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New perspectives on ‘geological strain rates’ calculated from both naturally deformed and actively deforming rocks

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Abstract

A value of \(\sim 10^{-14} \text{ s}^{-1}\) is commonly cited as an average geological strain rate. This value was first suggested for finite strain across an orogen, but based on more limited information than the combined geophysical, geological, and experimental data now available on active and ancient rock deformation. Thus, it is timely to review the data constraining strain rates in the continents, and to consider the quantifiable range of crustal strain rates. Here, where resolution allows, both spatial and temporal strain rate variations are explored. This review supports that a strain rate of \(10^{-14\pm1} \text{ s}^{-1}\) arises from geological estimates of bulk finite strains. Microstructural arguments combining laboratory-derived piezometers and viscous flow laws, however, imply local rates that are orders of magnitude faster. Geodetic rates, in contrast, are typically \(\sim 10^{-15} \text{ s}^{-1}\) in actively deforming areas, about an order of magnitude slower than the bulk rates estimated from geological observations. This difference in estimated strain rates may arise from either low spatial resolution, or the fact that surface velocity fields can not capture strain localisation in the mid to lower crust. Integration of geological and geodetic
rates also shows that strain rates can vary in both space and time, over both single and multiple earthquake cycles. Overall, time-averaged geological strain rates are likely slower than the strain rates in faults and shear zones that traverse the crust or lithosphere.

Keywords: strain rate, rock deformation, geodesy, faults, shear zones

1. Introduction

Pfiffner and Ramsay (1982) suggested a ‘conventional geological strain rate’ of $10^{-14} \pm 1$ s$^{-1}$. This estimate has been widely applied since the publication of their now classic paper, which was based on the finite strain record of orogenic belts. However, Pfiffner and Ramsay (1982) begin their article by stating that data on rates of natural rock deformation are rare. At the time of their writing, geodetic surveys of the San Andreas fault (Whitten, 1956) and measurements of glacial isostatic adjustment (Hicks and Shofnos, 1965) were the main sources of such data. Today, modern geodesy has hugely increased the data set on directly measured surface deformation. In addition, decades of rock deformation experiments and microstructural studies have led to new inferences regarding the mechanisms and rates of rock deformation based on the rock record. Collection and analysis of seismological data have also greatly increased knowledge of how this deformation is distributed in space and time. Huntington et al. (2018) raise the understanding of rheological variations through the lithosphere, for which strain rate distribution is a critical constraint, as a current Grand Challenge in tectonics research. This is therefore an appropriate time to revisit the outcrop record of rock deformation in light of new geodetic, seismic, and laboratory data, and to
discuss the calculation and interpretation of a ‘geological strain rate’. In particular, we consider the following three questions:

1. What is the observed, quantifiable, range of strain rates in nature?
2. How does strain rate vary in space, and to what degree is strain localised onto crustal-scale fault zones?
3. How does strain rate vary in time, not only through individual earthquake cycles, but also across geological timescales?

We consider these questions from two distinct perspectives: first we discuss continental strain over length scales greater than the lithospheric thickness and timescales of multiple earthquake cycles. We then consider how variations in strain with depth during different phases of the earthquake cycle (a) translate into surface strain and (b) are recorded within fault zone rocks.

2. Definitions of Strain Rate

Strain, and its derivative, strain rate, are formally described by a second order tensor, but for the purposes of discussion, we primarily use the scalar magnitude, which can be defined in a variety of ways. Longitudinal strain, $e$, is the change in length of a linear element, $\Delta l$, divided by its original length prior to a discrete deformation episode, $l_0$. Alternatively, one may calculate natural strain, $\epsilon$, where strain is defined as having occurred over multiple infinitesimal increments, each deforming a linear element that includes all the previous deformation increments, i.e. $\epsilon = \int_{l_0}^{l_f} \frac{dl}{l}$, where $l_f$ is the final length.
Shear strain rate in simple shear can be considered in terms of shear strain accumulated within an idealised shear zone of width, $w$, accommodating a finite displacement, $d$, parallel to its boundaries. In this case, shear strain is defined as $\gamma = d/w$ and the shear strain rate is $\dot{\gamma} = \gamma/t = s/w$ where $s$ is the velocity difference across the shear zone. In simple shear, shear strain rate is therefore critically dependent on the deforming shear zone thickness (Fig. 1a).

To express three dimensional strain, one can define principal strains as the longitudinal strains perpendicular to planes of zero shear strain. The strain ellipsoid represents strain relative to an originally undeformed sphere, and is defined by the principal strains $X \geq Y \geq Z$, where $X = (1 + e_x)$ and $Z = (1 + e_z)$ represent the greatest and least stretch, respectively. Strain rate ($\dot{e}$), is typically calculated by dividing longitudinal finite strain by the time taken to accumulate it. However, we note that Pfiffner and Ramsay (1982) explored the effect of strain path and found that among end-member strain histories and combinations thereof, pure shear is the most, and simple shear the least efficient at accumulating longitudinal strain after any given time period at a constant $\dot{e}$. Here, we will refer to $\dot{e} = \dot{e}_x$ as the greatest longitudinal strain rate at a given location, comparable with what is typically measured in laboratory experiments, or shear strain rate, $\dot{\gamma}$.

3. Crustal-scale strain over multiple earthquake cycles

3.1. Geological Strain Rates

Pfiffner and Ramsay (1982) arrived on a longitudinal, average, conventional geological strain rate of $10^{-14}$ s$^{-1}$ by considering calculations of bulk
finite strain across orogens, a range of potential strain paths, and geochronological constraints on the time taken to accumulate such strain. Updated constraints on such bulk strain accumulation rates have been obtained since. For example, in the Lachlan orogen, Australia, Foster and Gray (2007) estimate 67% bulk shortening based on restored thrust sheets, and determine from $^{40}\text{Ar}/^{39}\text{Ar}$ dating of white mica that deformation lasted approximately 16 million years. This gives an average strain rate ($\dot{\varepsilon}$) on the order of $10^{-15}$ s$^{-1}$ assuming deformation was evenly distributed in space and time. The authors note, however, that deformation could have occurred in much shorter pulses, giving a bulk strain rate as fast as $1 \times 10^{-14}$ s$^{-1}$. These rates reflect bulk deformation within a km-scale volume of rock, but result from a combination of localised thrust displacements and distributed folding. The latter represent zones of higher and lower strain, respectively, and thus record slower and faster strain rates embedded within the deformed volume (Fig. 1a).

