varphi_s ,$$

(3.7)

and decays to zero in the bulk far from the swimmer, $\Phi(r \to \infty) = 0$.

For the flow field on the swimmer surface,

$$v|_{r=1} = U^e ,$$

(3.8)
and \( \mathbf{v}(r \to \infty) = \mathbf{0} \) far in the bulk, where \( \mathbf{U}^e \) is the electric contribution to the propulsion velocity.

For the hydroxide and the salt concentrations, the zero flux boundary conditions due to the impermeability of the Janus particle surface,

\[
\mathbf{n} \cdot \mathbf{J}_{\text{oh}}|_{r=1} = \mathbf{n} \cdot \mathbf{J}_{s,\pm}|_{r=1} = 0.
\]

For the proton concentration, the non-zero flux boundary condition,

\[
\mathbf{n} \cdot \mathbf{J}_h|_{r=1} = \mathbf{J}_h(\theta) K(\cos \theta),
\]

The essential mechanism which drives this process depends on the presence of a (1) varying proton flux (as a result of variation of Pt thickness) which (2) averages to zero over the metallic hemisphere (due to charge conservation in the steady-state). In the limit of small linear variation in the thickness, this leads to a proton flux of the general form

\[
J_h(\theta) = \gamma^{(1)} (1 - 2 \cos \theta) K(\cos \theta) - \gamma^{(0)} \delta (\Phi + C_h) K(\cos \theta),
\]

where both \( \gamma^{(i)} \neq 0 \). We note that \( \gamma^{(1)} = 0 \) for a uniform thickness coating, and \( \delta (\Phi + C_h) = [(\Phi + C_h) - \int_0^\pi (\Phi + C_h) K(\cos \theta) \sin \theta d\theta] \) is the deviation of the local electric field and proton concentration from their surface average. \( \gamma^{(0)} \) is a measure of the scale of typical production and consumption of protons across the metallic hemisphere. Since both terms on the rhs of eqn. (3.11) integrated over the surface give zero, the flux, \( J_h \) automatically satisfies the steady state requirement (2.16) and hence the conservation of total charge on the swimmer surface.

Systems which possess both properties above, with both \( \gamma^{(i)} > 0 \), will show all the qualitative behaviours described in this article, however their values will depend on the specific details of the chemical reaction scheme. A specific reaction scheme described in detail in Appendix A gives:

\[
\gamma^{(0)} = \frac{k_{\text{eff}}^{(h)} c_{\text{hp}}^\infty a}{D_h \sum_i c_i^\infty}; \quad \gamma^{(1)} = \frac{\Delta k_{\text{eff}}^{(h)} c_{\text{hp}}^\infty a}{D_h \sum_i c_i^\infty}.
\]

\( k_{\text{eff}}^{(h)} > 0 \) is the typical scale of the average proton consumption and production while \( \Delta k_{\text{eff}}^{(h)} > 0 \) is the scale of the difference between the rates at the pole and equator (see Appendix A for their derivation from reaction kinetics).

We note that the conservation of protons also requires a relationship between the pH of the solution and the potential on the surface of the Janus particle, which depends on the reaction kinetics (see Appendix A);

\[
\varphi_s = \varphi_s(c_h^\infty),
\]

leading to an estimate of the average swimmer surface charge \( (\sigma_0(c_h^\infty)) \) using the Gouy-Chapman model (Russel et al. 1992) of the interfacial double layer

\[
\sigma_0(c_h^\infty) = \frac{e \kappa}{2 \pi l_B} \sinh \left( \frac{\varphi_s}{2} \right),
\]

where \( l_B = e^2/4\pi\kappa k_B T \) is the Bjerrum length, with \( \kappa \) the solution permittivity.

In this electrostatic problem, the inner boundary-layer (double layer) fields, \( H(r) \in \{c_i(r), \mathbf{v}(r), \Phi(r)\} \) are expanded as

\[
H(r, \theta) = \sum_n \lambda^n H^{(n)}(\rho, \theta); \quad \rho = \frac{r - 1}{\lambda},
\]
while the outer fields, $H(r) \in \{ c_i(r), v(r), \Phi(r) \}$ are expanded as

$$H(r, \theta) = H^{(0)}(r, \theta) + \sum_{n=1}^{\infty} \lambda^n H^{(n)}(r, \theta),$$

(3.16)

where $r$ is the bulk-scale coordinate. Similar expansions will apply for the self-diffusiophoretic problem, with $\lambda$ replaced by $\chi$.

The essence of the matched asymptotic method involves obtaining asymptotic expansions of the solutions of the equations in the limit $\lambda \to 0$ for both the inner and outer fields and matching the results in the intermediate region:

$$\lim_{\lambda \to 0; \rho \to \infty} \{ H^{(0)}_i \} (\rho, \theta) = \lim_{r \to 1; \lambda \to 0} \{ H^{(0)}_i \} (r, \theta) = \{ H_i \}(1, \theta).$$

(3.17)

In the next section, we will proceed to solve the outer problem in the limit of $\lambda = (\kappa a)^{-1} \to 0$, i.e. thin double-layer limit where the swimmer radius $a$ is much larger than the Debye-layer thickness $\kappa^{-1}$. The details of the inner (Debye-layer) calculations (Prieve et al. 1984; Yariv 2011) can be found in the Appendix B (see Figure 3).

### 3.1.3. Outer concentration and electric fields

In the bulk, the fields vary over length-scales comparable to the the swimmer size, with $O(1)$ leading order fields and are expanded as

$$H(r, \theta) = H^{(0)}(r, \theta) + \lambda H^{(1)}(r, \theta) + \cdots.$$  

(3.18)

We drop the $^{(0)}$ superscript in the following as we will consider only the leading order terms $C^{(0)}, \Phi^{(0)}, v_i^{(0)}, p^{(0)}$, in the expansions for the fields.

The leading order solute concentrations and electric potential outside the Debye-layer obey the equations

$$\sum_{i \in \{h, oh, s\}} Z_i C_i = 0,$$

(3.19)

$$\nabla \cdot [\nabla C_i + z_i (1 + C_i) \nabla \Phi] = 0,$$

(3.20)
Self-phoresis of a Pt-insulator Janus swimmer

Figure 4. (a) Proton concentration deviation from the uniform background profile and (b) associated electric potential difference contours (both plots with pH = 5.5 for 10% H₂O₂ without salt and the system parameters in table (1)). The equipotential contours 0.0066 and −0.0227 (in units of the thermal voltage \(k_B T/e \approx 25\text{mVolts} \)) are shown to indicate the electric pole-equator polarity. In both figures, the upper (dark) hemisphere is the Platinum cap.

where \(Z_i\) is defined in equation (3.5). It is useful for the rest of our analysis to treat all the ionic solutes together. Combining the two equations (3.19,3.20), we obtain,

\[
\nabla^2 C^* = 0 \quad ,
\]
\[
\nabla \cdot (C^* \nabla \Phi) = 0 \quad ,
\]

where we have defined the sum of the deviations of concentration of all of the ionic solutes and its value at \(r = 1\).

\[
C^*(r, \theta) = 2 \sum_{i \in \{n, s\}} Z_i (1 + C_i(r, \theta)) ;
\]
\[
C_s^*(\theta) \equiv C^*(r = 1, \theta) .
\]

The boundary conditions for \(\Phi\) and \(C^*\) are obtained by matching to the inner solutions (see Appendix B), giving

\[
- \hat{n} \cdot \nabla C^*|_{r=1} = \gamma^{(1)} (1 - 2 \cos \theta) K(\cos \theta) - \gamma^{(0)} \delta (\Phi + C_n) K(\cos \theta) ,
\]
\[
- \hat{n} \cdot (C^* \nabla \Phi)|_{r=1} = \gamma^{(1)} (1 - 2 \cos \theta) K(\cos \theta) - \gamma^{(0)} \delta (\Phi + C_n) K(\cos \theta) ,
\]

from eqns. (3.10) and (3.11).

The fluid velocity field in the outer region obeys the equation

\[
\nabla^2 v - \nabla p + \nabla^2 \Phi \nabla \Phi = 0 ,
\]

with the slip boundary condition (Prieve et al. 1984)

\[
v(1, \theta) = U^e + \left[ \zeta(\theta) \frac{\partial \Phi}{\partial \theta} + 4 \ln \cosh \left( \frac{\zeta(\theta)}{4} \right) \frac{\partial \ln C_s^*}{\partial \theta} \right] \hat{e}_\theta ,
\]

and quiescent fluid far away from the swimmer, \(v \to 0\) as \(r \to \infty\). The slip boundary condition for \(v\) is obtained by matching to the inner solution (see Appendix B).
3.1.4. Linear response and propulsion velocity

We note that with uniform coating, \( k_i = k^{(0)}_i \), which implies \( \gamma^{(1)} = 0 \), the deviations of the electric potential and the ionic concentrations vanish (\( \Phi = 0 = C_i \)). The zeta potential for this trivial solution is

\[
\zeta_0 := \zeta = \varphi_s . \tag{3.29}
\]

In addition, this implies the fluid velocity field vanishes \( v = 0 \), and hence the contribution of self-electrophoresis to the propulsion velocity vanishes \( U^e = 0 \). However, a varying thickness coating and the consequent non-zero \( \gamma^{(1)} \), lead to a qualitatively different scenario. To explore this we perform an expansion to linear order in \( \gamma^{(1)}/\gamma^{(0)} \) of the fields for the concentrations, fluid velocity, pressure and electric potential:

\[
\{ C_i, v, p, \Phi \}
\]

for \( \gamma^{(1)} \ll \gamma^{(0)} \), where \( \gamma^{(1)}, \gamma^{(0)} \) are defined in equation (3.12).

