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A Five Distance Theorem for Kronecker Sequences

Alan Haynes^{1,*} and Jens Marklof²

¹Department of Mathematics, University of Houston, Houston, TX 77204, USA and ²School of Mathematics, University of Bristol, Bristol BS8 1UG, UK

*Correspondence to be sent to: e-mail: alanhaynes@gmail.com

The three-distance theorem (also known as the three-gap theorem or Steinhaus problem) states that, for any given real number α and integer N , there are at most three values for the distances between consecutive elements of the Kronecker sequence $\alpha, 2\alpha, \dots, N\alpha \pmod{1}$. In this paper, we consider a natural generalization of the three-distance theorem to the higher-dimensional Kronecker sequence $\vec{\alpha}, 2\vec{\alpha}, \dots, N\vec{\alpha}$ modulo an integer lattice. We prove that in 2D, there are at most five values that can arise as a distance between nearest neighbors, for all choices of $\vec{\alpha}$ and N . Furthermore, for almost every $\vec{\alpha}$, five distinct distances indeed appear for infinitely many N and hence five is the best possible general upper bound. In higher dimensions, we have similar explicit, but less precise, upper bounds. For instance, in 3D, our bound is 13, though we conjecture the truth to be 9. We furthermore study the number of possible distances from a point to its nearest neighbor in a restricted cone of directions. This may be viewed as a generalization of the gap length in 1D. For large cone angles, we use geometric arguments to produce explicit bounds directly analogous to the three-distance theorem. For small cone angles, we use ergodic theory of homogeneous flows in the space of unimodular lattices to show that the number of distinct lengths is (1) unbounded for almost all $\vec{\alpha}$ and (2) bounded for $\vec{\alpha}$ that satisfy certain Diophantine conditions.

1 Introduction

Consider a finite set S_N comprising N distinct points ξ_1, \dots, ξ_N on the unit torus $\mathbb{T} = \mathbb{R}/\mathbb{Z}$. The points in S_N partition \mathbb{T} into N intervals, representing the *gaps* of S_N . We denote by

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$\delta_{n,N}$ the size of the n th gap, that is, the distance between ξ_n and its nearest neighbor *to the right*. We denote by $g_N = |\{\delta_{n,N} \mid 1 \leq n \leq N\}|$ the number of distinct gap sizes. For a generic choice of S_N one has $g_N = N$, since all gap lengths are generically distinct. A striking observation, known as the three-distance (or three-gap) theorem, is that for the Kronecker sequence $\xi_n = n\alpha + \mathbb{Z}$, one has $g_N \leq 3$, for any $\alpha \in \mathbb{R}$ and $N \in \mathbb{N}$; see [37–40] for the original proofs and [23, 26, 30, 32, 34–36] for alternative approaches. Natural extensions to return maps for billiards in rectangles and interval exchange transformations are discussed in [17, 19–21] and [41], respectively. There are various generalizations of the three-gap theorem to higher dimensions, several of which require Diophantine conditions on the choice of parameter. In the present paper, we discuss natural extensions of the three-distance theorem to higher-dimensional Kronecker sequences, which represent translations of a multidimensional torus by a vector $\vec{\alpha}$. We will here consider nearest neighbor distances as well as distances to neighbors in restricted directions. The former may be viewed as a special case of the setting of Biringer and Schmidt [2], who considered the number of distinct nearest neighbor distances for an orbit generated by an isometry of a general Riemannian manifold. If distances are measured by the maximum norm rather than a Riemannian metric, Chevallier [8, Corollaire 1.2] showed that there are at most five distinct distances for Kronecker sequences on 2D tori. Related studies in this context include the papers by Chevallier [9, 10, 12] and by Vijay [42]. For other higher-dimensional variants of the three-distance theorem, see [1, 3–5, 11, 13, 18, 22, 24, 26–28, 31].

Our setting is as follows. Let \mathcal{L} be a unimodular lattice in \mathbb{R}^d (one example to keep in mind is \mathbb{Z}^d) and consider a point set $S_N = \{\xi_1, \dots, \xi_N\}$ on the d -dimensional torus $\mathbb{T}^d = \mathbb{R}^d/\mathcal{L}$. The point set S_N that we are interested in is the d -dimensional Kronecker sequence,

$$S_N = S_N(\vec{\alpha}, \mathcal{L}) = \{\xi_n = n\vec{\alpha} + \mathcal{L} \mid 1 \leq n \leq N\} \subset \mathbb{T}^d, \quad (1.1)$$

for given $\vec{\alpha} \in \mathbb{R}^d$. Note that the ξ_n are not necessarily distinct if $\vec{\alpha} \in \mathbb{Q}\mathcal{L}$; in this case, we remove all multiple occurrences, and as a result the number of elements in S_N remains bounded as $N \rightarrow \infty$.

Let $\delta_{n,N}$ be the distance of ξ_n to its nearest neighbor with respect to the standard flat Riemannian metric on \mathbb{T}^d . As above, $g_N = g_N(\vec{\alpha}, \mathcal{L})$ denotes the number of distinct nearest neighbor distances $\delta_{n,N}$. Biringer and Schmidt [2] proved that, for all choices of \mathcal{L} , $\vec{\alpha}$, and N ,

$$g_N(\vec{\alpha}, \mathcal{L}) \leq 3^d + 1. \quad (1.2)$$

Our 1st theorem improves this bound and also gives the best possible result in dimension $d = 2$.

Theorem 1. For every unimodular lattice \mathcal{L} , $\vec{\alpha} \in \mathbb{R}^d$, and $N \in \mathbb{N}$, we have that

$$g_N(\vec{\alpha}, \mathcal{L}) \leq \begin{cases} 5 & \text{if } d = 2, \\ \sigma_d + 1 & \text{if } d \geq 3, \end{cases} \quad (1.3)$$

where σ_d is the kissing number for \mathbb{R}^d .

Recall that the *kissing number* σ_d for \mathbb{R}^d is the maximum number of non-overlapping spheres of radius one in \mathbb{R}^d which can be arranged so that they all touch the unit sphere in exactly one point. The study of kissing numbers has a long and interesting history and is connected to many areas of mathematics (see [6] and [33] for surveys of results). It is interesting to note that the three-distance theorem in dimension $d = 1$ is compatible with the bound $g_N \leq \sigma_1 + 1 = 3$, but that already in dimension $d = 2$ this becomes suboptimal, since here $\sigma_2 + 1 = 7 > 5$. A table of known bounds for kissing numbers in dimensions $d \leq 24$ is provided in Figure 1. Our corresponding bounds for g_N in dimensions $d = 3, \dots, 10$ are therefore 13, 25, 46, 79, 135, 241, 365, 555. We do not claim that these bounds are optimal for any dimension $d \geq 3$. In particular, we conjecture that $g_N(\vec{\alpha}, \mathcal{L}) \leq 9$ for $d = 3$. This conjecture is based on numerical experiments by Dettmann [16] that produced no more than nine distinct gaps. Figures 2 and 3 show examples where 5 (for $d = 2$) and 7 (for $d = 3$) distinct distances are obtained.