Another approach to estimating strain rate in exhumed rocks is to infer paleostress from microstructures in viscously deformed rocks, constrain temperature of deformation through a geothermometer, and put resulting values into empirically derived flow laws to calculate strain rate. This methodology has the advantage of allowing spatial variations in strain rate to be explored. To this end, a number of authors have used quartz paleopiezometry to estimate stresses involved in quartz deformation by dislocation creep, based on the empirical relationship (Twiss, 1977):

$$\Delta \sigma = BD^{-p}$$

which relates steady-state differential stress, $\Delta \sigma$, to recrystallised grain size,
$D$, through the empirical constants $p$ and $B$ that depend on the microscale
dynamic recrystallisation mechanism. The steady state shear stress can then
be related to the strain rate accommodated by dislocation creep through a
flow law

$$\dot{\varepsilon} = \Delta \sigma^n A \exp \left(-\frac{Q}{RT}\right)$$

where $A$ is a material constant, $Q$ is activation energy, $T$ is temperature
in Kelvin, $R$ is the universal gas constant, and $n$ is the stress exponent
which depends on the active deformation mechanism. Assuming a constant
temperature and steady flow at constant stress, strain rate can therefore be
calculated from the recrystallised grain size by calculating flow stress in Eq. 1 and extrapolating a laboratory flow law to this stress in Eq. 2.

This method takes advantage of advances in laboratory rock deformation
experiments since the work of Pfiffner and Ramsay (1982), but involves un-
certainties in extrapolating flow laws from laboratory to nature, estimating
temperature of deformation to calculate strain rate from driving stress, in
addition to the inherent error in the laboratory piezometer and flow law cal-
ibrations. These uncertainties are difficult to quantify, but could exceed an
order of magnitude in the final absolute strain rate estimate (cf. Hacker et al.,
1990). To minimise the effect of absolute uncertainty on our conclusions, we
will emphasise relative strain rate variations within a region. In the studies
we discuss, the authors measured grain size in monominerallic domains to
avoid grains whose growth was limited by pinning. However, in multiphase
rocks there is additional uncertainty arising because grain size may deviate
from the equilibrium state inferred by laboratory piezometer calibrations.
Gueydan et al. (2005) studied spatial variation in strain rate within the exhumed Tinos metamorphic core complex, Greece. They report recrystallised quartz grain size ranging from 160 µm to about 40 µm in distributed and localised ductile deformation zones respectively. Using the quartz piezometer of Stipp and Tullis (2003) and the dislocation creep flow law of Luan and Paterson (1992), these grain sizes imply ductile flow at strain rates of $1.5 \times 10^{-15} \text{s}^{-1}$ and $2.6 \times 10^{-14} \text{s}^{-1}$, for penetrative and localised ductile flow, respectively (Gueydan et al., 2005). However, scatter in the data implies that within the penetrative ductile flow regime, local strain rate variations are over an order of magnitude faster and slower than the mean inferred strain rate, and within shear zones, strain rate may locally be close to $10^{-13} \text{s}^{-1}$ (Gueydan et al., 2005). Adjacent to the main brittle detachment, ductilely deformed quartz shows a strain rate increase to $2 \times 10^{-12} \text{s}^{-1}$.

Similarly, strain rates locally elevated to faster than $10^{-14} \text{s}^{-1}$ have been reported from mylonitic gneisses in extended middle crust in the Whipple Mountains, California (Hacker et al., 1992). Behr and Platt (2011), however, suggest that this local increase in strain rate is a result of progressive strain localisation during exhumation along the Whipple Mountain detachment.

Spatial variations in geologically determined strain rates have also been quantified in the Red River and Karakorum shear zones, which are strike-slip zones exhumed from the lower crust. Boutonnet et al. (2013) combined stress estimates from the quartz paleopiezometer of Shimizu (2008) and the laboratory-derived stress-strain rate relationship of Hirth et al. (2001) and calculated strain rates less than $10^{-15} \text{s}^{-1}$ in low strain areas, and greater
than $10^{-13}$ s$^{-1}$ within localised high strain zones considered to have deformed at the same pressure-temperature conditions. The shear zones considered by Boutonnet et al. (2013) are a few kilometres wide, and represent a 1000-fold increase in shear strain rate relative to the surrounding low strain blocks.

In the exhumed mylonitic hanging wall of the transpressional Alpine Fault, New Zealand, finite shear strains of $\leq$ 300 were calculated from ductilely deformed pegmatites within a kilometre-wide mylonite-ultramylonite zone (Norris and Cooper, 2003). To our knowledge, these are the largest shear strains directly calculated from rock exposures. The strain distribution across the Alpine fault, as determined from deformed pegmatites, is best explained if lower crustal deformation along the Alpine fault is localised in a 1 - 2 km wide zone (Norris and Cooper, 2003), implying elevated strain rates where strain is localised in the lower crust, here as well as in Tinos, Karakorum and Red River (described above). Uplift on the Alpine fault occurred over the last 5 Ma (Suther, 1995), such that a total, integrated shear strain as high as 300 implies an average shear strain rate of at least $2 \times 10^{-12}$ s$^{-1}$ in localised zones. Based on paleopiezometry and Ti-in-quartz geothermometry, Cross et al. (2015) determined a strain rate range for Alpine fault zone mylonites deformed at 450-500°C, and preferred a value on the order of $10^{-13}$ s$^{-1}$.

The method and examples above rely on the rock record of dislocation creep in quartz. It is, however, likely that other mineral scale deformation mechanisms, such as diffusion creep, also accommodate significant strain rates in the mid- to lower crust. For example, as recrystallisation in high strain zones leads to grain size reduction, a transition from dislocation creep
to a grain-size sensitive flow mechanism can occur (e.g. Platt, 2015). The strain rate in shear zones accommodating flow by grain-size-sensitive creep cannot be directly obtained from a paleopiezometer, as the proportionality between stress and grain size no longer applies. However, for the strike-slip Pernambuco shear zone in Brazil, Viegas et al. (2016) identified deformed quartz ribbons and monominerallic quartz veins within a polyphase ultramylonite dominated by fine-grained feldspar. Based on microstructures and EBSD analyses, the authors infer the dominant deformation mechanism to be diffusion creep in feldspar, and dislocation creep in quartz ribbons. Viegas et al. (2016) therefore determined flow stresses from the quartz veins and ribbons, and through flow laws for dislocation creep in quartz and diffusion creep in feldspar estimated strain rates ranging from $10^{-10}$ s$^{-1}$ to $10^{-8}$ s$^{-1}$. These estimates, if correct, imply at least local and transient increases in shear zone strain rate, accommodated by viscous mechanisms, to $10^{-10}$ s$^{-1}$ or greater.