We first expand the deviations of the concentrations and the electric field as

\[
H = \gamma^{(1)} H^{(\gamma)} + \mathcal{O} \left( (\gamma^{(1)})^2 \right), \tag{3.30}
\]

with \( H \in \{ C_i, \gamma^{(1)} \} \) and keeping only linear terms. Substituting these perturbative fields into eqns. (3.21,3.22), we find that at leading order, \( C^{* (\gamma)} \) decouples from the electric potential field \( \Phi^{(\gamma)} \) - with both obeying Laplace equations

\[
\nabla^2 C^{* (\gamma)} = 0 , \tag{3.31}
\]

\[
\nabla^2 \Phi^{(\gamma)} = 0 , \tag{3.32}
\]

and the boundary conditions, from the matching with the inner solution, at this order are

\[
- \hat{n} \cdot \nabla C^{* (\gamma)} \bigg|_{r=1} = - \hat{n} \cdot \nabla \Phi^{(\gamma)} \bigg|_{r=1} = (1 - 2x) K(x) - \gamma^{(0)} \delta(\Phi^{(\gamma)} + C^{* (\gamma)}) K(x) , \tag{3.33}
\]

where \( x = \cos \theta, \delta(\Phi^{(\gamma)} + C^{* (\gamma)}) = \left[ (\Phi^{(\gamma)} + C^{* (\gamma)}) - \int_0^1 (\Phi^{(\gamma)} + C^{* (\gamma)}) dx \right] \).

Now, the Laplace equations above for \( C^{* (\gamma)}, \Phi^{(\gamma)} \) in conjunction with the electroneutrality condition (3.19) imply (see Figure 4)

\[
\Phi^{(\gamma)}(r, \theta) = C^{* (\gamma)}(r, \theta) \equiv C^{* (\gamma)}(r, \theta) - 1 = \sum_{l=0}^{\infty} A_l r^{-(l+1)} P_l(\cos \theta) , \tag{3.34}
\]

where \( P_l(\cos \theta) \)'s are the Legendre polynomials. The unknown coefficients \( A_l \)'s are determined by the boundary conditions in equation (3.33) above.

Finally, the coefficients \( A_l \) are obtained as a self-consistent system of equations,

\[
\sum_{l=0}^{\infty} A_l (l+1) P_l(x) = (1 - 2x) K(x) - 2 \gamma^{(0)} \sum_{l=0}^{\infty} A_l \left( P_l(x) - \int_0^1 P_l(x') dx' \right) K(x) , \tag{3.35}
\]

where \( x = \cos \theta \).

Using the orthogonality of the Legendre polynomials, we obtain a linear system of equations for the coefficients \( A_l \)'s,
Figure 5. (a) The deviations of the surface electric potential, $\Phi(1, \theta)$, and ionic concentrations, $C_h(1, \theta)$, $C_s^*(1, \theta) - 1$, from the uniform background values (for swimmer size $a = 1.00 \mu m$). We show the convergence of the solution as the number $N$ of the Legendre modes in eqn. (3.34) are increased, i.e $A = \{A_0, \cdots, A_{N-1}, A_N\}$. (b) The deviations of the surface potential and ionic concentration as a function of swimmer size $a$ (truncating at $N = 40$).

\[
\begin{pmatrix}
1 & 0 & 0 & \cdots & 0 & \cdots \\
0 & M_{11} & M_{12} & \cdots & M_{1l} & \cdots \\
0 & M_{21} & M_{22} & \cdots & M_{2l} & \cdots \\
\vdots & \vdots & \vdots & \ddots & \vdots & \ddots \\
0 & M_{n1} & M_{n2} & \cdots & M_{nl} & \cdots \\
\vdots & \vdots & \vdots & \ddots & \vdots & \ddots \\
\end{pmatrix}
\begin{pmatrix}
A_0 \\
A_1 \\
A_2 \\
\vdots \\
A_l \\
\vdots \\
A_n \\
\end{pmatrix}
= 
\begin{pmatrix}
0 \\
A_1 \\
A_2 \\
\vdots \\
A_l \\
\vdots \\
A_n \\
\end{pmatrix}
\]

or more compactly

\[
M \cdot A = A,
\]

where $A = (A_0, \ldots, A_N, \ldots)$, and the matrix $M$ and vector $A$ entries are given by

\[
M_{nl} = \delta_{nl} + \gamma^{(0)} \left( \frac{2n+1}{n+1} \right) \int_0^1 P_n(x) \left( P_l(x) - \int_0^1 P_l(x') dx' \right) dx,
\]

\[
A_n = \frac{1}{2} \left( \frac{2n+1}{n+1} \right) \int_0^1 (1 - 2x) P_n(x) dx.
\]

The infinite linear system of equations (3.36) above can be solved approximately by truncating the infinite system after a finite number of components, reducing the description to the first $N$ Legendre coefficients $A_l$’s. The approximate (numerical) solution requires inversion of an $N \times N$ matrix $M$ (see Figure 5). However, we can extract asymptotic regimes of this solution for $\gamma^{(0)} \ll 1$ and $\gamma^{(0)} \gg 1$. Note that $\gamma^{(1)} \ll \gamma^{(0)}$ in both limits.

$\gamma^{(0)} \ll 1$: In this regime, $A_l \sim A_l$ and

\[
A_1 \sim -\frac{1}{8}
\]

(3.40)
Table 1. System parameters

<table>
<thead>
<tr>
<th>Description</th>
<th>Symbol</th>
<th>Value</th>
<th>Units (SI)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Boltzmann energy scale (at 300 K)</td>
<td>$k_B T$</td>
<td>$4.05 \times 10^{-21}$</td>
<td>J</td>
</tr>
<tr>
<td>Permittivity (water)</td>
<td>$\epsilon$</td>
<td>$6.90 \times 10^{-10}$</td>
<td>CV$^{-1}$m$^{-1}$</td>
</tr>
<tr>
<td>Electronic charge</td>
<td>$e$</td>
<td>$1.60 \times 10^{-19}$</td>
<td>C</td>
</tr>
<tr>
<td>Average surface charge density (at zero salt conc.)</td>
<td>$\sigma_0$</td>
<td>$1.60 \times 10^{-3}$</td>
<td>Cm$^{-2}$</td>
</tr>
<tr>
<td>Viscosity of water (at 300K)</td>
<td>$\eta$</td>
<td>$8.9 \times 10^{-4}$</td>
<td>Nm$^{-2}$s$^{-1}$</td>
</tr>
<tr>
<td>Diffusiophoretic characteristic mobility</td>
<td>$\bar{\mu}_d$</td>
<td>$4.57 \times 10^{-38}$</td>
<td>m$^5$s$^{-1}$</td>
</tr>
<tr>
<td>Peroxide [H$_2$O$_2$] diffusion coefficient</td>
<td>$D_{hp}$</td>
<td>$6.60 \times 10^{-10}$</td>
<td>m$^2$s$^{-1}$</td>
</tr>
<tr>
<td>Oxygen [O$_2$] diffusion coefficient</td>
<td>$D_o$</td>
<td>$2.00 \times 10^{-9}$</td>
<td>m$^2$s$^{-1}$</td>
</tr>
<tr>
<td>Protons [H$^+$] diffusion coefficient</td>
<td>$D_h$</td>
<td>$9.30 \times 10^{-9}$</td>
<td>m$^2$s$^{-1}$</td>
</tr>
<tr>
<td>Swimmer radius</td>
<td>$a$</td>
<td>$1.00 \times 10^{-6}$</td>
<td>m</td>
</tr>
<tr>
<td>H$<em>2$O$<em>2$ decomposition reaction rate ($K := k</em>{hp}^{(K)} c</em>{hp}$)</td>
<td>$K$</td>
<td>$3.00 \times 10^{-22}$</td>
<td>m$^{-2}$s$^{-1}$</td>
</tr>
<tr>
<td>(Ebbens et al. 2014; Brown &amp; Poon 2014)</td>
<td>$c_{hp}^{(K)}$</td>
<td>$1.76 \times 10^{27}$</td>
<td>m$^{-3}$</td>
</tr>
<tr>
<td>10% w/v H$_2$O$_2$ number concentration</td>
<td>$c_{hp}^{(K)}$</td>
<td>$1.00 \times 10^{20}$</td>
<td>m$^{-2}$s$^{-1}$</td>
</tr>
<tr>
<td>Effective proton absorption/release rate ($\sim 0.3% K$)</td>
<td>$k_{hp}^{(K)}$</td>
<td>$2.70 \times 10^{19}$</td>
<td>m$^{-2}$s$^{-1}$</td>
</tr>
<tr>
<td>Proton pole-to-equator rate ‘difference’ ($\sim 0.09% K$)</td>
<td>$\Delta k_{hp}^{(K)}$</td>
<td>$1.10 \times 10^{-6}$</td>
<td>m$^{-2}$s$^{-1}$</td>
</tr>
</tbody>
</table>

γ(0) ≫ 1: In this regime,

\[ A_1 \sim -\frac{\alpha}{\gamma(0)} \quad (3.41) \]

where \( \alpha \) is a positive constant whose value can be determined numerically. The asymptotes show that the perturbations of \( C_i \) and \( \Phi \) decay to zero for large \( \gamma(0) \) (proportional to swimmer size) - when the diffusion time becomes large compared to the reaction time.

In Fig.5(a), the deviations of the proton concentration \( C_h^{(\gamma)}(1, \theta) \) and electric potential \( \Phi^{(\gamma)}(1, \theta) \) on the surface from their bulk values are plotted showing the excess at the equator and depletion at the pole. Increasing the number of Legendre polynomial modes \( (N) \) improves the accuracy of the fields on the polystyrene hemisphere. The proton depletion (excess) at the pole (equator) is stronger for larger swimmer sizes (see Fig. 5(b)).

The calculated coefficients \( A_i \)'s above determine the slip velocity and we can now solve the Stokes flow problem. Hence, as above, we expand the velocity and pressure fields about the trivial solution \( v = 0 \), \( p = p_\infty \),

\[ v = \gamma^{(1)} v^{(\gamma)} + \cdots \quad (3.42) \]
\[ p - p_\infty = \gamma^{(1)} p^{(\gamma)} + \cdots \quad (3.43) \]

and the propulsion velocity about the stationary colloid, \( U^e = 0 \)

\[ U^e = \gamma^{(1)} U^{e(\gamma)} + \cdots \quad (3.44) \]

Then, the Stokes equations become

\[ \nabla^2 v^{(\gamma)} - \nabla p^{(\gamma)} = 0 \quad ; \quad \nabla \cdot v^{(\gamma)} = 0 \quad , \quad (3.45) \]

with the slip boundary condition from matching to the inner solution,

\[ v^{(\gamma)}(1, \theta) = U^{e(\gamma)} + \mu_e \frac{\partial \Phi^{(\gamma)}}{\partial \theta} \hat{e}_\theta \quad , \quad (3.46) \]
where \( \mu_e = \zeta_0 + 4 \ln \cosh (\zeta_0/4) \). Recall that \( \zeta_0 = \varphi_s \) is the zeta potential for the trivial solution with \( \gamma^{(1)} = 0 \).