For general d , it follows from Theorem 1 together with an estimate for σ_d due to Kabatiansky and Levenshtein (see [29, Theorem 4, Corollary 1] or [14, Chapter 9]) that

$$g_N(\vec{\alpha}, \mathcal{L}) \leq 2^{0.401d(1+o(d))} \quad \text{as } d \rightarrow \infty. \quad (1.4)$$

The rate of convergence of the $o(d)$ term in this estimate can be made more precise and explicit (non-asymptotic) upper bounds can also be obtained by applying [29, Equation (52)].

Values of $\vec{\alpha}$ for which $g_N(\vec{\alpha}, \mathcal{L}) = 5$ are surprisingly rare. Our 1st computer search, which took 1000 randomly and uniformly selected numbers $\vec{\alpha} \in [0, 1)^2$ and checked $g_N(\vec{\alpha}, \mathbb{Z}^2)$ for all $N \leq 10^4$, found only five values of $\vec{\alpha}$ for which there was an N with $g_N(\vec{\alpha}, \mathbb{Z}^2) = 5$.

d	Upper bound for σ_d	d	Upper bound for σ_d
1	2	13	2069
2	6	14	3183
3	12	15	4866
4	24	16	7355
5	45	17	11072
6	78	18	16572
7	134	19	24812
8	240	20	36764
9	364	21	54584
10	554	22	82340
11	870	23	124416
12	1357	24	196560

Fig. 1. A table of known bounds for kissing numbers. All bounds are taken from [6], and bounds listed in bold face are known to be best possible.

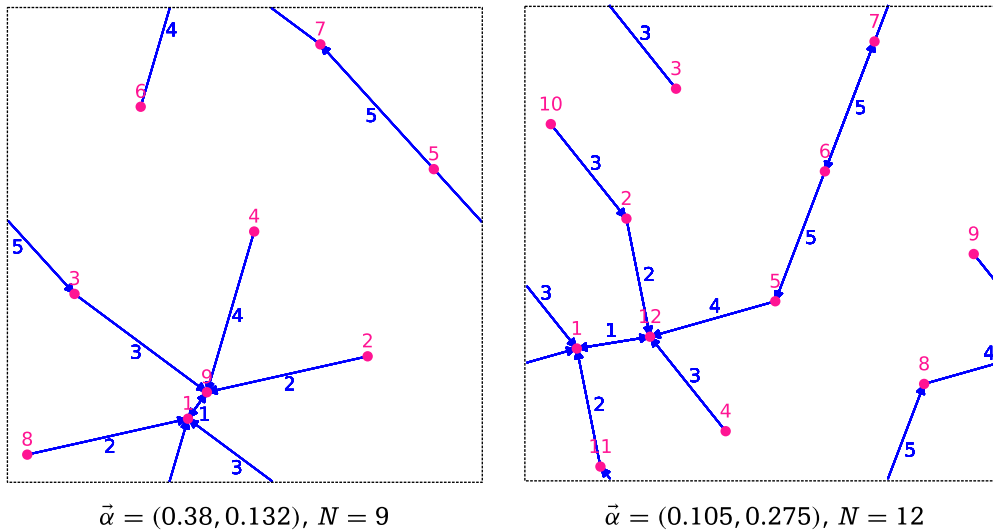


Fig. 2. The nearest neighbor graph for the Kronecker sequence $n\vec{\alpha} + \mathbb{Z}^2$ ($n = 1, \dots, N$) in the torus $\mathbb{R}^2/\mathbb{Z}^2$ (the unit square with opposite sides identified), for $N = 9$ (left) and $N = 12$ (right) and different choices of $\vec{\alpha}$. The vertex representing $n\vec{\alpha} + \mathbb{Z}^2$ is labeled by n and colored in pink. The blue directed edges point from a vertex to its nearest neighbor(s). The blue edge labels correspond to the indices of each of the five distinct distances. Note that in each example there is a vertex with two nearest neighbors: vertex $n = 5$ on the left and $n = 6$ on the right.

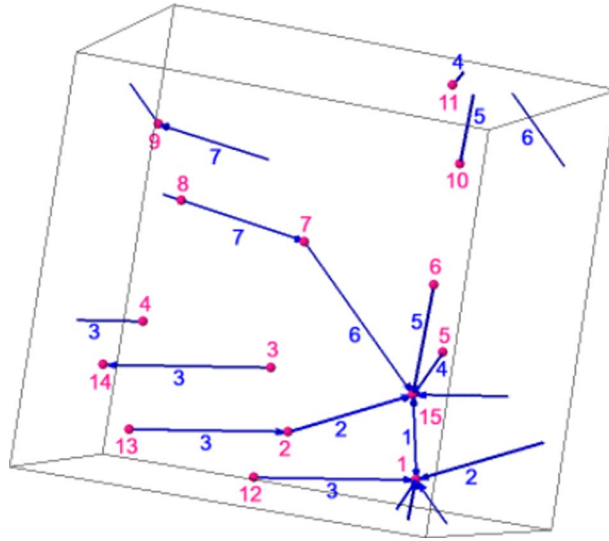


Fig. 3. The nearest neighbor graph for the Kronecker sequence $n\vec{\alpha} + \mathbb{Z}^3$ ($n = 1, \dots, 15$) in the torus $\mathbb{R}^3/\mathbb{Z}^3$ (the unit cube with opposite faces identified), for $\vec{\alpha} = (\frac{46}{125}, \frac{107}{500}, \frac{43}{500})$. The vertex representing $n\vec{\alpha} + \mathbb{Z}^3$ is labeled by n and colored in pink. The blue directed edges point from a vertex to its nearest neighbor(s). The blue edge labels correspond to the indices of each of the seven distinct distances.

Nevertheless, as we will now see, every numerical example gives rise to a lower bound for an infinite sequence of N and for almost every $\vec{\alpha}$. In what follows, we say a sequence $N_1 < N_2 < N_3 < \dots$ of integers is *sub-exponential* if

$$\lim_{i \rightarrow \infty} \frac{N_{i+1}}{N_i} = 1. \tag{1.5}$$

Theorem 2. Let \mathcal{L} and \mathcal{L}_0 be unimodular lattices. There is a $P \subset \mathbb{R}^d$ of full Lebesgue measure, such that for every $\vec{\alpha} \in P$, $\vec{\alpha}_0 \in \mathbb{R}^d$, and for every sub-exponential sequence $(N_i)_i$, we have

$$\limsup_{i \rightarrow \infty} g_{N_i}(\vec{\alpha}, \mathcal{L}) \geq \sup_{N \in \mathbb{N}} g_N(\vec{\alpha}_0, \mathcal{L}_0). \tag{1.6}$$

In dimension $d = 2$, the choices $\vec{\alpha}_0 = (\frac{19}{50}, \frac{33}{250})$, $N = 9$, and $\mathcal{L}_0 = \mathbb{Z}^2$ (this is the example in Figure 2, left) produce precisely five distinct distances given by

$$\begin{aligned} \delta_{1,N} &= \frac{\sqrt{74}}{125} \approx 0.0688, & \delta_{2,N} &= \frac{\sqrt{\frac{3793}{2}}}{125} \approx 0.3484, & \delta_{3,N} &= \frac{\sqrt{1901}}{125} \approx 0.3488, \\ \delta_{4,N} &= \frac{\sqrt{\frac{157}{2}}}{25} \approx 0.3544, & \delta_{5,N} &= \frac{3\sqrt{221}}{125} \approx 0.3568. \end{aligned}$$