We have now listed a number of examples where geological constraints indicate that strain is focused into relatively narrow zones. In most of these examples, the narrow zones are interpreted as established at mid- to lower crustal depths, but note that there are also examples where strain localisation results from progressive deformation during exhumation to lower temperatures and pressures in an extensional tectonic regime (Behr and Platt, 2011). On the crustal scale, localisation of strain into plate boundary zones weakened by grain size reduction, increased temperature, or elevated fluid content, was discussed by Bürgmann and Dresen (2008). These authors suggested the ‘banana split’ model for lateral strength reduction between stronger conti-
nental interiors; this model is consistent with the above-average strain rates locally recorded within the high strain zones described above.

3.2. Geodetic strain rate estimates

Whereas geological strain rate estimates are typically based on observations of deformation accumulated over millions of years, geodetic techniques, such as GPS and InSAR, measure current and ongoing surface displacements. By considering the lithosphere to deform as a continuum, surface velocity estimates can be used to calculate surface strain (e.g. Haines and Holt, 1993). This approach is valid when considering horizontal lengthscales several times the brittle, elastic thickness of the lithosphere, and also at shorter lengthscales if faults are considered locked. The Global Strain Rate Map (GSRM v2.1), interpolates horizontal velocities from 18,000 GPS sites to calculate the 2nd invariant of the strain rate tensor \( \sqrt{\epsilon_1^2 + \epsilon_3^2} \) (Kreemer et al., 2014), equivalent to the maximum strain rate reported in the geological estimates previously discussed. The highest strain rates occur on narrow plate boundaries, particularly at fast-spreading ridges where new crust is created, in which estimated strain rates are as high as \( 1.4 \times 10^{-13} \) s\(^{-1}\). Figure 1b shows the distribution of strain rates within the nodes defined as deforming in GSRM 2.1, the majority of which lie in the range \( 5 \times 10^{-17} - 10^{-14} \) s\(^{-1}\). Examining the distribution of strain rates shows that these values are an order of magnitude lower than the earlier geological estimates of \( 10^{-14\pm1} \) s\(^{-1}\) (Pfiffner and Ramsay, 1982), but that the variance is very similar (Fig. 1b).

Roughly 5% of the area defined as deforming in GSRM 2.1 exhibits a strain rate exceeding \( 10^{-14} \) s\(^{-1}\). These rates are concentrated in rapidly deforming zones with dense GPS networks such as the San Andreas fault.
zone where GSRM reports strain rates exceeding $10^{-14}$ s$^{-1}$ compared to $10^{-15}$ s$^{-1}$ or slower in the surrounding areas (Fig. 2a). These higher strain rate zones also correspond to areas of elevated seismic activity, attesting to localisation of deformation (Fig. 2b). However, comparison between the numerous strain models that have been produced for this well studied region demonstrates that the choice of interpolation scheme for GPS-derived models can lead to large near-fault discrepancies (Hearn et al., 2010). The inclusion of higher-resolution InSAR data is therefore critical to defining strain rates close to active structures (Fialko, 2006; Kaneko et al., 2013; Tong et al., 2013; Elliott et al., 2016). In particular, these InSAR data allow identification of structures that may accommodate locally higher strain rates (Elliott et al., 2016).

By approximating the lithosphere as a thin viscous sheet with vertically averaged forces and properties, continental-scale velocity fields can be used to investigate the rheology of the lithosphere (England and McKenzie, 1982). In such models, the horizontal gradients of the deviatoric stress associated with deformation are balanced by gradients of the gravitational potential energy (GPE). The models are capable of reproducing the first order patterns of deformation well, and typically return viscosities of $10^{21} - 10^{22}$ Pas for a viscous fluid with power law exponent $n = 3$, and strain rates up to $10^{-15}$ s$^{-1}$ (Table 1). The estimated average strain rate values are an order of magnitude lower than those derived by interpolating the velocity field, and averages from geological constraints, as the thin viscous sheet approach likely smooths out concentrations of strain over length-scales less than the thickness of the lithosphere. Some thin viscous sheet studies report large lateral variations in
rheological properties, for example, larger viscosities associated with semi-
rigid microplates and lower values in rapidly deforming areas (Flesch et al.,
2000, 2001). In other studies, however, such variations result in a negligible
reduction in misfit compared to homogeneous models (England and Molnar,
2015; Walters et al., 2017).

Because they vertically average rheological properties, thin viscous sheet
models result in lower strain rates than obtained within models with vertical
velocity gradients. Another end-member geodynamic model is the channel
flow model, in which low viscosity channels accommodate high strain rate
deformation driven by a lithostatic pressure gradient (Royden et al., 1997;
Beaumont et al., 2001; Godin et al., 2006). This model has been invoked
to explain both lack of shortening and presence of orogen-parallel extension
within the Tibetan Plateau (Royden et al., 1997), and also a dynamic link
between these two observations (Beaumont et al., 2001). Coupled to focused
denudation (Beaumont et al., 2001), channel flow may lead to extrusion of
mid-crustal rocks between bounding shear zones. Whereas the lower shear
zone will be a thrust, the upper shear zone is either normal or reverse de-
pending on the relative velocity of the channel versus its hanging wall (Godin
et al., 2006, and references therein). A commonality for channel flow models
is a low viscosity (typically $\leq 10^{19}$ Pas, versus $10^{21} - 10^{22}$ Pas typically re-
turned by thin viscous sheet models) invoked based on weakening by partial
melting under thickened crust (e.g. Jamieson et al., 2002). This local weak-
ness will lead to higher strain rates than in depth-averaged thin viscous sheet
models. For example, if channel thicknesses vary from 3 to 30 km (cf. Godin
et al., 2006), and displacement is on the order of a centimeter per year, aver-
age $\dot{\gamma}$ becomes $10^{-14}$ to $10^{-13}$ s$^{-1}$ (Fig. 1a). A range of geodynamic models employ strategies between the end member vertical strain rate average of the thin viscous sheet, and the significant vertical variation in strain rate of the channel flow model.