Solving the homogeneous Stokes equations (3.45) with these boundary conditions gives the following structure for the flow generated by the electrophoretic and ionic diffusiophoretic contributions:

\[
\mathbf{v}(\mathbf{r}) = \gamma^{(1)} \mathbf{v}(\gamma) = B_2 \left[ - \partial_z \mathbf{G}(\mathbf{r}) \right] + B_1 \mathbf{D}(\mathbf{r}) + B_3 \left[ \partial_z^2 \mathbf{G}(\mathbf{r}) \right] + \mathcal{O}(r^{-4}),
\]

expressed in terms of the leading order fundamental singularities of the Stokes equation:

\[
\mathbf{G}(\mathbf{r}) = \frac{\mathbf{e}_z}{r} + \frac{rr \cdot \mathbf{e}_z}{r^3}; \quad \mathbf{D}(\mathbf{r}) = 3 \frac{rr \cdot \mathbf{e}_z}{r^5} - \frac{\mathbf{e}_z}{r^5},
\]

with the strengths given by

\[
B_1 = -\frac{1}{3} \mu_e \gamma^{(1)} A_1 \left( 1 - \frac{3 A_3}{2 A_1} \right); \quad B_2 = \frac{3}{2} \mu_e \gamma^{(1)} A_2; \quad B_3 = \frac{5}{4} \mu_e \gamma^{(1)} A_3,
\]

where the \( A_l \) are obtained from solving equations (3.36). Imposing the constraint of zero total force, equation (3.6), leads to an expression for the electrophoretic and ionic-diffusiophoretic contributions to the propulsion velocity,

\[
\mathbf{U}^e = -\frac{2}{3} \mu_e \gamma^{(1)} A_1 \mathbf{e}_z.
\]

Written in dimensional form (see Figure 6),

\[
\bar{\mathbf{U}}^e = -\frac{1}{3} \left( \frac{k_B T}{e} \right)^2 \frac{\epsilon A_1 \Delta k_l^{(h)} h_{\text{eff}}}{\eta D_h (c^{\infty}_h + c^{\infty}_s)} \left[ \frac{e\bar{\zeta}_0}{k_B T} + 4 \ln \cosh \left( \frac{e\bar{\zeta}_0}{4k_B T} \right) \right] \mathbf{e}_z,
\]

where \( \bar{\zeta}_0 = (k_B T/e)\zeta_0 \) is the average zeta swimmer average zeta potential. A plot of this electrophoretic contribution against the solution salt concentration (ionic strength) is shown in Fig. 6(a). As expected, this contribution is strongly sensitive to salt concentration. Interestingly, the swimmer speed is only weakly dependent on pH (see Fig. 6(c)) under weakly acidic conditions (high \( c^{\infty}_h \)). This is due to the competition between the dependence on \( c^{\infty}_h \) of \( A_1 \) (decreases with \( c_h \)), \( \mu_e \) (increases with \( c_h \)) and the denominator of the expression for \( \mathbf{U}^e \) (increases with \( c_h \)). This is consistent with recent experiments (Brown & Poon 2014) which showed a minor reduction of swimming speed on addition of sodium hydroxide (NaOH). Furthermore, the propulsion speed is inversely dependent on swimmer size, \( a \) for large swimmer sizes as shown in Fig. 6(b). This is consistent with the experimental observation of \( \sim 1/a \) propulsion velocity decay for large swimmer sizes (Howse et al. 2007).

3.2. Self-diffusiophoresis

In this section, we outline a solution of the equations of motion for the neutral solutes in the outer region \( \chi = L_{\text{eff}}/a \to 0 \) to calculate the neutral diffusiophoretic contribution to the propulsion velocity, \( \mathbf{U}^d \). Detailed calculations for the inner interaction layer where the fields varies at the lengthscale \( L_{\text{eff}} \) can be found in the literature (Anderson et al. 1982; Golestanian et al. 2005, 2007; Howse et al. 2007; Michelin & Lauga 2014).

Here since there is a finite propulsion velocity, \( \bar{\mathbf{U}}^d \neq 0 \), for the uniformly coated system, \( k_i^{(0)} \neq 0, k_i^{(1)} = 0 \), then a weak variation of rates due to a varying thickness, \( k_i^{(0)} \gg k_i^{(1)} \), leads to a small correction which we can ignore. Hence we set \( k_i^{(1)} = 0 \) for the rest of this section.
3.2.1. Dimensionless equations

The position vector \( \vec{r} \) is measured in units of the swimmer size ‘\( a \)’, concentrations \( \bar{c}_i \) in units of the steady-state background values \( \bar{c}_i^\infty \) (note that \( \bar{c}_o \) is measured in units of \( c_{hp}^\infty \)), the short-ranged interaction potential of solutes with the Janus sphere, \( \bar{\Psi} \) in terms of the thermal energy scale \( \beta^{-1} = k_B T \), neutral solute fluxes, \( \bar{J}_n \) in units of \( D_n c_{hp}^\infty / a \), with \( D_i \) the diffusion coefficient of \( i \)’th solute. The fluid flow velocity \( \bar{\Psi} \) is rescaled by \( \bar{\mu}_d c_{hp}^\infty / a \), where \( \bar{\mu}_d \) is the characteristic diffusiophoretic mobility, the pressure \( \bar{p} \) is rescaled by \( \bar{\mu}_d \eta c_{hp}^\infty / a^2 \). Hence, the dimensionless quantities (no overbar) are expressed in terms of dimensional ones (with overbar) as follows

\[
\beta \bar{\Psi} = \bar{J}_n (\bar{\theta}) = \frac{D_n}{2D_o} \bar{\mu}_d \eta c_{hp}^\infty (1 + \bar{C}_{hp}) K(\cos \theta),
\]

and vanishing concentration deviations far from the swimmer \( \bar{C}_o, \bar{C}_{hp} \to 0 \) as \( r \to \infty \). \( K(\cos \theta) \), the catalyst coverage function, is 1 on the Platinum hemisphere and zero on the polystyrene hemisphere. From the reaction kinetics in Appendix A, we obtain non-zero fluxes for hydrogen peroxide and oxygen

\[
\begin{align*}
\partial_r \bar{C}_o |_{r=1} &= \bar{J}_o(\bar{\theta}) K(\cos \theta) = \frac{D_{hp}}{2D_o} \bar{\mu}_d \eta c_{hp}^\infty (1 + \bar{C}_{hp}) K(\cos \theta), \\
\partial_r \bar{C}_{hp} |_{r=1} &= \bar{J}_{hp}(\bar{\theta}) K(\cos \theta) = -\bar{K}_{hp} (1 + \bar{C}_{hp}) K(\cos \theta),
\end{align*}
\]

and

\[
\begin{align*}
\bar{J}_o(\bar{\theta}) &= \frac{1}{2} \left( \frac{k_{hp}^{(hp)} c_{hp} a}{D_o c_{hp}^\infty} \right) K(\cos \theta) = \frac{D_{hp}}{2D_o} \bar{\mu}_d \eta c_{hp}^\infty (1 + \bar{C}_{hp}(1, \theta)) K(\cos \theta), \\
\bar{J}_{hp}(\bar{\theta}) &= -\left( \frac{k_{hp}^{(hp)} c_{hp} a}{D_{hp} c_{hp}^\infty} \right) K(\cos \theta) = -\bar{K}_{hp} (1 + \bar{C}_{hp}(1, \theta)) K(\cos \theta).
\end{align*}
\]

We have defined dimensionless \( \bar{K}_{hp} = k_{hp}^{(hp)} a / D_{hp} \), where \( k_{hp}^{(hp)} c_{hp} > 0 \) is the effective rate of consumption of the hydrogen peroxide (see Appendix A for details of the derivation).

The boundary conditions for the fluid velocity are

\[
\vec{v} |_{r=1} = \vec{U}^d + \vec{v}_{slip}^d; \quad \vec{v}(r \to \infty) = 0,
\]

where \( \vec{U}^d \) is the neutral self-diffusiophoretic contribution to the propulsion velocity.
The form determines the diffusiophoretic propulsion velocity \( U \) is a unit matrix. The dimensionless self-diffusiophoretic mobility is given by \( \mu_d^{(i)} = \lim_{\rho' \to \infty} \int_0^{\rho'} [1 - e^{-\psi_i(\rho)}] \, d\rho \) (Anderson 1989).

Finally, the zero total force condition on the swimmer

\[
F = \oint_{r=1} \Pi \cdot \hat{n} \sin \theta \, d\theta = 0 ,
\]

(3.60)
determines the diffusiophoretic propulsion velocity \( \mathbf{U}^d \).

### 3.2.3. Outer concentration fields

The general solution of the Laplace equations (3.52,3.53) for the neutral solutes is of the form

\[
C_o(r, \theta) = \sum_{l=0}^{\infty} \left( \frac{D_{hp}}{2D_o} \right) W_l \frac{P_l(\cos \theta)}{r^{l+1}} ,
\]

(3.61)

\[
C_{hp}(r, \theta) = - \sum_{l=0}^{\infty} W_l \frac{P_l(\cos \theta)}{r^{l+1}} ,
\]

(3.62)

where \( P_l(\cos \theta) \) are the Legendre polynomials and note that we have used the fact that \( D_{hp}J_{hp} + 2D_oJ_o = 0 \). The amplitudes \( W_l \)'s, are determined from either of the boundary conditions;

\[
- \partial_r C_o|_{r=1} = \frac{D_{hp}K_{(hp)}^{(eff)}}{2D_o} (1 + C_{hp}) K(\cos \theta) ,
\]

(3.63)

\[
- \partial_r C_{hp}|_{r=1} = - K_{(hp)}^{(eff)} (1 + C_{hp}) K(\cos \theta) .
\]

(3.64)

This gives rise to a system of equations :

\[
\sum_{l=0}^{\infty} W_l (l+1) P_l(\cos \theta) = K_{(hp)}^{(eff)} \left( 1 - \sum_{l=0}^{\infty} W_l P_l(\cos \theta) \right) K(\cos \theta) .
\]

(3.65)

From this, using the orthogonality condition of the Legendre polynomials, we obtain the linear system of equations for the amplitudes, \( W_l \):

\[
\mathbf{M}^{(d)} \cdot \mathbf{W} = \mathbf{A}^{(d)} ,
\]