Moreover, for $d = 3$, $\vec{\alpha}_0 = (\frac{46}{125}, \frac{107}{500}, \frac{43}{500})$, $N = 15$, and $\mathcal{L}_0 = \mathbb{Z}^3$ (cf. Figure 3), we have seven distinct distances,

$$\begin{aligned} \delta_{1,N} &= \frac{17\sqrt{\frac{7}{2}}}{125} \approx 0.2544, & \delta_{2,N} &= \frac{\sqrt{\frac{13513}{2}}}{250} \approx 0.3288, & \delta_{4,N} &= \frac{21\sqrt{\frac{37}{2}}}{250} \approx 0.3613, \\ \delta_{5,N} &= \frac{\sqrt{\frac{177}{2}}}{25} \approx 0.3763, & \delta_{6,N} &= \frac{\sqrt{\frac{19237}{2}}}{250} \approx 0.3923, & \delta_{7,N} &= \frac{\sqrt{\frac{2866}{125}}}{125} \approx 0.4283, \\ \delta_{8,N} &= \frac{\sqrt{\frac{23577}{2}}}{250} \approx 0.4343. \end{aligned}$$

Applying these data to Theorem 2, combined with the upper bound of 5 in Theorem 1, we immediately obtain the following result.

Theorem 3. Let $d = 2$ or 3 . For any unimodular lattice \mathcal{L} in \mathbb{R}^d , there is a set $P \subset \mathbb{R}^d$ of full Lebesgue measure, such that for every $\vec{\alpha} \in P$, and for every sub-exponential sequence $(N_i)_i$, we have that

$$\limsup_{i \rightarrow \infty} g_{N_i}(\vec{\alpha}, \mathcal{L}) \begin{cases} = 5 & \text{if } d = 2, \\ \geq 7 & \text{if } d = 3. \end{cases} \quad (1.7)$$

Thus, the upper bound of 5 in Theorem 1 is indeed optimal for every \mathcal{L} , almost every $\vec{\alpha}$ and infinitely many N .

In dimension $d = 1$, nearest neighbor distances do not necessarily coincide with the set of gap lengths, as gaps are the distance to the nearest neighbor in a fixed direction. To generalize this interpretation of a gap to higher dimensions, fix a subset \mathcal{D} of the unit sphere \mathbb{S}_1^{d-1} , and denote by $\delta_{n,N}(\mathcal{D})$ the distance from ξ_n to its nearest neighbor *in the direction of* \mathcal{D} . More precisely, denote by $\vec{\xi}_n \in \mathbb{R}^d$ a fixed representative of the coset $\xi_n \bmod \mathcal{L}$ so that $\xi_n = \vec{\xi}_n + \mathcal{L}$ and define

$$\delta_{n,N}(\mathcal{D}) = \min\{|\vec{\xi}_m - \vec{\xi}_n + \vec{\ell}| \mid \vec{\xi}_m - \vec{\xi}_n + \vec{\ell} \in \mathbb{R}_{>0}\mathcal{D}, 1 \leq m \leq N, \vec{\ell} \in \mathcal{L}\}, \quad (1.8)$$

where $|\cdot|$ is the standard Euclidean norm in \mathbb{R}^d . For $\mathcal{D} = \mathbb{S}_1^{d-1}$, we recover the nearest neighbor distance

$$\delta_{n,N}(\mathbb{S}_1^{d-1}) = \delta_{n,N} = \min\{|\vec{\xi}_m - \vec{\xi}_n + \vec{\ell}| > 0 \mid 1 \leq m \leq N, \vec{\ell} \in \mathcal{L}\}. \quad (1.9)$$

In particular, note that the nearest neighbor of ξ_n might be ξ_n itself; in this case, $\delta_{n,N} = |\vec{\ell}|$ for suitable non-zero $\ell \in \mathcal{L}$.

As an illustration consider dimension $d = 1$. The circle of radius one is $\mathbb{S}_1^0 = \{-1, 1\}$ and the choice $\mathcal{D} = \{1\}$ produces the distance to the nearest neighbor to the right (which leads to the classical three-distance theorem). On the other hand,

$\mathcal{D} = \{-1, 1\}$ yields the distance to the nearest neighbor (in both directions). Since we are in dimension one, the set of distances to nearest neighbors is contained in the set of distances to nearest neighbors to the right, but it is not necessarily equal to it. However, for the case of the Kronecker sequence, the three-distance theorem also holds also for nearest neighbors. In other words, there are examples of α and N for which the number of distinct nearest neighbor distances is equal to three (e.g., take $\alpha = e$ and $N = 5$).

The central object of our study is the number $g_N(\mathcal{D})$ of distinct nearest neighbor distances in direction $\mathcal{D} \subseteq \mathbb{S}_1^{d-1}$,

$$g_N(\mathcal{D}) = |\{\delta_{n,N}(\mathcal{D}) \mid 1 \leq n \leq N\}|, \tag{1.10}$$

for $d \geq 2$. We will also write $g_N(\mathcal{D}) = g_N(\mathcal{D}, \vec{\alpha}, \mathcal{L})$ to highlight the dependence on vector and lattice.

We first present detailed results for dimension $d = 2$. In this case, \mathbb{S}_1^{d-1} is the unit circle in \mathbb{R}^2 . The following theorem deals with the case when $\mathcal{D} \subseteq \mathbb{S}_1^1$ is an interval of arclength $\tau > \pi$. (The case $\tau = 2\pi$ has already been covered in Theorem 1 and we include it here for completeness.)

Theorem 4. Let $d = 2$, and assume $\mathcal{D} \subseteq \mathbb{S}_1^1$ is a half-open interval of arclength $\tau > \pi$. Then for any unimodular lattice \mathcal{L} , $\vec{\alpha} \in \mathbb{R}^2$, and $N \in \mathbb{N}$, we have that

$$g_N(\mathcal{D}, \vec{\alpha}, \mathcal{L}) \leq \begin{cases} 5 & \text{if } \tau = 2\pi, \\ 9 & \text{if } 5\pi/3 < \tau < 2\pi, \\ 8 & \text{if } \tau = 5\pi/3, \\ 9 & \text{if } 4\pi/3 < \tau < 5\pi/3, \\ 8 & \text{if } \tau = 4\pi/3, \\ 12 + 2 \left\lfloor \frac{\sin(\tau/2 + \pi/6)}{\sin(\tau - \pi)} \right\rfloor & \text{if } \pi < \tau < 4\pi/3. \end{cases} \tag{1.11}$$

Related results in various settings have been obtained independently by Chevallier [9, 10, 12] and Vijay [42], but the precise description of the nearest neighbor problem that we give here does not appear to have been considered. However, the problem studied by Vijay in his paper “Eleven Euclidean distances are enough” [42] is roughly comparable to the special case of $\tau = 3\pi/2$ in Theorem 4 above.

By way of contrast with the upper bounds above, our next result demonstrates that the restriction in Theorems 1 and 4 to a “large” set of directions \mathcal{D} is essential. Note

that the upper bound for g_N in the final case of Theorem 4 tends to infinity as $\tau \rightarrow \pi^+$. In fact, in dimension $d = 2$ intervals $\mathcal{D} \subset \mathbb{S}_1^1$ of lengths $\tau < \pi$ produce unbounded numbers of distinct distances, for almost every $\vec{\alpha}$. This is part of the content of the following theorem, which also deals with analogous regions \mathcal{D} in higher dimensions.