3.3. Seismological strain rate estimates

Whereas geodetic strain rates represent continuous deformation over some time period, seismic strain rates represent time-averaged slip along faults in earthquakes. By Kostrov summation (Kostrov, 1974; Jackson and McKenzie, 1988), a seismic strain rate tensor can be obtained from earthquake moment tensors determined in a seismic volume over a given time period. Comparing geodetic and seismic strain rates allows comparison of aseismic and seismic deformation in a region. If seismic strain rates are low compared to geodetic strain rates, then either some deformation occurs aseismically, or the time of observation is shorter than the recurrence time of major earthquakes.

A comparison of seismic and aseismic strain rates for Iran, where the combined instrumental and historical earthquake catalogues go back over a millennium, has shown a large contrast in deformation style across the country (Masson et al., 2005). In Zagros, southern Iran, > 95% of strain is accommodated aseismically, although intensive microseismic activity is spatially correlated with this deformation. In contrast, northern Iran experiences large earthquakes that account for 30 - 100% of the geodetically determined strain. A reason for the largely aseismic strain accommodation in southern Iran could be that a salt layer decouples an upper, 8 - 10 km thick, aseismically deforming, sedimentary cover from underlying basement rocks, leading to a thin seismogenic thickness (Jackson and McKenzie, 1988).
northern Iran, few large earthquakes may accommodate the majority of the displacement because deformation occurs in characteristic earthquakes on a few, major strike-slip faults (Masson et al., 2005). Kreemer et al. (2002) have also argued that low seismicity rates, in regions of high geodetic strain rate along major strike-slip faults, can result from faults hosting few but large characteristic earthquakes. Such regions would lack small earthquakes relative to predictions by a Gutenberg-Richter relationship (Wesnousky, 1994).

Although seismic strain rates may differ from geodetic and geological rates, they are particularly informative where other data are not available, such as for regions, depths, and time periods for which reliable geodetic data do not exist. Masson et al. (2005) found that although magnitudes of seismic and aseismic strain rates differ in places, orientations of principal strain axes are comparable. This observation was also made by Ekström and England (1989), who found that seismic strain rates were systematically smaller than expected from relative plate motions, but provided reliable estimates for the orientations of the principal horizontal strains. Therefore, summation of moment tensors may allow velocity fields to be calculated over time periods much longer than the geodetic record. For example, in deforming Asia the strain rate tensor based on instrumental and historical earthquakes show little difference from the velocity field indicated by paleomagnetic rotations in Cretaceous rocks (Holt and Haines, 1993). Furthermore, seismic strain rates can be estimated at depths where geodetic data are not available, and have for example been used to estimate a strain rate magnitude of $\sim 1 \times 10^{-15} \, \text{s}^{-1}$ within slabs subducted to depths in excess of 75 km, implying significant internal deformation in these deeply subducted slabs of oceanic lithosphere.
(Bevis, 1988; Holt, 1995).

3.4. Temporal Variations in Strain Rate

Attempts to correlate decadal geodetic and seismic observations with much longer term geological estimates of strain rate have shed light on temporal strain rate variations at timescales of multiple seismic cycles. For example, tectonic reconstructions of the Hikurangi Margin, North Island, New Zealand, show approximately constant rates since 1.5 Ma (Nicol et al., 2007). These near-constant long-term rates are compatible with geodetic strain estimates reflecting deformation in the last 10 - 15 years (Wallace et al., 2004). Thus, Nicol and Wallace (2007) concluded that on a million year timescale, strain rates can be essentially steady for a significant portion of the seismic cycle, with the corollary that GPS largely measures elastic strains that will be converted to permanent, localised deformation along faults in coseismic earthquake slip. Similar comparisons between decadal and million year strain rate estimates have been made elsewhere, including the Arabia-Eurasia collision zone (Allen et al., 2004), southwest United States (McCaffrey, 2005), and the Andes (Hindle et al., 2002). Like in New Zealand, these areas of well studied, regional crustal deformation show current geodetically determined strain rates within error of the geological strain rates estimated for the last few million years.

In contrast, the Tibetan Plateau has been an area of considerable controversy. Slip rates on major faults agree between geological and geodetic data; however, geomorphological data suggest more rapid motion over timescales of kyrs. Strain rate maps derived from InSAR and GPS demonstrate that at the present day, strain rates are relatively uniform within the Tibetan
Plateau at $10^{-15}$ s$^{-1}$ (Wang and Wright, 2012; Garthwaite et al., 2013)(Fig. 2c). Major Tibetan faults accumulate strain at rates generally less than 1 cm/yr, resulting in near negligible increases in surface strain rate. Interestingly, broad zones of slightly elevated strain rate are associated with faults that have experienced recent earthquakes (Wang and Wright, 2012; Garthwaite et al., 2013), for example the Kunlun fault (Garthwaite et al., 2013)(Fig. 2c). In addition, Daout et al. (2018) recently used InSAR data to highlight a wide zone of active strike-slip shear along the Jinsha suture, indicating reactivation of a lithospheric weakness that lacks expression of surface faulting. These observations highlight that long-term time-averaged strain rate estimates need to consider temporal variations within the earthquake cycle. Temporal strain rate variation is also seen in the Central Nevada Seismic Belt, where uplift detected by InSAR can be explained by postseismic mantle relaxation lasting several decades after major earthquakes (Gourmelen and Amelung, 2005).

Chatzaras et al. (2015) have provided a model for time-dependent interaction between rheologically distinct mantle and crust. Their model is based on that low resolved shear stresses (less than 10 MPa) are recorded in both the frictional crust and viscous mantle of the San Andreas fault. They suggest an integrated crust-mantle system where distributed mantle deformation controls displacement, and loads the upper crust until its frictional failure strength is reached. This model implies that mantle deformation should accelerate as strain rate increases post-seismically, as seen for example after major earthquakes in southern California (Freed and Bürgmann, 2004), and that the next earthquake will occur where failure strength is first overcome.
above a broad deforming zone in the mantle. Although designed for strike-slip faults (Chatzaras et al., 2015), this model may also explain the spatial and temporal strain rate variations cited above in collisional settings.