(3.66)

where \( \mathbf{W} = (W_0, \ldots, W_l, \ldots) \), and more explicitly

\[
\begin{pmatrix}
1 & 0 & 0 & \cdots & 0 & \cdots \\
0 & M_{11}^{(d)} & M_{12}^{(d)} & \cdots & M_{1l}^{(d)} & \cdots \\
0 & M_{21}^{(d)} & M_{22}^{(d)} & \cdots & M_{2l}^{(d)} & \cdots \\
\vdots & \vdots & \vdots & \ddots & \vdots & \ddots \\
0 & M_{n1}^{(d)} & M_{n2}^{(d)} & \cdots & M_{nl}^{(d)} & \cdots \\
\vdots & \vdots & \vdots & \cdots & \vdots & \cdots 
\end{pmatrix}
\begin{pmatrix}
W_0 \\
W_1 \\
W_2 \\
\vdots \\
W_l \\
\vdots 
\end{pmatrix}
= 
\begin{pmatrix}
0 \\
A_1^{(d)} \\
A_2^{(d)} \\
\vdots \\
A_n^{(d)} \\
\vdots 
\end{pmatrix}
\]

(3.67)
where the matrix $M^{(d)}$ and vector $A^{(d)}$ entries are given by

$$M_{nl}^{(d)} = \delta_{nl} + \mathcal{K}_{\text{eff}}^{(hp)} \left( \frac{n + \frac{1}{2}}{n + 1} \right) \int_0^1 P_n(x) P_l(x) \, dx ,$$

$$A_n^{(d)} = \mathcal{K}_{\text{eff}}^{(hp)} \left( \frac{n + \frac{1}{2}}{n + 1} \right) \int_0^1 P_n(x) \, dx .$$

(3.68) (3.69)

Here as in the ionic section, we solve a truncated approximation of the linear equations above, including all modes up to the $N$’th Legendre mode $\{W_0, W_1, \ldots , W_N\}$. As above, we can obtain analytic asymptotic solutions for $\mathcal{K}_{\text{eff}}^{(hp)} \ll 1$ and $\mathcal{K}_{\text{eff}}^{(hp)} \gg 1$:

$\mathcal{K}_{\text{eff}}^{(hp)} \ll 1 :$ In this regime, $W_l \sim A_l^{(d)}$ and

$$W_1 \sim \frac{3}{8} \mathcal{K}_{\text{eff}}^{(hp)}$$

(3.70)

$\mathcal{K}_{\text{eff}}^{(hp)} \gg 1 :$ In this regime,

$$W_1 \sim \Xi$$

(3.71)

where $\Xi > 0$ is some constant to be determined numerically. Since $\mathcal{K}_{\text{eff}}^{(hp)} \propto a$ (swimmer size), this implies the limit $\mathcal{K}_{\text{eff}}^{(hp)} \gg 1$ corresponds to large swimmer size. For $a = 1.00\mu m$ sized swimmer in 10% w/v $\text{H}_2\text{O}_2$ solution, and the measured reaction rates in table (1), the estimate of the dimensionless reaction rate coefficient is $\mathcal{K}_{\text{eff}}^{(hp)} \approx 0.026$. Hence, this puts the current experimental measurements (Ebbens et al. 2014; Brown & Poon 2014) in the first regime ($W_l \sim A_l^{(d)}$). We note that in this regime $C_{hp} \sim W_l \sim \mathcal{K}_{\text{eff}}^{(hp)} \ll 1$.

The coefficients $W_l$ determine the solute concentration, and hence the slip velocity which act as boundary conditions for the Stokes flow problem. Hence the velocity fields generated, expressed in terms of the fundamental singularities (see equation (3.48)) of Stokes flow are

$$v(r) = B_1^{(d)} D(r) + B_3^{(d)} \left[ \partial_z^2 G(r) \right] + \mathcal{O}(r^{-4}) ,$$

(3.72)

where the coefficients $(B_1^{(d)}, B_3^{(d)})$ are

$$B_1^{(d)} = - \frac{1}{3} \mu_d W_1 \left( 1 - \frac{3}{2} \frac{W_3}{W_1} \right) ; \quad B_3^{(d)} = \frac{5}{4} \mu_d W_3 .$$

(3.73)

Imposing the condition of net zero total force, we obtain the the neutral diffusiophoretic contribution to the propulsion velocity as

$$U^d = - \sum_{i \in \{hp,o\}} \left[ \frac{1}{4\pi} \int_0^{2\pi} \int_0^{\pi} \sin \theta \, d\theta \, \mu_d \mu_d^{(i)} (1 - \hat{n} \hat{n} \cdot \nabla C_i) \right] ,$$

(3.74)

where since we have taken the interaction potential, $\Psi$ identical for all species, we have identical neutral diffusiophoretic mobilities for all the neutral solute species, $\mu_d^{(i)} = 1$, $i \in \{o, hp\}$. From the modes calculated above, we thus obtain

$$U^d = - \frac{2}{3} \mu_d W_1 \hat{e}_z ,$$

(3.75)

where $\mu_d = \mu_d^{(hp)} - (D_{hp}/2D_o)\mu_d^{(o)} = 1 - (D_{hp}/2D_o)$ is the combined effective diffusiophoretic mobility.
Figure 6. (Electrophoretic and ionic-diffusiophoretic contribution): (a) The propulsion speed $U^e$ as a function of the salt concentration $C_\infty$. (b) The propulsion speed $U^e$ decay with increasing size $a$. (c) The speed $U^e$ against the solution pH (we expect that the charge balance maybe more complicated and the reaction kinetics are known to change with the solution pH (Liu et al. 2014; McKee 1969)).

3.3. Comparison of ionic and neutral velocities

Finally, we can now compare the two contributions to the swimmer propulsion from ionic and neutral solutes using dimensional quantities. From equations (3.50,3.75), the relative speed

$$\frac{\bar{U}^e}{\bar{U}^d} = \frac{(\epsilon k_B T^2 / q e^2) U^e}{\left(\bar{\mu}_d c_\infty^c / a\right) U^d} = \frac{\bar{\mu}_e}{\bar{\mu}_d} \frac{(k_B T / e) \gamma^{(1)} A_1}{c_\infty^p W_1},$$

where $\bar{\mu}_e = (\epsilon k_B T / e \eta) \mu_e$ is the electrophoretic mobility and $\bar{\mu}_d = \mu_d \bar{\mu}_d^+$ is the diffusiophoretic mobility both in dimensional form. For a fixed swimmer size, and in the limit $\gamma^{(0)} \ll 1$, $K_{\text{eff}}^{(hp)} \ll 1$, the above ratio takes the simple analytic expression

$$\frac{\bar{U}^e}{\bar{U}^d} = \frac{1}{6} \frac{\bar{\mu}_e D_{hp} \Delta k_{\text{eff}}^{(hp)}}{\bar{\mu}_d D_h k_{\text{eff}}^{(hp)}} \frac{k_B T / e}{(c_\infty^c + c_\infty^h)},$$

where $k_{\text{eff}}^{(hp)} c_\infty^c > 0$ is the effective rate of the hydrogen peroxide consumption and $\Delta k_{\text{eff}}^{(hp)} > 0$ is the scale of the difference between the rates at the pole and equator due to the Pt thickness variation (defined in Appendix A for a particular example of reaction model). These rates are linear functions of the $c_\infty^hp$ concentration for low fuel concentration. In Fig. (7), it can be seen that the electrophoretic contribution vanishes at large ionic strengths, and the swimmer speed asymptotically approaches the diffusiophoretic contribution value $\bar{U}^d$. The self-diffusiophoretic speed $\bar{U}^d = \mu_d k_{\text{eff}}^{(hp)} c_\infty^c / 4 D_{hp} \sim 0.52 \mu m s^{-1}$ (see table 1) for the chosen system parameter values in the plot (Fig. 7).

4. Summary and discussion

Therefore, the total propulsion velocity of the metallic-insulator sphere from both electrophoresis and diffusiophoresis, from equations (3.50 and 3.75), in dimensional form is

$$\bar{U} = - \left[ \frac{1}{3} \bar{\mu}_e \frac{\Delta k_{\text{eff}}^{(hp)} c_\infty^c}{D_h (c_\infty^c + c_\infty^h)} \left(\frac{k_B T}{e}\right) A_1 + \frac{2}{3} \frac{\bar{\mu}_d c_\infty^c}{a} W_1 \right] \hat{e}_z,$$

where $\bar{\mu}_e$ and $\bar{\mu}_d$ are the electrophoretic and diffusiophoretic mobilities. The scale of the difference between the rates at the poles and the equator due to the Pt thickness variation $\Delta k_{\text{eff}}^{(hp)} > 0$ is defined in Appendix A for a particular reaction kinetic model. We point
out that these results are qualitatively independent of the details of the reaction kinetics, provided the reaction involves both charged and neutral pathways for the reduction of the hydrogen peroxide and the reaction rate varies along the catalytic cap.

The ionic contribution to the expression above has a number of important simple features that are in agreement with recent experimental results on this system Howse et al. (2007); Ebbens et al. (2012); Brown & Poon (2014); Ebbens et al. (2014); Das et al. (2015): (1) it depends linearly on the fuel, \( c_{hp}^{\infty} \), at low concentrations and the dependence weakens at high concentrations, (2) it is independent of \( a \) at small \( a \) and behaves as \( 1/a \) for large \( a \) due to fuel depletion as shown in Ref. Ebbens et al. (2012), and (3) it is a monotonically decreasing function of salt concentration, \( c_{s}^{\infty} \), starting from a finite value.
when $c_\infty = 0$ and tending to zero as $c_\infty$ becomes large. Hence at high salt concentration the swimming speed saturates to the neutral diffusiophoretic value (see Fig. 7). The electrophoretic contribution, which can be much larger than the diffusiophoretic part, vanishes if there is no variation in the rates $k_i$ on the surface.

Adding salt to the solution containing the swimmer would influence the propulsion in three possible ways (1) pH neutral salts that do not specifically adsorb to the surface would enhance the solution conductivity thereby reducing the effective screening length (2) while alkali or acidic salts would in general alter the total surface charge in addition to the increased solution conductivity (3) Pt catalytic decomposition of $\text{H}_2\text{O}_2$ is known to strongly depend on the solution pH (Liu et al. 2014; McKee 1969). Hence, non-pH neutral salts would also affect the Pt catalytic activity.