Theorem 5. Let $d \geq 2$ and \mathcal{L} a unimodular lattice. There exists a set $P \subset \mathbb{R}^d$ of full Lebesgue measure, such that for every $\mathcal{D} \subset \mathbb{S}_1^{d-1}$ with non-empty interior and closure contained in an open hemisphere, for every $\vec{\alpha} \in P$, and for every sub-exponential sequence $(N_i)_i$, we have

$$\sup_i g_{N_i}(\mathcal{D}, \vec{\alpha}, \mathcal{L}) = \infty, \quad \liminf_i g_{N_i}(\mathcal{D}, \vec{\alpha}, \mathcal{L}) < \infty. \quad (1.12)$$

Our final observation is that the finite distance phenomenon is recovered in any dimension, for general test sets \mathcal{D} , if we impose Diophantine conditions on $\vec{\alpha}$. We say that $\vec{\alpha} \in \mathbb{R}^d$ is *badly approximable* by $\mathbb{Q}\mathcal{L}$ if there is a constant $c > 0$ such that $|n\vec{\alpha} - \vec{\ell}|_\infty > cn^{-1/d}$ for all $\vec{\ell} \in \mathcal{L}$, $n \in \mathbb{N}$. Here $|\cdot|_\infty$ denotes the maximum norm.

Theorem 6. Let $d \geq 2$, \mathcal{L} a unimodular lattice and $\vec{\alpha} \in \mathbb{R}^d$ badly approximable by $\mathbb{Q}\mathcal{L}$. For $\mathcal{D} \subseteq \mathbb{S}_1^{d-1}$ with non-empty interior, we have that

$$\sup_{N \in \mathbb{N}} g_N(\mathcal{D}, \vec{\alpha}, \mathcal{L}) < \infty. \quad (1.13)$$

For comparison, the more precise bounds in Theorems 1 and 4 hold for all $\vec{\alpha}$, but only for a restricted class of \mathcal{D} .

To relate the above Diophantine condition on $\vec{\alpha}$ to the standard notion of *badly approximable* by \mathbb{Q}^d (which corresponds to the special case $\mathcal{L} = \mathbb{Z}^d$), take $M_0 \in \mathrm{SL}(d, \mathbb{R})$ so that $\mathcal{L} = \mathbb{Z}^d M_0$. We then see that $\vec{\alpha} \in \mathbb{R}^d$ is badly approximable by $\mathbb{Q}\mathcal{L}$ if and only if $\vec{\alpha}_0 = \vec{\alpha} M_0^{-1}$ is badly approximable by \mathbb{Q}^d . (The positive constants c appearing in both definitions are not necessarily the same.) Furthermore, by Khintchine's transference principle (see the Corollary to Theorem II in [7, Chapter VI]), the vector $\vec{\alpha}_0$ is badly approximable by \mathbb{Q}^d if and only if there is $c > 0$ such that $\|\vec{m} \cdot \vec{\alpha}_0\|_{\mathbb{R}/\mathbb{Z}} > c|\vec{m}|^{-d}$ for all non-zero $\vec{m} \in \mathbb{Z}^d$. Here $\|x\|_{\mathbb{R}/\mathbb{Z}} = \min_{k \in \mathbb{Z}} |x + k|$ denotes the distance to the nearest integer.

The key strategy of the proofs of the above theorems is to express the quantities $S_N(\vec{\alpha})$, $\delta_{n,N}(\mathcal{D})$ and $g_N(\mathcal{D})$ in terms of functions on the space $\mathrm{SL}(d+1, \mathbb{Z}) \setminus \mathrm{SL}(d+1, \mathbb{R})$ of unimodular lattices in \mathbb{R}^{d+1} . This is explained in detail in Section 2. Once this

connection is established, the proofs of Theorems 1 and 4 reduce to geometric arguments involving lattices and sphere coverings, which are laid out in Sections 3–5 in dimension $d = 2$ and in Section 6 for dimensions $d \geq 3$. The proofs of Theorems 2, 5, and 6 require upper and lower bounds for the relevant functions on the space of lattices, combined with the same ergodic-theoretic arguments used in [27]. This material is presented in Section 7.

2 Reformulation in Terms of Lattices

This section follows the approach developed for the three-gap theorem [32] and higher-dimensional variants concerning gaps in values taken by linear forms and hitting times for toral rotations [27].

By substituting $k = m - n$ in equation (1.8), we find that the distance from ξ_n to its nearest neighbor in the direction of \mathcal{D} is given by

$$\begin{aligned} \delta_{n,N}(\mathcal{D}) &= \min\{|k\vec{\alpha} + \vec{\ell}| \mid k\vec{\alpha} + \vec{\ell} \in \mathbb{R}_{>0}\mathcal{D}, -n < k \leq N - n, \vec{\ell} \in \mathcal{L}\} \\ &= \min\{|k\vec{\alpha} + \vec{\ell}| \mid k\vec{\alpha} + \vec{\ell} \in \mathbb{R}_{>0}\mathcal{D}, -n < k < N_+ - n, \vec{\ell} \in \mathcal{L}\}, \end{aligned} \tag{2.1}$$

where $N_+ := N + \frac{1}{2}$. Select $M_0 \in \text{SL}(d, \mathbb{R})$ so that $\mathcal{L} = \mathbb{Z}^d M_0$, and let

$$A_N(\vec{\alpha}) = A_N(\vec{\alpha}, \mathcal{L}) = \begin{pmatrix} 1 & 0 \\ 0 & M_0 \end{pmatrix} \begin{pmatrix} 1 & \vec{\alpha} \\ 0 & \mathbf{1}_d \end{pmatrix} \begin{pmatrix} N^{-1} & 0 \\ 0 & N^{1/d} \mathbf{1}_d \end{pmatrix}. \tag{2.2}$$

Then we have that

$$\begin{aligned} \delta_{n,N}(\mathcal{D}) &= N_+^{-1/d} \min \left\{ |\vec{v}| \mid (u, \vec{v}) \in \mathbb{Z}^{d+1} A_{N_+}(\vec{\alpha}), \right. \\ &\quad \left. -\frac{n}{N_+} < u < 1 - \frac{n}{N_+}, \vec{v} \in \mathbb{R}_{>0}\mathcal{D} \right\}, \end{aligned} \tag{2.3}$$

for all $1 \leq n \leq N$. To cast this in a more general setting, let $G = \text{SL}(d + 1, \mathbb{R})$ and $\Gamma = \text{SL}(d + 1, \mathbb{Z})$. Then for general $M \in G$ and $t \in (0, 1)$, define

$$\mathcal{Q}_{\mathcal{D}}(M, t) = \{(u, \vec{v}) \in \mathbb{Z}^{d+1} M \mid -t < u < 1 - t, \vec{v} \in \mathbb{R}_{>0}\mathcal{D}\} \tag{2.4}$$

and

$$F_{\mathcal{D}}(M, t) = \min \{ |\vec{v}| \mid (u, \vec{v}) \in \mathcal{Q}_{\mathcal{D}}(M, t) \}. \tag{2.5}$$

In this notation, it is clear that

$$\delta_{n,N}(\mathcal{D}) = N_+^{-1/d} F_{\mathcal{D}} \left(A_{N_+}(\vec{\alpha}), \frac{n}{N_+} \right). \quad (2.6)$$

Before proceeding further, we first establish the following basic result.