Geodetic strain rate estimates may be similar to strain rates inferred from the rock record of the last few million years of deformation. However, the geological records at several active zones of convergence show variation in the spatial distribution of strain rate on the multi-million year time scale. In the Himalayas, deformation can be interpreted to have gradually migrated onto the current locus at the orogenic front over a few tens of millions of years, as material accreted in the now > 100 km wide zone of finite strain in the Himalayan arc (Fig. 2c)(Avouac, 2008). In the Central Andes, shortening currently accommodated by distributed strain in the foreland is faster than at 25 - 10 Ma, a time when convergence occurred at up to twice the current rate (Hindle et al., 2002). Hindle et al. (2002) interpreted this temporal change in strain rate partitioning to reflect a change in interseismic coupling, with convergence prior to 10 Ma dominantly accommodated by stable sliding localised along the megathrust, with little hanging wall shortening. This change from localised to distributed strain (and therefore strain rate) may reflect a change in the physical properties at the megathrust itself. Similarly, strain localised along many currently active faults in the Arabia-Eurasia collision zone occurs at strain rates that far exceed those calculated from their finite strain over the life time of the orogen (Allen et al., 2004). Allen et al. (2004) explain that currently active faults, located in areas of low elevation at the edges of the collision zone, initiated or took up increasing amounts of strain after 7 Ma. In earlier stages of collision, deformation occurred in what
is now uplifted regions with thickened crust. Similarly, shortening across the Himalayan mountain range does not occur on the high Tibetan Plateau, but has localised to the Main Himalayan Thrust Zone at the orogenic front in Nepal (Fig. 2c,d), for at least the last 20 Ma (Bilham et al., 1997; Bollinger et al., 2006; Avouac, 2008). These examples show that partitioning of deformation varies in time and space as convergent and collisional margins evolve, with deformation either slowing or accelerating in a given zone over time. Thus, a particular strain rate field is unlikely to be maintained for more than a few million years, substantially less than the lifetime of an orogen. Consequently, a bulk strain rate calculated from finite geological strain across an orogenic belt will not represent local, temporal strain rates that may control the bulk rheology at a given period of time.

4. Strain within and around faults

The earthquake cycle includes high strain rate slip that lasts from seconds to minutes, associated with brittle failure of the upper, elastic layer, followed by slower postseismic transient creep that decays towards steady-state interseismic deformation rates driven by viscous creep at depth (e.g. Hetland and Hager, 2005; Handy et al., 2007; Wang et al., 2012). Postseismic transients are attributed to viscoelastic relaxation of the lower crust and/or upper mantle, and/or afterslip caused by creep within the brittle fault zone (e.g. Wright et al., 2013). Variations in strain rates through the earthquake cycle are recorded as mutually crosscutting relationships between pseudotachylyte and mylonites in the rock record (Fig. 3a)e.g. Sibson, 1980a; Price et al., 2012; Menegon et al., 2017), and maybe also by mutually cross-cutting con-
tinuous and discontinuous deformation structures (Fig. 3b)(Fagereng and
Sibson, 2010; Rowe and Griffith, 2015). It is possible, maybe even likely,
that peak strain rates derived from quartz paleopiezometry (e.g. Boutonnet
et al., 2013; Viegas et al., 2016) could be related to post-seismic afterslip. In
the following section, we review strain rates associated with the earthquake
cycle on individual fault zones from both geodetic and geological perspec-
tives, since both records agree that strain rate is not constant in time.

4.1. Surface deformation during the interseismic period

Geodetic observations record surface strain, and hence underestimate
strain rates generated in the deep portions of fault zones. To illustrate,
Savage and Burford (1973)’s widely used model of interseismic strain accu-
mulation shows that surface velocity, \( u \), at a distance \( x \) caused by slip rate
of \( s \) on an infinitely long vertical, strike-slip fault with a locked elastic lid of
thickness \( d \) is given by \( u(x) = \frac{s}{\pi} \arctan \frac{x}{d} \). The shear strain rate is given by
the derivative, such that \( \dot{\gamma}(x) = \frac{s}{\pi d (1 + x^2/d^2)} \), and the peak strain rate mea-
sured at the surface, \( \dot{\gamma}_{\text{max}} = \frac{s}{\pi d} \), depends not only on the slip rate across the
fault, but also the locking depth. Thus a slip rate of 1 cm/yr with a locking
depth of 20 km would produce a peak surface strain rate of \( 5 \times 10^{-15} \text{s}^{-1} \),
but \( 2 \times 10^{-14} \text{s}^{-1} \) for a locking depth of 5 km (Fig 4).

Thus surface strain rate alone is not a direct indicator of strain rates
within a fault zone itself. Locking depth must also be considered when inter-
preting geodetic strain measurements. Locking depth is considered broadly
equivalent to the frictional-viscous transition, and across the continents typ-
ically lies within a range of 14 ± 7 km (Wright et al., 2013). In contrast to
oceanic crust, where locking depth varies smoothly as a function of temper-
ature, variations in continental locking depth do not correlate strongly with variations in crustal thickness, and it has therefore been suggested that variations in lithology and strain rate can be responsible (Wright et al., 2013). However, heat flow also varies significantly throughout continents, particularly as a function of tectonic regime, and long wavelength variations in thermal structure has successfully explained much of the depth variations in the seismologically determined locking depth (e.g. Sibson, 1984; Tse and Rice, 1986; McKenzie et al., 2005). Maggi et al. (2000) reviewed variations in earthquake focal depths, and suggested close correlation between elastic and seismogenic thickness, consistent with a first order dependence of locking depth on temperature, and secondary variations caused by lithology and fluid content.

Relatively few faults exhibit creeping behaviour, with slip extending all the way to the surface (Burford and Harsh, 1980; Lee et al., 2001; Harris, 2017). We expect the greatest rates of geodetic surface strain to be associated with these creeping faults. For example, the maximum rate of surface strain in California occurs on the creeping segment of the San Andreas fault, where slip rates up to 28 mm/yr generate surface strain rates that locally reach $2 \times 10^{-13} \text{ s}^{-1}$ (Tong et al., 2013)(Fig. 2a). Deformation associated with fluid flow within weakened fault rocks may well enhance shallow strain rate values, however, through alteration to frictionally weak minerals, or local elevation in fluid pressures (Rice, 1992; Wintsch et al., 1995). Ingleby and Wright (2017) have suggested that Omori-like decay of postseismic velocities is consistent with rate-and-state friction or power law shear zone models, implying that postseismic creep is also localised within a narrow tabular
zone. The fact that localised shear strain rate at depth is not fully recorded in the broad deformation field generated at the surface, may explain the order of magnitude difference between the Global Strain Rate Map (Kreemer et al., 2014), which considers the surface strain during interseismic periods, and the geological estimates of Pfiffner and Ramsay (1982), which consider the total intergrated strain.