We note also that due to the existence of the two separate reaction loops, the overall catalytic reaction rate (measured from the current $J_o$ above) can be significantly reduced with only small reductions to the swimming speed; say by a significant decrease in $k_1$. This type of behaviour would be expected from any reaction scheme which has this topological structure.

In conclusion, we have shown that in a system with catalytic reaction with charged intermediates, the existence of thickness-dependence in the reaction rates up to a certain limit (a few nanometres), allows us to create—by tapering the catalyst layer—spatially separated nonequilibrium cycles that could lead to large scale (many microns) ionic currents in the form of closed loops in the bulk. This remarkable effect, combining long range electrostatic interactions with nonequilibrium chemical reactions to substantially enhance surface generated flows has potential for application in many different areas of nanoscience.

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Appendix A. Reaction kinetics

In this section, our goal is to obtain the fluxes on the surface of the swimmer, $\vec{J}_i$ of all the chemical species involved in the $\text{H}_2\text{O}_2$ decomposition

$$\text{Pt} + 2\text{H}_2\text{O}_2 \rightarrow \boxed{\text{Intermediate complexes}} \rightarrow \text{Pt} + 2\text{H}_2\text{O} + \text{O}_2. \quad (A\ 1)$$

Though a complete picture of the intermediate complexes in reaction (A 1) remains elusive, it is known that there are neutral pathways as well as ionic electrochemical pathways (Hall et al. 2000; Katsounaros et al. 2012). However, we find that our results are qualitatively independent of many details of the reaction scheme considered as long as they involve both neutral and charged pathways. So our lack of knowledge of the microscopic chemical kinetics is not such a hindrance. To illustrate this, we consider two different reaction schemes involving a neutral as well a charged pathway. We emphasize that both schemes are provided simply as examples as the precise details of the chemical kinetics are not known.
Figure 9. (Reaction scheme 1): Schematic complexation kinetics of the Platinum catalyst with free (0'th state) Pt occupied with probability density \( p_0 \); first complex state Pt(H\(_2\)O\(_2\)) occupied with probability density \( p_1 \), and the second complex state Pt(H\(_2\)O\(_2\))\(_2\) occupied with probability density \( p_2 \).

A.1. Reaction scheme 1

First, we consider a reaction scheme for the reaction (A 1) made up of two pathways, one neutral

\[
\text{Pt} + 2\text{H}_2\text{O}_2 \xrightarrow{k_0} \text{Pt(H}_2\text{O}_2) + \text{H}_2\text{O}_2 \xrightarrow{k_1} \text{Pt(H}_2\text{O}_2)_2 \xrightarrow{k_2} \text{Pt} + 2\text{H}_2\text{O} + \text{O}_2 ,
\]

(A 2)

and the other ionic involving charged intermediates,

\[
\text{Pt} + 2\text{H}_2\text{O} \xrightleftharpoons[k_3]{k_{-3}} \text{Pt(H}_2\text{O}_2) + 2\text{e}^- + 2\text{H}^+ .
\]

(A 3)

The reaction scheme above and the intermediate states denoted by (0,1,2) are enumerated in Fig. (9). The kinetics of the Pt catalyst complexation in stationary state reads

\[
0 = \partial_t p_0 = -k_0 c_{hp} p_0 - k_3 p_0 + k_2 p_2 + k_{-3} c_h^2 p_1 ,
\]

(A 4)

\[
0 = \partial_t p_1 = k_0 c_{hp} p_0 + k_3 p_0 - k_1 c_{hp} p_1 - k_{-3} c_h^2 p_1 ,
\]

(A 5)

\[
0 = \partial_t p_2 = k_1 c_{hp} p_1 - k_2 p_2 ,
\]

(A 6)

where \( p_i \)'s are the complexation probabilities. Solving for these probabilities \( p_i \), we obtain

\[
p_0 = M^{-1} k_2 (k_1 c_{hp} + k_{-3} c_h^2) ,
\]

(A 7)

\[
p_1 = M^{-1} k_2 (k_0 c_{hp} + k_3) ,
\]

(A 8)

\[
p_2 = M^{-1} k_1 c_{hp} (k_0 c_{hp} + k_3) ,
\]

(A 9)

where the normalization condition \( p_0 + p_1 + p_2 = 1 \) was used and we have defined

\[
M := k_2 k_3 + k_2 k_{-3} c_h^2 + (k_0 k_2 + k_1 k_3 + k_1 k_2) c_{hp} + k_0 k_1 c_{hp}^2 .
\]

(A 10)
This leads to expressions for the fluxes $\vec{J}_i$ of $i \in \{o, hp, h\}$

$$\vec{J}_o(\theta) = k_2 p_2 K(\cos \theta),$$

$$= M^{-1} k_1 k_2 \bar{c}_{hp} \left(k_0 \bar{c}_h + k_3\right) K(\cos \theta), \quad \text{(A 11)}$$

$$\vec{J}_{hp}(\theta) = -(k_0 p_0 + k_1 p_1) \bar{c}_{hp} K(\cos \theta),$$

$$= -M^{-1} k_2 \bar{c}_{hp} \left(k_1 k_3 + k_0 k_{-3} \bar{c}_h^2 + 2k_0 k_1 \bar{c}_{hp}\right) K(\cos \theta), \quad \text{(A 12)}$$

$$\vec{J}_h(\theta) = 2 \left( k_3 p_0 - k_{-3} \bar{c}_h^2 p_1 \right) K(\cos \theta),$$

$$= 4M^{-1} k_2 \bar{c}_{hp} \left(k_1 k_3 - k_0 k_{-3} \bar{c}_h^2\right) K(\cos \theta), \quad \text{(A 13)}$$

and for the fluxes of hydroxide and the salt, $\vec{J}_{oh} = 0$, $\vec{J}_{s, \pm} = 0$. Measurements of the reaction rates (Ebbens et al. 2014) imply that $\vec{J}_{hp}$ and $\vec{J}_o$ vary with the Pt coating thickness (of $\sim$nm scale). Hence we may assume that the rate ‘constants’ $k_i$’s vary in a similar manner.

Since the thickness of the coating varies across the Pt cap, the reaction rates $k_i(\theta)$’s vary over the coated hemisphere, and can be expanded in Legendre polynomials. We consider a simple linear approximation

$$k_i(\theta) \cong k_i^{(0)} + k_i^{(1)} \cos \theta, \quad \text{(A 14)}$$

in $\cos \theta$ and we assume a weak variation $k_i^{(1)} / k_i^{(0)} \ll 1$ of the rates.

The solute fluxes $\vec{J}_i$ above in eqns. (A 11 - A 13) require the inner (Debye-layer) proton concentration profile

$$\bar{c}_h(1, \theta)/c_{h}^\infty = (1 + C_h(1, \theta)) e^{-\zeta(\theta)}; \quad \zeta(\theta) = \varphi_s - \Phi(1, \theta), \quad \text{(A 15)}$$

from eqn. (B 22) in Appendix B, where $C_h(1, \theta)$ and $\Phi(1, \theta)$ are the deviations from the uniform background of proton concentration and electric fields. $\varphi_s$ is the electric potential on the swimmer surface. We have taken $\varphi_s$ constant here, but it is straightforward to generalise our calculations to situations in which it varies across the surface. We note that having an electric potential difference between the coated and non-coated hemispheres does not lead to qualitative differences from the results presented here. Hence, the proton flux at the outer edge of the double-layer reads

$$\vec{J}_h(\theta) = 4M^{-1} k_2 \bar{c}_{hp} \left(k_1 k_3 - k_0 k_{-3} (c_{h}^\infty)^2 (1 + C_h) e^{-2\zeta(\theta)}\right) K(\cos \theta). \quad \text{(A 16)}$$

Furthermore, Taylor-expanding the flux up to linear order in $k_i^{(1)}$, and the deviations $C_h, \Phi$;

$$\vec{J}_h(\theta) = \left(\vec{J}_h^{(0)} + \vec{J}_h^{(1)} P_1(\cos \theta) + \vec{J}_h^{(1)} (\Phi + C_h)\right) K(\cos \theta), \quad \text{(A 17)}$$

where $j \in \{0, 1, 2\}$. We define

$$\vec{J}_h^{(0)} = 4\{k_2 c_{hp}\}^{(0)} \left\{(k_1 k_3)^{(0)} - \{k_0 k_{-3}\}^{(0)} (c_{h}^\infty)^2 e^{-2\varphi_s}\right\} / M^{(0)}, \quad \text{(A 18)}$$

$$\vec{J}_h^{(1)} = 4\{k_2 c_{hp}\}^{(0)} \left\{(k_1 k_3)^{(1)} - \{k_0 k_{-3}\}^{(1)} (c_{h}^\infty)^2 e^{-2\varphi_s}\right\} / M^{(0)}, \quad \text{(A 19)}$$

$$\vec{J}_h' = 8\{k_2 c_{hp}\}^{(0)} \{k_0 k_{-3}\}^{(0)} (c_{h}^\infty)^2 e^{-2\varphi_s} / M^{(0)}, \quad \text{(A 20)}$$

$$M^{(0)} = \{k_2 k_3 + k_2 k_{-3} \bar{c}_h^2 + (k_0 k_2 + k_1 k_3 + k_1 k_2) \bar{c}_{hp} + k_0 k_1 \bar{c}_{hp}^2\}^{(0)}. \quad \text{(A 21)}$$
Now, imposing net charge conservation, equation (2.16) on the swimmer surface, equation (A 17) for the proton flux leads to

\[ \mathcal{J}_h^{(0)} + \frac{1}{2} \mathcal{J}_h^{(1)} + \int_0^{\pi} (\Phi + C_h) K(\cos \theta) \sin \theta d\theta = 0. \] (A 22)

Then, substituting for \( \mathcal{J}_h^{(i)} \)’s (from eqns. A 18-A 20) and simplifying:

\[ (c_h^\infty)^2 e^{-2}\varphi_s \left( 1 + \frac{1}{2} \left\{ \frac{k_0 k_{-3}^{(1)}}{k_0 k_{-3}^{(0)}} \right\} + 2 \int_0^{\pi} (\Phi + C_h) K(\cos \theta) \sin \theta d\theta \right) \]

\[ = \frac{\{k_1 k_3\}^{(0)}}{\{k_0 k_{-3}\}^{(0)}} + \frac{1}{2} \frac{\{k_1 k_3\}^{(1)}}{\{k_0 k_{-3}\}^{(0)}}. \] (A 24)