Proposition 1. If $\mathcal{D} \subseteq \mathbb{S}_1^{d-1}$ has non-empty interior, then $F_{\mathcal{D}}$ is well defined as a function $\Gamma \backslash G \times (0, 1) \rightarrow \mathbb{R}_{>0}$.

Proof. We first show that the set $\mathcal{Q}_{\mathcal{D}}(M, t)$ is non-empty for all $M \in G$ and $t \in (0, 1)$. Fix any $\vec{w} \in \mathcal{D}^\circ$, and denote by $\Sigma_{\perp} \subset \mathbb{R}^d$ the $(d-1)$ -dimensional hyperplane perpendicular to \vec{w} . Denote by \vec{v}_{\perp} the orthogonal projection of \vec{v} to Σ_{\perp} . Given (M, t) , let $\epsilon > 0$ be sufficiently small so that (1) $\epsilon < \min\{t, 1-t\}$ and (2) there is no non-zero lattice point in $\mathbb{Z}^{d+1}M$ within ϵ -distance to the origin. Furthermore, fix $\delta > 0$ sufficiently small so that

$$\{\vec{v} \in \mathbb{R}^d \mid \vec{w} \cdot \vec{v} > \epsilon, |\vec{v}_{\perp}| < \delta\} \subset \mathbb{R}_{>0}\mathcal{D}. \quad (2.7)$$

Such a δ exists since $\vec{w} \in \mathcal{D}^\circ$. By construction,

$$\{(u, \vec{v}) \in \mathbb{Z}^{d+1}M \mid |u| < \epsilon, \vec{w} \cdot \vec{v} > \epsilon, |\vec{v}_{\perp}| < \delta\} \subset \mathcal{Q}_{\mathcal{D}}(M, t). \quad (2.8)$$

In view of Minkowski's theorem, the symmetric, convex set $\{(u, \vec{v}) \in \mathbb{R}^{d+1} \mid |u| < \epsilon, |\vec{v}_{\perp}| < \delta\}$ contains a non-zero element of $\mathbb{Z}^{d+1}M$. By construction, there is no non-zero lattice point in $\mathbb{Z}^{d+1}M$ within ϵ -distance to the origin, and furthermore $\mathbb{Z}^{d+1}M$ is symmetric under reflection at the origin. We can therefore conclude that the set in (2.8), and therefore also $\mathcal{Q}_{\mathcal{D}}(M, t)$, is non-empty. Hence, by the uniform discreteness of $\mathbb{Z}^{d+1}M$, the minimum value in the definition of $F_{\mathcal{D}}$ exists.

Finally, note that $F_{\mathcal{D}}(\gamma M, t) = F_{\mathcal{D}}(M, t)$ for $\gamma \in \Gamma$, and hence F is well defined on $\Gamma \backslash G \times (0, 1)$. ■

Note that for $R \in \text{SO}(d)$, we have

$$F_{\mathcal{D}R} \left(M \begin{pmatrix} 1 & 0 \\ 0 & R \end{pmatrix}, t \right) = F_{\mathcal{D}}(M, t). \quad (2.9)$$

Let us define

$$\mathcal{Q}_{\mathcal{D}}(M) = \bigcup_{t \in (0,1)} \mathcal{Q}_{\mathcal{D}}(M, t) = \{(u, \vec{v}) \in \mathbb{Z}^{d+1}M \mid |u| < 1, \vec{v} \in \mathbb{R}_{>0}\mathcal{D}\}. \quad (2.10)$$

The set

$$\mathcal{M}_{\mathcal{D}}(M) = \{|\vec{v}| \mid (u, \vec{v}) \in \mathcal{Q}_{\mathcal{D}}(M)\} \tag{2.11}$$

contains the set of values taken by the function $t \mapsto F_{\mathcal{D}}(M, t)$. It is a locally finite subset of $\mathbb{R}_{>0}$, that is, there are at most finitely many points in any bounded interval. It follows that for fixed M , the function $t \mapsto F_{\mathcal{D}}(M, t)$ is piecewise constant.

We denote by

$$\mathcal{G}_{\mathcal{D}}(M) = |\{F_{\mathcal{D}}(M, t) \mid 0 < t < 1\}| \tag{2.12}$$

the number of distinct values attained by the function $t \mapsto F_{\mathcal{D}}(M, t)$. For $N > 0$, let

$$\mathcal{G}_{\mathcal{D},N}(M) = |\{F_{\mathcal{D}}(M, \frac{n}{N_+}) \mid 1 \leq n \leq N\}|. \tag{2.13}$$

We have $\mathcal{G}_{\mathcal{D},N}(M) \leq \mathcal{G}_{\mathcal{D}}(M)$, and so in particular

$$g_N(\mathcal{D}) = \mathcal{G}_{\mathcal{D},N}(A_{N_+}(\vec{\alpha})) \leq \mathcal{G}_{\mathcal{D}}(A_{N_+}(\vec{\alpha})). \tag{2.14}$$

3 Geometric Lemmas in Dimension $d = 2$

To fix notation for our subsequent discussion, we define a representative set of vectors $(u_i, \vec{v}_i) \in \mathcal{Q}_{\mathcal{D}}(M)$, for which the lengths $|\vec{v}_i|$ are distinct, and each of which corresponds to an element in the set

$$\mathcal{F}_{\mathcal{D}}(M) = \{F_{\mathcal{D}}(M, t) \mid 0 < t < 1\}. \tag{3.1}$$

To be specific, for each $M \in \Gamma \backslash G$ we fix vectors $(u_1, \vec{v}_1), \dots, (u_K, \vec{v}_K) \in \mathcal{Q}_{\mathcal{D}}(M)$ with $K = \mathcal{G}_{\mathcal{D}}(M)$, so that the following conditions hold:

- (V1) $0 < |\vec{v}_1| < |\vec{v}_2| < \dots < |\vec{v}_K|$.
- (V2) For each $\delta \in \mathcal{F}_{\mathcal{D}}(M)$, there exists an $1 \leq i \leq K$ such that $\delta = |\vec{v}_i|$.
- (V3) For each $1 \leq i \leq K$, there exists a $t \in (0, 1)$ such that $(u_i, \vec{v}_i) \in \mathcal{Q}_{\mathcal{D}}(M, t)$ and $|\vec{v}_i| = F_{\mathcal{D}}(M, t)$.

Let us now focus on the case $d = 2$. In the following, we identify the unit circle \mathbb{S}_1^1 with the interval $[-\pi, \pi) \bmod 2\pi$, so that 0 corresponds to direction $(1, 0) \in \mathbb{S}_1^1$. In view of the rotation invariance (2.9), we may assume without loss of generality that $\mathcal{D} \subseteq \mathbb{S}_1^1$ is centered at $\theta = 0$, that is, $\mathcal{D} = [-\tau/2, \tau/2)$, which we still view as a subset of \mathbb{S}_1^1 (not \mathbb{R}).