4.2. Postseismic surface deformation

Elevated rates of surface deformation have been detected following more than 20 earthquake sequences (Wright et al., 2013). Models of the earthquake cycle show that viscous postseismic transients occur when the earthquake return period is much longer than the relaxation time (Savage and Prescott, 1978; Hetland and Hager, 2005). Models typically require Maxwell viscosities in the range $10^{17} - 7 \times 10^{19}$ Pas to fit observational strain data (Wright et al., 2013), but the associated changes in velocity are on the order of mm/yr and occur over wavelengths of tens of kilometers, so the associated surface strain rates rarely exceed $10^{-15}$ s$^{-1}$ (e.g. Wang and Wright, 2012). As argued above, however, even slightly elevated surface strain rate could translate into a much greater increase in subsurface strain rate if it reflected postseismic strain localised along the deep extension of crustal faults.

Afterslip within the brittle fault zone can amount to a significant portion of the coseismic slip and produce surface displacements (e.g. Reilinger et al., 2000; Lee et al., 2006; D’Agostino et al., 2012). Afterslip is associated with velocity-strengthening frictional properties and attempts have been made to model it with rate-and-state friction (e.g. Perfettini and Avouac, 2007). However, high resolution GPS and InSAR studies show short wavelength (less
than a few km) variations in afterslip that can only be attributed to along-
strike variations in frictional properties that possibly relate to differences in
lithology (Barbot et al., 2009; Floyd et al., 2016). Because fault geometry
and material properties at depth cannot be determined from observations of
surface deformation patterns alone, we return to the geological data set to
discuss strain accommodation within localised structures.

4.3. Shear Strain within Fault Zones

Geodetic models of strain accumulation cannot distinguish between slip
on a single dislocation and that in a wider, tabular shear zone. Thus, esti-
mates of strain rate within fault zones rely on geological observations of fault
zone structure and dimensions. Sibson (2003) argued that the coseismic slip
zone is commonly < 10 cm, so that the $\dot{\gamma}$ for seismic slip rates of 1 m/s
becomes $\geq 10$ s$^{-1}$, assuming the coseismic slip zone behaves as a contin-
umum (Fig. 1a). Such localised principal slip zones, commonly embedded in
wider damage zones, are typical of faults in crystalline rocks, as described by
Chester and Logan (1987) for the Punchbowl fault, and also seen in several
other continental faults (Fig. 3c). In contrast, Burford and Harsh (1980) re-
ported that aseismic distortion along a creeping segment of the San Andreas
fault is accommodated within simple shear zones up to 15 metres wide. In
these zones, taking the creep rate as 10s of millimetres per year (e.g. Titus
et al., 2006), $\dot{\gamma}$ can be approximated to an order of magnitude as $10^{-3}$ yr$^{-1}$
or $10^{-11}$ s$^{-1}$ (Fig. 1a), which is orders of magnitude faster than peak surface
strain rates estimated at the resolution of the GSRM (Fig. 2a). While creep-
ing faults in the upper crust are relatively unusual (Harris, 2017), mid- to
lower crustal mylonites are typically inferred to accommodate steady creep,
or transient afterslip, over thicknesses of metres to kilometres. These shear zone widths imply strain rates ranging from $10^{-10}$ s$^{-1}$ to $10^{-14}$ s$^{-1}$ if slip rates are 1 - 10 mm/yr for shear zone width of 1 to 1000 m. Paleopiezometry results obtained from monomineralic quartz layers in viscous shear zones reflect strain rates in this range (Fig. 1a)(Gueydan et al., 2005; Boutonnet et al., 2013; Cross et al., 2015). Although some mylonites record relatively homogeneous strain (Fig. 3d), others have accumulated heterogeneous strain (Fig. 3e), implying variable degrees of localisation, which by our logic implies heterogeneous strain rate. An end-member example of such heterogeneity may be the discrete discontinuities observed within a zone of continuous deformation structures in mélangé shear zones (Fagereng and Sibson, 2010; Ujiie et al., 2018)(Fig. 3f). In such mélanges, deformation occurs both in mm-cm wide principal slip zones, and distributed through matrix material over metres to hundreds of metres (Rowe et al., 2013). Thus, overall, localised deformation within high strain zones, which could be either steady or transient, appears to occur at rates that range from $< 10^{-10}$ s$^{-1}$ to $> 10$ s$^{-1}$. Strain rates may be partitioned between individual, relatively homogeneous structures of different widths (Fig. 3c,d), or within a single, heterogeneous zone with variable degrees of strain localization (Fig. 3e,f).

We know that major shear zones typically contain thinner, anastomosing ultramylonites separating less deformed protomylonite to mylonite domains (e.g. Coward, 1990; Carreras, 2001; Rennie et al., 2013), meaning that strain rates within kilometre-scale shear zones are likely higher than the minimum estimated for their bulk. Evidence of strain localization, coupled with geometrical arguments of associated strain rate distribution over many orders
of magnitude (Fig. 1a), raise the question of how representative an average
strain rate of \(10^{-14}\ \text{s}^{-1}\) is in space. This point is emphasised by the range of
strain rates inferred from calculations based on paleopiezometry (e.g. Guey-
dan et al., 2005)(Fig. 1a).

An additional set of field observations is how structures crosscut each
other. Pseudotachylytes, ‘fossilised’ and variably crystallised friction melt
interpreted as unequivocal evidence for earthquake slip (cf. Cowan, 1999),
are reported both crosscutting and locally overprinted by mylonitic fabric in
a range of tectonic settings (Sibson, 1980b; Price et al., 2012; White, 2012;
Menegon et al., 2017)(Fig. 3a). This mutually crosscutting relationship
implies a strain rate cycling between spatially distributed, but temporally
steady or transient, viscous flow in the mylonite, likely at \(\dot{\gamma} \leq 10^{-10}\ \text{s}^{-1}\), and
seismic slip at rates exceeding \(10\ \text{s}^{-1}\). Examples of this strain rate cycling
are particularly abundant in places where shear zones were active within
relatively dry, strong, middle to lower crust (Sibson, 1980b; Menegon et al.,
2017; Hawemann et al., 2018).