For a uniform coating (i.e \( k_i^{(1)} = 0 \) for all \( i \)’s), which has the trivial solution \( \Phi = C_h = 0 \), the zero total current condition gives rise to

\[ (c_h^\infty)^2 e^{-2}\varphi_s \simeq \frac{\{k_1 k_3\}^{(0)}}{\{k_0 k_{-3}\}^{(0)}}. \] (A 25)

which is all that is required for a linear expansion about a uniform coating. Hence solving for the swimmer potential \( \varphi_s \), we obtain the equation

\[ \varphi_s = \varphi_s^{\ominus} - \ln 10 \text{ pH}, \] (A 26)

where \( \text{pH} = -\log_{10} c_h^\infty \) (with \( c_h^\infty \) measured in molar units) and

\[ \varphi_s^{\ominus} = -\frac{1}{2} \ln \left( \frac{\{k_1 k_3\}^{(0)}}{\{k_0 k_{-3}\}^{(0)}} \right). \] (A 27)

Therefore, eliminating the swimmer potential and proton background concentration \( (\varphi_s, c_h^\infty) \) by substituting eqn. (A 25) into eqn. (A 17) and keeping only linear perturbations, the proton flux assumes a simple form

\[ \mathcal{J}_h(\theta) \simeq \left[ \Delta k_{\text{eff}}^{(h)} (1 - 2 \cos \theta) - k_{\text{eff}}^{(h)} \delta (\Phi + C_h) \right] c_{h_p}^\infty K(\cos \theta), \] (A 28)

where we have defined

\[ k_{\text{eff}}^{(h)} = \frac{8\{k_1 k_2 k_3\}^{(0)}}{\mathcal{M}^{(0)}}; \] (A 29)

\[ \Delta k_{\text{eff}}^{(h)} = \frac{k_{\text{eff}}^{(h)}}{2} \left( \frac{\{k_0 k_{-3}^{(1)}}{\{k_0 k_{-3}^{(0)}} - \frac{\{k_1 k_3\}^{(1)}}{\{k_1 k_3\}^{(0)}} \right), \] (A 30)

\[ \delta (\Phi + C_h) = \left[ (\Phi + C_h) - \int_0^{\pi} (\Phi + C_h) K(\cos \theta) \sin \theta d\theta \right]. \] (A 31)

\( k_{\text{eff}}^{(h)} c_{h_p}^\infty > 0 \) is the typical scale of the average proton consumption and production and \( \Delta k_{\text{eff}}^{(h)} c_{h_p}^\infty \) the scale of the difference between the rates at the pole and equator due to variation of coating thickness over the surface. \( \delta (\Phi + C_h) \) is the deviation of the perturbative fields from their surface average; which promotes/penalise the oxidation/reduction reactions. The proton flux \( \mathcal{J}_h \) is linear in \( c_{h_p}^\infty \) for low fuel concentration and the dependence weakens for high fuel concentration. It is noteworthy that with uniform coating, \( k_i = k_i^{(0)} \Rightarrow \Delta k_{\text{eff}}^{(h)} = 0 \) and the deviation fields vanish \( (\Phi = 0 = C_i) \).
The fluxes of neutral solutes from eqns. (A 11,A 12) give
\[
\bar{J}_o(\theta) \approx \frac{1}{2} k_{\text{eff}}^{(hp)} \bar{c}_{hp}(1, \theta) ,
\]
\[
\bar{J}_{hp}(\theta) \approx -k_{\text{eff}}^{(hp)} \bar{c}_{hp}(1, \theta) ,
\]
where the effective rate of hydrogen peroxide consumption is defined
\[
k_{\text{eff}}^{(hp)} = \frac{2}{M(0)} \left\{ k_0 k_1 k_2 \right\}^{(0)} \bar{c}_{hp}(1, \theta) + \frac{1}{2} k^{(h)}_{\text{eff}} ,
\]
and the effective rate of proton consumption/desorption \(k^{(h)}_{\text{eff}}\) is defined in equation (A 29). Note that \(\bar{J}_{hp}\) and \(\bar{J}_o\) are linear in \(c_{hp}^\infty\) for low fuel \(c_{hp}^\infty\) concentration, and show the saturation typical of Michaelis-Menten kinetics at high fuel concentration.

**A.2. Reaction scheme 2**

Alternatively, we may consider a different reaction scheme, with the same neutral pathway
\[
\text{Pt} + 2\text{H}_2\text{O}_2 \xrightarrow{k_0} \text{Pt}(\text{H}_2\text{O}_2) + \text{H}_2\text{O}_2 \xrightarrow{k_1} \text{Pt}(\text{H}_2\text{O}_2)_2 \xrightarrow{k_3} \text{Pt} + 2\text{H}_2\text{O} + \text{O}_2 ,
\]
but with a different electrochemical pathway
\[
\text{Pt}(\text{H}_2\text{O}_2) \xrightarrow{k_3} \text{Pt} + 2\text{H}^+ + 2e^- + \text{O}_2 ,
\]
\[
\text{Pt}(\text{H}_2\text{O}_2) + 2\text{H}^+ + 2e^- \xrightarrow{k_4} \text{Pt} + 2\text{H}_2\text{O} .
\]
This is the reaction scheme commonly used in modeling the electrophoretic motion of the bimetallic nanorods (Paxton et al. 2005; Dhar et al. 2006; Kline et al. 2005b,a; Sabass & Seifert 2012). As for the reaction scheme considered in the previous section, we can write down the equations of motion for the kinetics for this scheme (see Fig. 10). Hence,
we can, as in the previous section, obtain the fluxes \( \vec{J}_i \)'s,

\[
\vec{J}_h(\theta) = 2M^{-1}k_0k_2\bar{c}_{hp} \left(k_3 - k_4c_h^2\right) K(\cos \theta),
\]
\[
\vec{J}_{hp}(\theta) = -M^{-1}k_0k_2\bar{c}_{hp} \left(2k_1\bar{c}_{hp} + k_3 + k_4c_h^2\right) K(\cos \theta),
\]
\[
\vec{J}_o(\theta) = M^{-1}k_0k_2\bar{c}_{hp} \left(k_1\bar{c}_{hp} + k_3\right) K(\cos \theta),
\]

where here \( M := k_2k_3 + (k_0 + k_1)k_2\bar{c}_{hp} + k_2k_4c_h^2 + k_0k_1c_h^2 \).

Now, imposing the steady state constraint \( \int \vec{J}_h(\theta)d\cos \theta = 0 \), and following the same procedure as in the previous section (with \( k_i = k_i^{(0)} + k_i^{(1)}\cos \theta \)), we obtain the same expression for the proton flux as equation (A 28)

\[
\vec{J}_h(\theta) \approx \left[\Delta k_{\text{eff}}^{(h)} \left(1 - 2\cos \theta\right) - k_{\text{eff}}^{(h)} \delta (\Phi + C_h)\right] \bar{c}_{hp}^\infty K(\cos \theta),
\]

where here we have

\[
k_{\text{eff}}^{(h)} = 4\left\{k_0k_2k_3 \right(0) \right\} / M(0); \quad \Delta k_{\text{eff}}^{(h)} = k_{\text{eff}}^{(h)} \left(\frac{k_4^{(0)}}{k_4^{(1)}} - \frac{k_3^{(0)}}{k_3^{(1)}}\right).
\]

The deviation \( \delta (\Phi + C_h) = [(\Phi + C_h) - \int_0^\pi (\Phi + C_h) K(\cos \theta) \sin \theta \ d\theta] \) retains its previous definition as given in equation (A 31). Finally, we obtain the same relation \( \varphi_s = \varphi_s^\Theta - \ln 10 \ pH \) and the kinetically defined potential for this scheme is \( \varphi_s^\Theta = -(1/2) \ln \left(k_3^{(0)}/k_4^{(0)}\right) \).

It is noteworthy that both reaction schemes possess many similar qualitative features: the solute fluxes \( \vec{J}_i \)'s retain the same functional dependence on the fuel concentration \( \bar{c}_{hp} \) and the variation in reaction rates.

**Appendix B. Derivation of the slip velocity**

In the Debye-layer, where the fields varies on the Debye-lengthscale \( \kappa^{-1} \), we re-scale the radial coordinate by the \( \lambda = (\kappa a)^{-1} \),

\[
\rho = \frac{r - 1}{\lambda},
\]

and expand the deviation fields in the form

\[
C_i(r, \theta) = C_i^{(0)}(\rho, \theta) + \lambda C_i^{(1)}(\rho, \theta) + \cdots,
\]
\[
\Phi(r, \theta) = \varphi^{(0)}(\rho, \theta) + \lambda \varphi^{(1)}(\rho, \theta) + \cdots
\]
\[
v(r, \theta) = V^{(0)}(\rho, \theta) + \lambda V^{(1)}(\rho, \theta) + \cdots
\]
\[
p(r, \theta) = \lambda^{-2}P^{(-2)}(\rho, \theta) + \lambda^{-1}P^{(-1)}(\rho, \theta) + \cdots
\]

where \( i \in \{h, oh, s\pm\} \). It is noteworthy that the expansion for the pressure field begins with \( P^{(-2)} \) to balance \( O(\lambda^{-2}) \) radial electric stresses that could not be accounted by the viscous stresses at the interface (Anderson 1989; Yariv 2011).