Our proof of Theorem 4, or rather the proofs of the more general Theorems 7 and 8 below, will be divided into three main cases, which together cover all possible angles $\tau \in (\pi, 2\pi]$ described in (1.11). In each of these cases, we will partition \mathcal{D} into subsets, consisting of a *symmetric* set $S \subset \mathcal{D}$ (symmetric with respect to the rotation $\theta \mapsto \theta + \pi \pmod{2\pi}$) and up to three *asymmetric* subsets. For notational convenience, let us set

$$\psi = 2\pi - \tau \in [0, \pi) \quad \text{and} \quad \phi = \tau - \pi \in (0, \pi]. \quad (3.2)$$

First, we specify our definitions of the asymmetric subsets in each of the three main cases.

Case (C1): if $5\pi/3 \leq \tau \leq 2\pi$, then we define one asymmetric subset $\mathcal{A}_0 \subset \mathcal{D}$ by

$$\mathcal{A}_0 = [-\psi/2, \psi/2). \quad (3.3)$$

(Note that this is the empty set if $\tau = 2\pi$.)

Case (C2): if $4\pi/3 \leq \tau < 5\pi/3$, then we define two asymmetric subsets \mathcal{A}_{-1} and \mathcal{A}_1 by

$$\mathcal{A}_{-1} = [-\psi/2, 0), \quad \mathcal{A}_1 = [0, \psi/2). \quad (3.4)$$

Case (C3): if $\pi < \tau < 4\pi/3$, then we define three asymmetric subsets \mathcal{A}_{-1} , \mathcal{A}_0 , and \mathcal{A}_1 by

$$\mathcal{A}_{-1} = [-\psi/2, -\pi/6), \quad \mathcal{A}_0 = [-\pi/6, \pi/6), \quad \mathcal{A}_1 = [\pi/6, \psi/2). \quad (3.5)$$

In all three cases, we define the symmetric subset S by

$$S = [-\tau/2, -\psi/2) \cup [\psi/2, \tau/2). \quad (3.6)$$

It is clear that S is the largest symmetric subset of \mathcal{D} , that \mathcal{D} is the disjoint union of S and its asymmetric subsets, and that each asymmetric subset is a half-open interval of length at most $\pi/3$.

Now we will establish several propositions that will help streamline the proofs of Theorems 7 and 8 below (which in turn will imply Theorem 4). First, we will need the following elementary fact which, for future reference, we state for arbitrary dimension $d \geq 2$.

Proposition 2. If $d \geq 2$ and if the angle between two non-zero vectors $\vec{w}_1, \vec{w}_2 \in \mathbb{R}^d$ is less than $\pi/3$, then

$$|\vec{w}_1 - \vec{w}_2| < \max\{|\vec{w}_1|, |\vec{w}_2|\}. \quad (3.7)$$

Furthermore, this inequality also holds if the angle between $\vec{w}_1, \vec{w}_2 \in \mathbb{R}^d$ is equal to $\pi/3$, as long as $|\vec{w}_1| \neq |\vec{w}_2|$.

Proof. For the 1st part of the proposition, suppose without loss of generality that $|\vec{w}_1| \leq |\vec{w}_2|$. Then the vectors $\vec{w}_1/|\vec{w}_2|$ and $\vec{w}_2/|\vec{w}_2|$ lie in the closed unit ball and are separated by an angle less than $\pi/3$. Therefore,

$$\left| \frac{\vec{w}_1}{|\vec{w}_2|} - \frac{\vec{w}_2}{|\vec{w}_2|} \right| < 1, \tag{3.8}$$

and the result follows. Furthermore, under the assumptions of the 2nd part of the proposition, we draw the same conclusion. ■

Next we will prove several propositions that place various restrictions on the integer $K = \mathcal{G}_{\mathcal{D}}(M)$ defined at the start of this section; recall (V1)–(V3).

Proposition 3. If for some integer $1 \leq i \leq K$, we have that $u_i \in (-1/2, 1/2)$ and $\vec{v}_i \in \mathbb{R}_{>0}\mathcal{S}$, then we must have that $i = K$.

Proof. Suppose first that $u_i \in [0, 1/2)$. Then for any $0 < t < 1 - u_i$, we have that $(u_i, \vec{v}_i) \in \mathcal{Q}_{\mathcal{D}}(M, t)$ and thus $|\vec{v}_i| \geq F_{\mathcal{D}}(M, t)$. By the symmetry of \mathcal{S} , we have $(-u_i, -\vec{v}_i) \in \mathcal{Q}_{\mathcal{D}}(M)$. Thus, for any $u_i < t < 1$, we have that $(-u_i, -\vec{v}_i) \in \mathcal{Q}_{\mathcal{D}}(M, t)$ and thus $|\vec{v}_i| \geq F_{\mathcal{D}}(M, t)$. Since $u_i < 1/2$, we conclude that $|\vec{v}_i| \geq F_{\mathcal{D}}(M, t)$ for all $0 < t < 1$, which proves $i = K$. The case $u_i \in (-1/2, 0]$ follows from the same argument. ■

Proposition 4. If for some i and j with $1 \leq i, j \leq K$, we have that $u_i \in (-1/2, 0]$ and $u_j \in [0, 1/2)$, then $i = K$ or $j = K$.

Proof. Under the hypotheses of the proposition, we have $|\vec{v}_i| \geq F_{\mathcal{D}}(M, t)$ for $-u_i < t < 1$ and $|\vec{v}_j| \geq F_{\mathcal{D}}(M, t)$ for $0 < t < 1 - u_j$. This covers all possible values of $t \in (0, 1)$ and shows that i or j must equal K . ■

Proposition 5. If $1 \leq i, j \leq K$ and $u_i = u_j$, then $i = j$.

Proof. Suppose by way of contradiction that $i \neq j$, and without loss of generality that $i < j$. Then for any $t \in (0, 1)$ satisfying $-t < u_i = u_j \leq 1 - t$, we would have by (V1) that

$$F_{\mathcal{D}}(M, t) \leq |\vec{v}_i| < |\vec{v}_j|. \tag{3.9}$$

However, this contradicts condition (V3), so we must have that $i = j$. ■

Proposition 6. Let $1 \leq i \leq K$ and $(u, \vec{v}) \in \mathcal{Q}_{\mathcal{D}}(M)$. If

$$-1 < u_i \leq u \leq 0 \quad \text{or} \quad 0 \leq u \leq u_i < 1 \quad (3.10)$$

then $|\vec{v}_i| \leq |\vec{v}|$.

Proof. Suppose that $0 \leq u \leq u_i < 1$; the other case follows by symmetry. By (V3), there exist $t_i \in (0, 1 - u_i)$ such that $F_{\mathcal{D}}(M, t_i) = |\vec{v}_i|$. Furthermore, $F_{\mathcal{D}}(M, t) \leq |\vec{v}|$ for all $t \in (0, 1 - u)$. Thus, taking $t = t_i \in (0, 1 - u)$, we have $|\vec{v}_i| \leq |\vec{v}|$. ■

Proposition 7. Let $1 \leq i, j \leq K$. If

$$-1 < u_i < u_j \leq 0 \quad \text{or} \quad 0 \leq u_j < u_i < 1, \quad (3.11)$$

then $|\vec{v}_i| < |\vec{v}_j|$ and $i < j$.