Recently, Rowe and Griffith (2015) noted evidence for several other in-
dicators, in the rock record, of frictional heating to temperatures too low
to produce melting, but which also imply dynamic, elevated strain rates.
Similarly, other mutually crosscutting structures implying different degrees
of strain localisation, such as hydrothermal veins and synmetamorphic fo-
liations in subduction-related thrust-sense mélangé shear zones (Fig. 3b),
may also reflect cycling between relatively steady and dynamic strain rates
(Fagereng et al., 2011, 2018; Ujiie et al., 2018). Such temporal variations are
not captured by bulk strain rate estimates.
A note of caution on when and where to invoke strain localisation, however, is raised from observations of distributed strain in lower crustal and upper mantle rocks that lack signs of local high strain domains but record low differential stresses. For example, olivine grain size paleopiezometry in mantle xenoliths from the San Andreas transform fault system implies that increased mantle strain rates following crustal earthquakes can be accommodated by viscous dissipation of stress across a deforming zone much wider than in the overlying crust (Chatzaras et al., 2015). In another continental transform system, the Marlborough fault system of New Zealand’s South Island, lack of Moho displacement and pervasive seismic anisotropy below the faulted upper crust has also been interpreted to show strain distributed over a wide zone in the lower crust and upper mantle (Wilson et al., 2004).

Handy et al. (2007) reviewed the structure of continental faults below the transition from dominantly frictional deformation in the upper crust to dominantly thermally activated viscous deformation in the lower crust and upper mantle. They make the point that the structure and rheology of faults and shear zones depends on their strain and thermal histories. Pennacchioni and Mancktelow (2018) make the case that geometry of small scale shear zones is pre-determined by precursor heterogeneities such as fractures or low viscosity compositional layers. However, over time, additional mechanisms to develop and grow weak zones in the lower crust include networking of shear zones with increasing strain (Handy, 1994) and reaction weakening with increasing fluid-rock interaction (Wintsch et al., 1995). Handy et al. (2007) raise examples of faults that show fast post-seismic deformation that is well fitted to a localised low viscosity zone in the lower crust, such as the
North Anatolian transform fault of Turkey (Bürgmann et al., 2002) and the Chelungpu thrust fault in Taiwan (Hsu et al., 2002), and contrast these with faults where only minor surface displacement is recorded after major earthquakes, including the 2001 Bhuj intraplate thrust event in India (Jade et al., 2002). In summary, it is likely that strain localisation in the lower crust requires some long-term thermal and/or kinematic weakening effects, although it is also promoted by stress increases down-dip of major earthquakes (Ellis and Stöckhert, 2004).

5. Spatiotemporal strain rate distribution and average strain rate

Overall, the observations we have collated show that where strain is not localised, strain rates are commonly $10^{-15}$ s$^{-1}$ or slower, particularly if averaged over multiple earthquake cycles. Higher strain zones, in contrast, typically record strain rates of $10^{-14}$ s$^{-1}$ or greater. Strain rates in high strain zones are likely underestimated, particularly where they are calculated from geodetic data. There are at least two reasons for this: (1) the spatial resolution of the data is not sufficient to identify high strain zones within anastomosing networks, which are known to exist from geological maps of shear zones (e.g. Carreras, 2001; Rennie et al., 2013); and (2) except along faults that creep steadily at the surface, surface strain rates underestimate strain rates on localised structures at depth (Fig. 4). We therefore highlight a need for care when comparing strain rates determined from geodetic data to those estimated from geological observations of rocks deformed at depth.

A picture arises of high strain zones accommodating strain rates faster than an average near $10^{-14}$ s$^{-1}$, separating lower strain blocks where transient
strain rate increases may occur, but average strain rate is less than $10^{-14}$ s$^{-1}$.

Strain rate estimates based on a combination of microstructural observations and empirical stress-grain size and stress-strain rate relationships imply that the maximum strain rate within viscous high strain zones is in the range of $10^{-13}$ s$^{-1}$ to $10^{-8}$ s$^{-1}$ (e.g. Gueydan et al., 2005; Boutonnet et al., 2013; Viegas et al., 2016). Thus, while $10^{-14}$ s$^{-1}$ may be a good estimate for the time-averaged bulk strain rate in an orogen, it does not represent the range of strain rates evidenced by the rock record. Low strain areas record slower strain rates. In contrast, localised high strain zones that are active for limited amounts of time accommodate strain rates higher than average (Fig. 1a).

On time scales comparable to the seismic cycle, seismological and geodetic networks in well instrumented, actively deforming areas record a spectrum of deformation rates (e.g. Peng and Gomberg, 2010). This spectrum ranges from plate tectonic displacement rates of mm/yr to earthquakes of m/s, through geodetically detected ‘slow slip’ of cm/week, to very low and low frequency earthquakes defined as seismic phenomena, with slip speeds slower than 1 m/s but sufficient to radiate seismic wave energy. Thus, in contrast to a paradigm where slip speeds are either steady or seismic, a range of values are allowed by the observations. This raises a question when interpreting strain rates that are elevated relative to a global average. Do they record steady viscous creep, transient slow slip, or post-seismic afterslip within a narrow zone or zones? This is a question to consider in future high resolution geophysical experiments, and highlights the point that strain rates are constant in neither space nor time.

In essence, any calculation of mid- to lower crustal rheology over multiple
earthquake cycles requires an estimate of strain rate. Pfiffner and Ramsay (1982)’s estimate of $10^{-14} \text{s}^{-1}$ is reasonable as a time averaged, bulk strain rate. However, strain rate is not steady in either time or space as the locus of deformation shifts in both time and space. The spatiotemporal variation in strain rate may, intriguingly, reflect changes in rheology with progressive strain. Another question with scope for additional future study is therefore what controls spatiotemporal variations in strain rate, particularly where geological and geodetic strain rates disagree, as in the India-Eurasia collision zones (Wang and Wright, 2012; Garthwaite et al., 2013) and the Andes (Hindle et al., 2002).