**B.1. Ionic solute concentrations**

Exploiting the axisymmetry of the problem, we write the steady state Nernst-Planck equations (3.1) in spherical polar coordinates, with only radial and polar angle depen-
dence.

\[ \nabla \cdot \mathbf{J}_i(r, \theta) = \left( \frac{\partial}{\partial r} + \frac{2}{r} \right) J_{i,r} + \frac{1}{r} \left( \frac{\partial}{\partial \theta} + \cot \theta \right) J_{i,\theta} = 0 . \quad (B 6) \]

where

\[ J_{i,\theta} = -r^{-1} \partial_\theta C_i - z_i (1 + C_i) r^{-1} \partial_\theta \Phi \quad (B 7) \]
\[ J_{i,r} = -\partial_r C_i - z_i (1 + C_i) \partial_r \Phi , \quad (B 8) \]

We therefore expand the fluxes in the inner coordinates \((\rho, \theta)\), noting that \(r = \lambda \rho + 1\)

\[ \mathbf{J}_i(r, \theta) = \mathbf{J}_i(\rho, \theta) = \lambda^{-1} \mathbf{J}_i^{(-1)}(\rho, \theta) + \mathbf{J}_i^{(0)}(\rho, \theta) + \mathcal{O}(\lambda) , \quad (B 9) \]
where we define radial and polar components of the currents (see eqns. B 2 and B 3)

\[ \mathbf{J}_i^{(-1)}(\rho, \theta) = 0 , \quad (B 10) \]
\[ \mathbf{J}_i^{(-1)}(\rho, \theta) = - \frac{\partial \mathbf{C}_i^{(0)}}{\partial \rho} - z_i \left( 1 + \mathbf{C}_i^{(1)} \right) \frac{\partial \mathbf{\Phi}^{(0)}}{\partial \rho} , \quad (B 11) \]
\[ \mathbf{J}_i^{(0)}(\rho, \theta) = - \frac{\partial \mathbf{C}_i^{(0)}}{\partial \theta} - z_i \left( 1 + \mathbf{C}_i^{(1)} \right) \frac{\partial \mathbf{\Phi}^{(0)}}{\partial \theta} , \quad (B 12) \]
\[ \mathbf{J}_i^{(1)}(\rho, \theta) = - \frac{\partial \mathbf{C}_i^{(1)}}{\partial \rho} - z_i \mathbf{C}_i^{(1)} \frac{\partial \mathbf{\Phi}^{(0)}}{\partial \rho} . \quad (B 13) \]

Hence, equation (B 6) can be written

\[ \nabla \cdot \mathbf{J}_i(\rho, \theta) = \frac{1}{\lambda^2} \frac{\partial \mathbf{J}_i^{(-1)}}{\partial \rho} + \frac{2}{(1 + \lambda \rho)^2} \mathbf{J}_i^{(-1)} + \frac{1}{(1 + \lambda \rho)^2} \left( \frac{\partial}{\partial \theta} + \cot \theta \right) \mathbf{J}_i^{(0)} , \quad (B 14) \]
from which performing an expansion in \(\lambda\) and equating terms order by order gives the following equations at order

\[ \lambda^{-2} : \quad \frac{\partial \mathbf{J}_i^{(-1)}}{\partial \rho} = 0 , \quad \Rightarrow \quad \mathbf{J}_i^{(-1)}(\rho, \theta) = h_1(\theta) , \quad (B 15) \]
\[ \lambda^{-1} : \quad \frac{\partial \mathbf{J}_i^{(0)}}{\partial \rho} + 2 \mathbf{J}_i^{(-1)} = 0 , \quad \Rightarrow \quad \mathbf{J}_i^{(0)}(\rho, \theta) = g_1(\theta) + 2 h_1(\theta) \rho , \quad (B 16) \]
\[ \lambda^0 : \quad \frac{\partial \mathbf{J}_i^{(1)}}{\partial \rho} + 2 \mathbf{J}_i^{(0)} - 2 \rho \mathbf{J}_i^{(-1)} + \left( \frac{\partial}{\partial \theta} + \cot \theta \right) \left( \mathbf{J}_i^{(0)} - \rho \mathbf{J}_i^{(-1)} \right) = 0 , \quad (B 17) \]
where \(h_1(\theta), g_1(\theta)\) are arbitrary functions of \(\theta\). Matching the currents in the inner and outer regions,

\[ h_1(\theta) = \lim_{\lambda \to 0, \rho \to \infty} \mathbf{J}_i^{(-1)}(\rho, \theta) = \lim_{r \to 1, \lambda \to 0} \hat{\mathbf{n}} \cdot \mathbf{J}_i^{(-1)}(r, \theta) = 0 , \quad (B 18) \]

which implies \(h_1(\theta) = 0\) for all the species. Furthermore, the next order matching

\[ g_1(\theta) = \mathbf{J}_i^{(0)}(\rho = 0, \theta) = \lim_{\lambda \to 0, \rho \to \infty} \mathbf{J}_i^{(0)}(\rho, \theta) = \lim_{r \to 1, \lambda \to 0} \hat{\mathbf{n}} \cdot \mathbf{J}_i^{(0)}(r, \theta) , \quad (B 19) \]
providing the solution \(g_1(\theta) = \mathcal{J}_i(\theta) K(\cos \theta)\); where \(\mathcal{J}_i(\theta)\) are defined in Appendix A and \(K(\cos \theta)\) is defined in equation (2.10). Therefore, the outer flux boundary conditions at
leading order are,
\[ \hat{n} \cdot \mathbf{J}_i(r = 1, \theta) = g_i(\theta) = \begin{cases} J_h(\theta)K(\cos \theta) ; & i = h, \text{(protons)} , \\ 0 ; & i \in \{oh, s\pm\} \end{cases} \].

(B20)

In the following we drop the \(^{(0)}\) subscript for the outer fluxes as we are interested only in the leading order contributions (i.e we have set \( \mathbf{J}_i^{(n)} = 0 \) for \( n \geq 1 \)).

Next, we obtain the concentration profiles by first matching the inner fields with the \( \mathcal{O}(1) \) outer fields \( \mathbf{C}_i(r, \theta), \Phi(r, \theta) \);

\[ \lim_{\lambda \to 0; \rho \to \infty} \{ \mathbf{C}_i^{(0)}, \Phi^{(0)} \}(\rho, \theta) = \lim_{r \to 1; \lambda \to 0} \{ \mathbf{C}_i^{(0)}, \Phi^{(0)} \}(r, \theta) = \{ \mathbf{C}_i, \Phi \}(1, \theta) . \]

(B21)

Integrating equation (B11) and using equations (B15,B18) and (B21), we obtain the leading order concentration profile

\[ 1 + \mathbf{C}_i^{(0)}(\rho, \theta) = (1 + C_i(1, \theta)) e^{-z_i(\Phi^{(0)}(\rho, \theta) - \Phi^{(1)}(\theta))} . \]

(B22)

This method can be iterated to obtain the higher order concentration fields such as \( \mathbf{C}^{(1)}(\rho, \theta) \) from equation (B17) above.

B.2. Electric field

Writing out Poisson’s equation, in spherical polar coordinates,

\[ -\lambda^2 \left( \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r} + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial}{\partial \theta} \right) \Phi(r, \theta) = \sum_{i \in \{h, oh, s\pm\}} Z_i \mathbf{C}_i , \]

(B23)

which at the leading order in the inner expansion, reduces to

\[ -\frac{\partial^2 \Phi^{(0)}}{\partial \rho^2} = \sum_i Z_i \mathbf{C}_i^{(0)} . \]

(B24)

Substituting the concentration profiles from eqns. (B22) into the foregoing eqn. (B24), we have

\[ -\frac{\partial^2 \Phi^{(0)}}{\partial \rho^2} = \sum_{i \in \{h, oh, s\pm\}} Z_i \left( 1 + C_i(1, \theta) \right) e^{-z_i(\Phi^{(0)}(\rho, \theta) - \Phi^{(1)}(\theta))} . \]

(B25)

In addition, applying electroneutrality in the outer region (see eqn. 3.19 in the main text) at leading order,

\[ \sum_{i \in \{h, oh, s\pm\}} Z_i \mathbf{C}_i = 0 , \]

(B26)

leads to the simpler expression

\[ \frac{\partial^2 \Phi^{(0)}}{\partial \rho^2} = C_s^*(\theta) \sinh \left( \Phi^{(0)}(\rho, \theta) - \Phi^{(1)}(\theta) \right) , \]

(B27)

where we have defined

\[ C_s^*(\theta) = 2 \sum_{i \in \{h, s+\}} Z_i \left( 1 + C_i(1, \theta) \right) . \]

(B28)

Introducing a convenient factor

\[ 2 \frac{\partial \Phi^{(0)}}{\partial \rho} \frac{\partial^2 \Phi^{(0)}}{\partial \rho^2} = 2C_s \frac{\partial \Phi^{(0)}}{\partial \rho} \sinh \left( \Phi^{(0)}(\rho, \theta) - \Phi^{(1)}(\theta) \right) \]

(B29)
and integrating once gives
\[
\left( \frac{\partial \phi^{(0)}}{\partial \rho} \right)^2 = 2C_s^* \left[ \cosh \left( \phi^{(0)}(\rho, \theta) - \Phi(1, \theta) \right) - 1 \right],
\]  
(B30)
where the matching condition \( \partial_\rho \phi^{(0)}(\rho \to \infty, \theta) = 0 \) (since the outer electric field expansion begins at \( \mathcal{O}(1) \)) was applied. Thus, we obtain the electric field in the Debye-layer using the identity \( 2 \sinh^2(x/2) = \cosh(x) - 1 \),
\[
-\frac{\partial \phi^{(0)}}{\partial \rho} = 2\sqrt{C_s^*} \sinh \left( \frac{\phi^{(0)}(\rho, \theta) - \Phi(1, \theta)}{2} \right).
\]  
(B31)
Integrating once again, we obtain
\[
\frac{1}{2} \ln \left[ \frac{\cosh \left( \left[ \phi^{(0)}(\rho', \theta) - \Phi(1, \theta) \right]/2 \right) - 1}{\cosh \left( \left[ \phi^{(0)}(\rho', \theta) - \Phi(1, \theta) \right]/2 \right) + 1} \right]^{\rho' = \rho}_{\rho' = 0} = -\sqrt{C_s^*} \rho.
\]  
(B32)
Now, using the hyperbolic identities \( 2 \left( \sinh \cosh \right)^2 \left( \frac{x}{2} \right) = \cosh(x) - 1 \), we obtain (Anderson 1989; Yariv 2011)
\[
\tanh \left( \frac{\phi^{(0)}(\rho, \theta) - \Phi(1, \theta)}{4} \right) = \tanh \left( \frac{\zeta(\theta)}{4} \right) e^{-\sqrt{C_s^*} \rho},
\]  
(B33)
where \( \zeta(\theta) = \varphi_s - \Phi(1, \theta) \).