Proof. In view of (V1), this is a direct consequence of Proposition 6. ■

Proposition 8. Let $\tau \geq \pi$, $1 \leq j \leq K$, and $(u, \vec{v}) \in \mathcal{Q}_{\mathcal{D}}(M)$ such that $\vec{v}_j \neq \vec{v}$ and $0 < |\vec{v}| \leq |\vec{v}_j|$. Suppose the angle between the vectors \vec{v}_j and \vec{v} is less than $\pi/3$. If

$$-1 < u \leq u_j \leq -1/2 \quad \text{or} \quad 1/2 \leq u_j \leq u < 1, \quad (3.12)$$

then $j = K$.

Proof. We consider the case $1/2 \leq u_j \leq u < 1$; the proof for the alternative follows from the same argument by symmetry. By the assumption on the angle between the vectors \vec{v}_j and \vec{v} , we have by Proposition 2 that $|\vec{v}_j - \vec{v}| < |\vec{v}_j|$. Since $\vec{v}_j \neq \vec{v}$ and $\tau \geq \pi$, we have that at least one of $\vec{v}_j - \vec{v}$, $\vec{v} - \vec{v}_j$ is in $\mathbb{R}_{>0}\mathcal{D}$.

First, suppose that $\vec{v} - \vec{v}_j \in \mathbb{R}_{>0}\mathcal{D}$. Then, since

$$0 \leq u - u_j < 1/2 \leq u_j < 1,$$

we have $(u - u_j, \vec{v} - \vec{v}_j) \in \mathcal{Q}_{\mathcal{D}}(M)$ and by Proposition 6 that $|\vec{v} - \vec{v}_j| \geq |\vec{v}_j|$. This is a contradiction, so we conclude that $\vec{v}_j - \vec{v} \notin \mathbb{R}_{>0}\mathcal{D}$.

The only other possibility is that $\vec{v}_j - \vec{v} \in \mathbb{R}_{>0}\mathcal{D}$. In this case, $(u_j - u, \vec{v}_j - \vec{v}) \in \mathcal{Q}_{\mathcal{D}}(M)$,

$$u_j - u \leq 0 \quad \text{and} \quad u - u_j < 1 - u_j. \quad (3.13)$$

It follows from this that, for $u - u_j < t < 1$, we have $F_{\mathcal{D}}(M, t) \leq |\vec{v} - \vec{v}_j| < |\vec{v}_j|$ and for $0 < t < 1 - u_j$ (which in particular holds for all t with $0 < t \leq u - u_j$), we have $F_{\mathcal{D}}(M, t) \leq |\vec{v}_j|$. Therefore, $j = K$. ■

Proposition 9. Let $\tau \geq \pi$ and $1 \leq i, j \leq K$. Suppose the angle between the vectors \vec{v}_i and \vec{v}_j is less than $\pi/3$. If

$$-1 < u_i < u_j \leq -1/2 \quad \text{or} \quad 1/2 \leq u_j < u_i < 1, \tag{3.14}$$

then $j = K$.

Proof. This is a direct corollary of Proposition 8 (take $u = u_i$). ■

Proposition 10. Let $\tau \geq \pi$ and $1 \leq i, j \leq K$. Suppose the angle between the vectors \vec{v}_i and \vec{v}_j is less than $\pi/3$. If

$$-1/2 < u_i < u_j \leq 0 \quad \text{or} \quad 0 \leq u_j < u_i < 1/2, \tag{3.15}$$

then $\vec{v}_j - \vec{v}_i \notin \mathbb{R}_{>0}\mathcal{D}$ and

$$|\vec{v}_i| \leq |\vec{v}_i - \vec{v}_j| < |\vec{v}_j|. \tag{3.16}$$

Proof. We assume $0 \leq u_j < u_i < 1/2$; the other case follows by symmetry. It follows from Proposition 7 that $i < j$ and $|\vec{v}_i| < |\vec{v}_j|$, and it follows from Proposition 2 that $|\vec{v}_i - \vec{v}_j| < |\vec{v}_j|$.

Suppose, contrary to what we are trying to prove, that $\vec{v}_j - \vec{v}_i \in \mathbb{R}_{>0}\mathcal{D}$. Then, since $0 < u_i - u_j < 1/2$, we have $(u_j - u_i, \vec{v}_j - \vec{v}_i) \in \mathcal{Q}_{\mathcal{D}}(M)$ and hence for $u_i - u_j < t < 1$ we have $F_{\mathcal{D}}(M, t) \leq |\vec{v}_i - \vec{v}_j| < |\vec{v}_j|$. Furthermore, for $0 < t < 1 - u_i$, we have $F_{\mathcal{D}}(M, t) \leq |\vec{v}_i| < |\vec{v}_j|$. Now $u_i - u_j < 1 - u_i$, so $F_{\mathcal{D}}(M, t) < |\vec{v}_j|$ for all $t \in (0, 1)$. But by (V3) there is $t \in (0, 1)$ such that $F_{\mathcal{D}}(M, t) = |\vec{v}_j|$. This is a contradiction, so we conclude that $\vec{v}_j - \vec{v}_i \notin \mathbb{R}_{>0}\mathcal{D}$.

It remains to show that $|\vec{v}_i| \leq |\vec{v}_i - \vec{v}_j|$. Since $\vec{v}_j - \vec{v}_i \notin \mathbb{R}_{>0}\mathcal{D}$ and $\tau \geq \pi$, we have $\vec{v}_i - \vec{v}_j \in \mathbb{R}_{>0}\mathcal{D}$. Then $(u_i - u_j, \vec{v}_i - \vec{v}_j) \in \mathcal{Q}_{\mathcal{D}}(M)$ with $0 < u_i - u_j < 1/2$. Thus, for $0 < t < 1 - (u_i - u_j)$, we have $F_{\mathcal{D}}(M, t) \leq |\vec{v}_i - \vec{v}_j|$. Note that by (V3) there exists a $t_i \in (0, 1 - u_i)$ such that $F_{\mathcal{D}}(M, t_i) = |v_i|$. Now $1 - u_i \leq 1 - (u_i - u_j)$ and so $F_{\mathcal{D}}(M, t_i) = |v_i| \leq |\vec{v}_i - \vec{v}_j|$ as needed. ■

The previous proposition will be used in the proof of Theorem 7 in conjunction with the following two elementary geometric propositions.

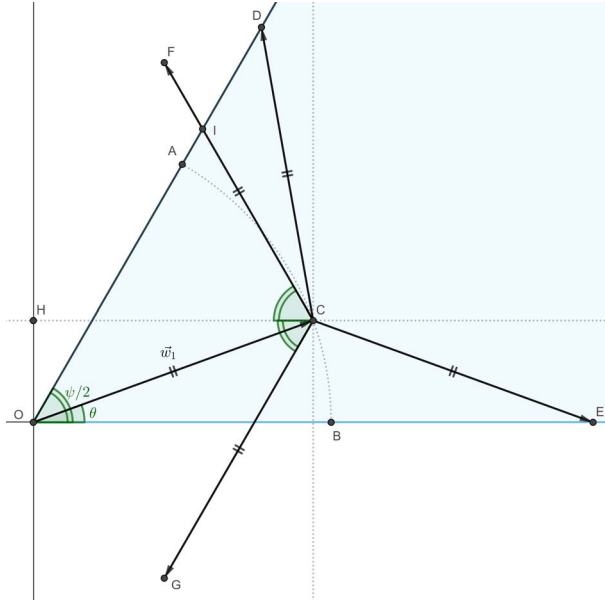


Fig. 4. Diagram of \mathcal{A}_1 in case (C2).