6. Conclusion and consequences

High strain zones that traverse the lithosphere, which accommodate the bulk of continental deformation at any one time, typically deform at local and transient rates exceeding both the $10^{-14} \text{s}^{-1}$ estimated from bulk geological reconstructions (Pfiffner and Ramsay, 1982), and absolute rates estimated from geodetically determined surface velocity fields (Kreemer et al., 2014). Two consequences of this conclusion are: (1) if higher strain rates are inserted in crustal strength curves, this implies either higher stresses or lower strengths within high strain zones, relative to predictions using a $10^{-14} \text{s}^{-1}$ strain rate; and (2) in cases of spatiotemporal strain rate variations on timescales of the earthquake cycle, there is a need for care in using time-averaged strain rates in estimating earthquake repeat times. The first of these consequences supports Bürgmann and Dresen (2008)’s banana split model for lithospheric strength distribution, with lateral strength and strain
gradients around weak, high strain, plate boundary zones.

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Figure Captions

Figure 1: Examples of geologically estimated and geodetically calculated shear strain rates. a) Shear strain rate as a function of lengthscale, contoured for displacement rate in ideal simple shear. See text for details, and note that ellipses represent typical ranges but exceptions may occur. Note logarithmic axes, and that localisation of strain in zones thinner than one kilometre implies strain rates faster than $10^{-14} \text{s}^{-1}$ for displacement rates greater than 0.1 mm/yr, whereas estimates for deformation distributed over larger areas produces strain rates less than $10^{-15} \text{s}^{-1}$.

b) The distribution of strain rates taken from the deforming zones in the Global Strain Rate Model (Kreemer et al., 2014) compared to those of Pfiffner and Ramsay (1982). ‘Deforming zones’ are defined as plate boundaries and zones of diffuse deformation separating rigid plates, amounting to about 14 % of the Earth’s surface (Kreemer et al., 2014).

Figure 2: Strain rate and seismicity in California, USA, and strain rate and topography for the Himalayan orogen. The strain rate maps show the 2nd invariant of strain rate as determined by the Global Strain Rate Map project (Kreemer et al., 2014) at 0.1° resolution. (a) Strain rate in California. Note the localisation, by at least an order of magnitude in strain rate, into the San Andreas fault system, which deforms at a strain rate greater than $10^{-14} \text{s}^{-1}$.

(b) Earthquakes with magnitude 3.0 or greater recorded in the NEIC catalogue since 1970. (c) Strain rate in the Himalayan orogen. Note the increase by at least an order of magnitude at the Himalayan front, as well as along a few other localised (and potentially transient) active structures. (d) Eleva-
tion from the GEBCO 2014 grid at 30 second resolution (The GEBCO_2014
Grid, version 20150318, www.gebco.net). Figures created in Generic Map-
ping Tools (Wessel et al., 2013).

Figure 3: Examples of strain heterogeneity in the rock record, as shown by
brittle and ductile structures referring to mesoscopically discontinuous and
continuous deformation. Kinematics indicated by yellow arrows. (a) Duc-
tilely deformed pseudotachylyte (red arrow points to sheared injection vein)
that also crosscuts metamorphic tectonite (blue arrow), Nusfjord, Norway
(see Menegon et al., 2017, for more detail). (b) Hydrothermal veins cross-
cut metamorphic tectonite, but are also rotated and ductilely sheared. Both
veins and rotated foliation record normal shear sense. A later brittle fault
that is not ductilely deformed cuts through the centre of the veins implying
further brittle localisation with time. Makimine mélangé, Kyushu, Japan
(Ujiie et al., 2018). (c) Localised brittle deformation in the core of the San
Gabriel strike-slip fault, California, produced cataclasite in a narrow principal
slip zone. (d) Strain localisation within a relatively homogeneous ductile
shear zone, Nusfjord, Norway (see Menegon et al., 2017, for more detail). (e)
Quartz and felspar porphyroclasts behaving as relatively rigid bodies within
a lower viscosity biotite-rich matrix, Maud Belt, Antarctica. (f) A low com-
petency matrix enveloping sheared competent clasts in the Chrystalls Beach
Complex, New Zealand. Note thin cataclastic surfaces both parallel to, and
cross-cutting, the matrix cleavage (examples in dashed yellow lines).

Figure 4: Simple model of surface velocity and strain rate caused by inter-
seismic slip on an infinitely long strike-slip fault (Savage and Burford, 1973). Both parameters are controlled by locking depth, meaning geodetic measurements of strain do not accurately record localised strain rates at depth, particularly for regions with deep brittle-ductile transitions.
Table 1: Estimates of viscosity and strain rate from thin viscous sheet models of various continental regions. The quoted viscosities assume a power law exponent of $n=3$.

<table>
<thead>
<tr>
<th>Region</th>
<th>Viscosity</th>
<th>Strain Rate</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Arabian-Eurasia</td>
<td>$1 - 5 \times 10^{22}$</td>
<td>$3 \times 10^{-16} - 3 \times 10^{-15}$</td>
<td>Walters et al. (2017)</td>
</tr>
<tr>
<td>Anatolia</td>
<td>$3 \times 10^{21} - 10^{22}$</td>
<td>$6 \times 10^{-17} - 6 \times 10^{-15}$</td>
<td>England et al. (2016)</td>
</tr>
<tr>
<td>Tibet</td>
<td>$10^{22}$</td>
<td>$10^{-16} - 10^{-15}$</td>
<td>England and Molnar (1997)</td>
</tr>
<tr>
<td>Tibet</td>
<td>$5 \times 10^{21} - 5 \times 10^{22}$</td>
<td>$&lt; 5 \times 10^{-15}$</td>
<td>Flesch et al. (2001)</td>
</tr>
<tr>
<td>Tien Shan</td>
<td>$1 - 4 \times 10^{22}$</td>
<td>$10^{-15}$</td>
<td>England and Molnar (2015)</td>
</tr>
<tr>
<td>North America</td>
<td>$10^{21} - 10^{22}$</td>
<td>-</td>
<td>Flesch et al. (2000)</td>
</tr>
<tr>
<td>Appenines</td>
<td>$1.5 - 3 \times 10^{21}$</td>
<td>$2 \times 10^{-15}$</td>
<td>D’Agostino et al. (2014)</td>
</tr>
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Figure 1:
Figure 2:
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