### B.3. Momentum conservation

Writing the Stokes equations in spherical polar coordinates,
\[
(\nabla \cdot \Pi) \cdot \hat{e}_r = \nabla^2 v_r - \frac{2v_r}{r^2} - \frac{2}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta v_\theta \right) - \frac{\partial p}{\partial \rho} + \frac{\partial \Phi}{\partial \rho} \nabla^2 \Phi = 0,
\]  
(B34)
\[
(\nabla \cdot \Pi) \cdot \hat{e}_\theta = \nabla^2 v_\theta - \frac{v_\theta}{r^2 \sin^2 \theta} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} - \frac{1}{r} \frac{\partial p}{\partial \theta} + \frac{1}{r} \frac{\partial \Phi}{\partial \rho} \nabla^2 \Phi = 0,
\]  
(B35)
\[
\nabla \cdot \mathbf{v} = \frac{\partial v_r}{\partial \rho} + \frac{2v_r}{r} + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta v_\theta \right) = 0.
\]  
(B36)
To the leading order in the inner expansion (see eqns. B2-B4), the static pressure balances the electrostatic stresses normal to the surface (Anderson 1989; Yariv 2011)
\[
\hat{e}_\rho : \quad \lambda^{-3} \left[ - \frac{\partial P^{(-2)}}{\partial \rho} - \sum_i Z_i C_i^{(0)} \frac{\partial \phi^{(0)}}{\partial \rho} \right] + \lambda^{-2} \frac{\partial^2 V^{(0)}}{\partial \rho^2} + \mathcal{O} \left( \lambda^{-1} \right) = 0.
\]  
(B37)
Note that the expansion for the pressure field begins at \( P^{(-2)} \) to balance \( \mathcal{O} \left( \lambda^{-2} \right) \) radial electric stresses that cannot be accounted by the viscous stresses (Anderson 1989; Yariv 2011). The viscous stresses balances the static pressure gradient and tangential electric stresses along the surface
\[
\hat{e}_\theta : \quad \lambda^{-2} \left( \frac{\partial^2 V^{(0)}}{\partial \rho^2} - \frac{\partial P^{(-2)}}{\partial \theta} - \sum_i Z_i C_i^{(0)} \frac{\partial \phi^{(0)}}{\partial \theta} \right) + \mathcal{O} \left( \lambda^{-1} \right) = 0,
\]  
(B38)
with the leading order incompressibility constraint
\[
\lambda^{-1} \frac{\partial V^{(0)}}{\partial \rho} + \mathcal{O} \left( 1 \right) = 0.
\]  
(B39)
Therefore, to leading $\mathcal{O}(\lambda^{-3})$ in eqn. (B.37), the static pressure balances the radial electrostatic stresses

$$- \frac{\partial P^{(-2)}}{\partial \rho} - \sum_i Z_i C_i^{(0)} \frac{\partial \varphi^{(0)}}{\partial \rho} = 0,$$  \hspace{1cm} (B.40)

which gives the static pressure field

$$P^{(-2)}(\rho, \theta) = 2 C_s^* (\theta) \sinh^2 \left( \frac{\varphi^{(0)}(\rho, \theta) - \Phi(1, \theta)}{2} \right),$$  \hspace{1cm} (B.41)

where matching with the outer solution implies $P^{(-2)}(\infty, \theta) = 0$ (since the outer field $p$ expansion begins at $\mathcal{O}(1)$). The next order $\mathcal{O}(\lambda^{-2})$ in eqn. (B.37) momentum balance is

$$\frac{\partial^2 \mathcal{V}_\rho^{(0)}}{\partial \rho^2} = 0,$$  \hspace{1cm} (B.42)

where the continuity equation (B.39), $\partial_\rho \mathcal{V}_\rho^{(0)} = 0$ (i.e. $\mathcal{V}_\rho^{(0)}$ is $\rho$ independent), implies

$$\mathcal{V}_\rho^{(0)}(\rho, \theta) = U^e \cdot \hat{e}_\rho.$$  \hspace{1cm} (B.43)

At $\mathcal{O}(\lambda^{-2})$ in eqn. (B.38), viscous stresses balance the tangential pressure gradient $\partial_\theta P^{(-2)}$ and the tangential electrical stress;

$$\frac{\partial^2 \mathcal{V}_\theta^{(0)}}{\partial \rho^2} - \frac{\partial P^{(-2)}}{\partial \theta} - \sum_i Z_i C_i^{(0)} \frac{\partial \varphi^{(0)}}{\partial \theta} = 0.$$  \hspace{1cm} (B.44)

Using equations (B.41) and (B.27), we obtain

$$\frac{\partial^2 \mathcal{V}_\theta^{(0)}}{\partial \rho^2} = 2 \sinh^2 (2\varphi) \frac{\partial C_s^*}{\partial \theta} - 2 C_s^* \sinh (2\varphi) \cosh (2\varphi)$$
$$= \frac{2 \tanh (2\varphi)}{1 - \tanh^2 (2\varphi)} \left[ \tanh (2\varphi) \frac{\partial C_s^*}{\partial \theta} + C_s^* \frac{\partial \Phi}{\partial \theta} \right],$$  \hspace{1cm} (B.45)

where $4\varphi(\rho, \theta) = \varphi^{(0)}(\rho, \theta) - \Phi(1, \theta)$. Using the identity $\tanh(2x) = 2 \tanh(x)/(1 + \tanh^2(x))$,

$$\frac{\partial^2 \mathcal{V}_\theta^{(0)}}{\partial \rho^2} = 2 \left[ \frac{4 \tanh^2 (\varphi) \frac{\partial C_s^*}{\partial \theta}}{(1 + \tanh(\varphi))^2 (1 - \tanh(\varphi))^2} - \frac{2 \tanh(\varphi) C_s^* \frac{\partial \Phi}{\partial \theta}}{(1 + \tanh(\varphi))^2 (1 - \tanh(\varphi))^2} \right].$$  \hspace{1cm} (B.46)

It is helpful to write the coefficients of the RHS first and second terms as

$$\frac{4 \tanh^2 (\varphi)}{(1 + \tanh(\varphi))^2 (1 - \tanh(\varphi))^2} = \frac{-1}{(1 + \tanh(\varphi))^2} + \frac{1}{(1 + \tanh(\varphi))^2} + \frac{-1}{(1 - \tanh(\varphi))^2} + \frac{1}{(1 - \tanh(\varphi))^2},$$  \hspace{1cm} (B.47)

$$\frac{2 \tanh(\varphi)}{(1 + \tanh(\varphi))^2 (1 - \tanh(\varphi))^2} = \frac{1}{(1 + \tanh(\varphi))^2} + \frac{-1}{(1 + \tanh(\varphi))^2} + \frac{-1}{(1 - \tanh(\varphi))^2} + \frac{1}{(1 - \tanh(\varphi))^2}.$$  \hspace{1cm} (B.48)
Using eqn. (B33) and integrating once, we obtain
\[
\frac{\partial V^{(0)}_\theta}{\partial \rho} = \frac{2}{\sqrt{C_s^*}} \left[ \frac{2Q^2}{Q^2 - e^2 \sqrt{C_s^*} \rho} \frac{\partial C_s^*}{\partial \theta} - \frac{2Qe^{\sqrt{C_s^*} \rho}}{Q^2 - e^2 \sqrt{C_s^*} \rho} C_s^* \frac{\partial \Phi}{\partial \theta} \right].
\]  
(B49)

where \( Q = \tanh \left( \frac{\zeta(\theta)}{4} \right) \) and such that matching with the outer solution imposes \( \partial_\rho V^{(0)}_\theta(\infty, \theta) = 0 \). In obtaining the above expression, we have used the following integral identities
\[
\int \frac{d\rho'}{1 + Qe^{-\sqrt{C_s^*} \rho}} = \frac{1}{\sqrt{C_s^*}} \ln \left( Q + e^{\sqrt{C_s^*} \rho} \right) + \text{constant},
\]  
(B50)
\[
\int \frac{d\rho'}{(1 + Qe^{-\sqrt{C_s^*} \rho})^2} = \frac{1}{\sqrt{C_s^*}} \frac{Q}{Q + e^{\sqrt{C_s^*} \rho}} + \frac{1}{\sqrt{C_s^*}} \ln \left( Q + e^{\sqrt{C_s^*} \rho} \right) + \text{constant},
\]  
(B51)
\[
\int \frac{d\rho'}{(1 - Qe^{-\sqrt{C_s^*} \rho})^2} = -\frac{1}{\sqrt{C_s^*}} \frac{Q}{Q + e^{\sqrt{C_s^*} \rho}} + \frac{1}{\sqrt{C_s^*}} \ln \left( e^{\sqrt{C_s^*} \rho} - Q \right) + \text{constant}.
\]  
(B52)

Finally, integrating again,
\[
V^{(0)}_\theta(\rho, \theta) = V^{(0)}_\theta(0, \theta) + \frac{2}{C_s^*} \frac{\partial C_s^*}{\partial \theta} \ln \left( \frac{1 - Q^2 e^{-2\sqrt{C_s^*} \rho}}{1 - Q^2} \right) - 4 \frac{\partial \Phi}{\partial \theta} \left( \tanh^{-1} \left( e^{-\sqrt{C_s^*} \rho} \right) - \tanh^{-1} (Q) \right).
\]  
(B54)

Therefore, in the thin-layer limit \( \lambda \to 0 \) and \( \rho \to \infty \),
\[
\lim_{\lambda \to 0; \rho \to \infty} V^{(0)}_\theta(\rho, \theta) = V^{(0)}_\theta(0, \theta) + \zeta(\theta) \frac{\partial \Phi}{\partial \theta} - \frac{2}{C_s^*} \frac{\partial C_s^*}{\partial \theta} \ln \left( 1 - \tanh^2 \left( \frac{\zeta(\theta)}{4} \right) \right).
\]  
(B55)

Finally, matching with the leading order outer flow field
\[
\lim_{\lambda \to 0; \rho \to \infty} V^{(0)}_\theta(\rho, \theta) = \lim_{r \to 1; \lambda \to 0} v^{(0)}(r, \theta) = v(1, \theta),
\]  
(B56)

we obtain the slip velocity boundary condition for the outer flow (Anderson et al. 1982; Yariv 2011)
\[
v(1, \theta) = U^e + \left[ \zeta(\theta) \frac{\partial \Phi}{\partial \theta} + 4 \frac{\partial \ln C_s^*}{\partial \theta} \ln \cosh \left( \frac{\zeta(\theta)}{4} \right) \right] \hat{e}_\theta.
\]  
(B57)

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