Proposition 11. Suppose that

- we are in case (C1) or (C3) and $\vec{w}_1, \vec{w}_2 \in \mathbb{R}_{>0}\mathcal{A}_0$, or
- we are in case (C2) and $\vec{w}_1, \vec{w}_2 \in \mathbb{R}_{>0}\mathcal{A}_{-1}$, or
- we are in case (C2) and $\vec{w}_1, \vec{w}_2 \in \mathbb{R}_{>0}\mathcal{A}_1$.

If

$$|\vec{w}_1| \leq |\vec{w}_1 - \vec{w}_2| < |\vec{w}_2|, \tag{3.17}$$

then $\vec{w}_2 - \vec{w}_1 \in \mathbb{R}_{>0}\mathcal{D}$.

Proof. First suppose that we are in case (C2), that \vec{w}_1 and \vec{w}_2 point in direction \mathcal{A}_1 , and that (3.17) holds. We will argue using Figure 4.

In the figure, angle AOB measures $\psi/2$ and sweeps out \mathcal{A}_1 , and the line through H and C is parallel to the x-axis. The vector \vec{w}_1 is shown, and the angles HCF and HCG also measure $\psi/2$. Also, we have labeled the angle between \vec{w}_1 and the positive real axis as θ (not to be confused with other uses of θ outside the scope of this proof).

By condition (3.17), vector \vec{w}_2 has to lie outside of both the circle of radius $|\vec{w}_1|$ centered at O, and the circle of radius $|\vec{w}_1|$ centered at C. The circle of radius

$|\vec{w}_1|$ centered at C intersects the boundary of $\mathbb{R}_{>0}\mathcal{A}_1$ at the three points D, O, and E, and the points F and G have also been chosen so that they lie on this circle. We will show (as indicated in the figure) that F and G lie outside of $\mathbb{R}_{>0}\mathcal{A}_1$. This will complete the proof in this sub-case since, if $\vec{w}_2 - \vec{w}_1$ were not in $\mathbb{R}_{>0}\mathcal{D}$ then \vec{w}_2 would have to lie in the cone swept out by angle FCG, above the ray originating from C and passing through G, and on or below the ray originating from C and passing through F. This, together with the condition that it lies outside of the circle of radius $|\vec{w}_1|$ centered at C, would force it to lie outside of $\mathbb{R}_{>0}\mathcal{A}_1$, which is contradictory to our hypotheses.

It is clear from the fact the $\psi/2 \leq \pi/3$ that G lies below the x-axis, so it cannot be in $\mathbb{R}_{>0}\mathcal{A}_1$ (in fact we only need $\psi/2 < \pi/2$ for this to hold). To see why F is not in $\mathbb{R}_{>0}\mathcal{A}_1$, first note that angle OCH has measure θ , from which it follows that angle CIO has measure $\pi - \psi$ (to avoid circular reasoning, the point I is defined as the intersection of the line through C and F with the line through O and A). On the other hand, angle CDO has measure $\psi/2 - \theta$ and, since $3\psi/2 \leq \pi$, we have that

$$\psi/2 - \theta \leq \pi - \psi. \tag{3.18}$$

This implies that the point F lies on or to the left of the line through O and D; therefore, it is not in $\mathbb{R}_{>0}\mathcal{A}_1$. The proof for case (C2) when \vec{w}_1 and \vec{w}_2 point in direction \mathcal{A}_{-1} follows by symmetry.

Next suppose that we are in case (C1), that \vec{w}_1 and \vec{w}_2 point in direction \mathcal{A}_0 , and that (3.17) holds. Here the proof is similar, and we will argue using Figure 5. Once again, let θ denote the angle between \vec{w}_1 and the positive real axis.

First, assume that $0 \leq \theta < \psi/2$. Since $\psi/2 \leq \pi/6$, the argument given above implies again that F lies outside of $\mathbb{R}_{>0}\mathcal{A}_0$. Angle HCO has measure θ ; therefore, angle OCI has measure $\psi/2 - \theta$, and it follows that angle CIO has measure $\pi - \psi$. Since triangle OCE is isosceles, angle CEO has measure $\psi/2 + \theta$, and since

$$\psi/2 + \theta < \pi - \psi, \tag{3.19}$$

this implies that G lies outside of $\mathbb{R}_{>0}\mathcal{A}_0$. This argument actually works for all θ and ψ satisfying $0 \leq \theta < \psi/2 \leq \pi/4$, and a symmetrical argument applies when $-\pi/4 \leq -\psi/2 < \theta < 0$. The proof for case (C3), when \vec{w}_1 and \vec{w}_2 point in direction \mathcal{A}_0 , follows from the same argument. ■

Proposition 12. Suppose that we are in case (C3) and that $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_n$ are any vectors which all point in direction \mathcal{A}_{-1} , or which all point in direction \mathcal{A}_1 . If, for each

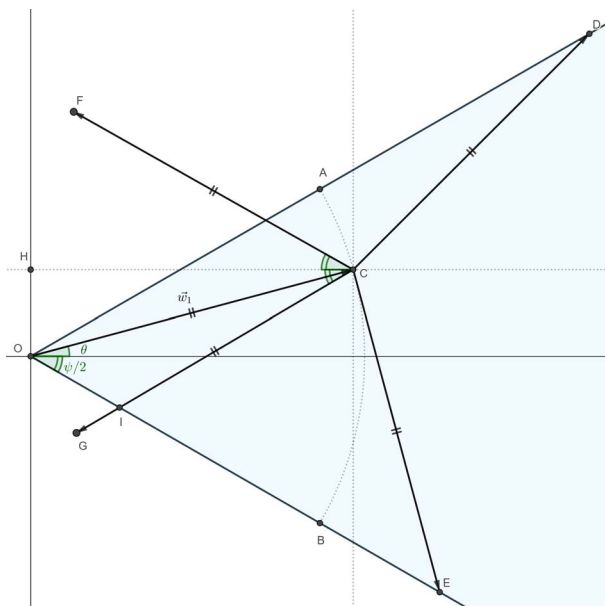


Fig. 5. Diagram of \mathcal{A}_0 in case (C1).

$1 \leq i \leq n - 1$, we have that $\vec{w}_{i+1} - \vec{w}_i \notin \mathbb{R}_{>0}\mathcal{D}$ and that

$$|\vec{w}_i| \leq |\vec{w}_i - \vec{w}_{i+1}| < |\vec{w}_{i+1}|, \tag{3.20}$$

then we must have that

$$n \leq 1 + \left\lfloor \frac{\sin(\tau/2 + \pi/6)}{\sin(\tau - \pi)} \right\rfloor. \tag{3.21}$$

Proof. Suppose $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_n$ point in direction \mathcal{A}_1 and consider Figure 6.

In the figure, angle AOB measures $\psi/2 - \pi/6 < \pi/3$ and sweeps out \mathcal{A}_1 , the vector \vec{w}_1 has initial point O and terminal point C, and the line through G and C is parallel to the x-axis. For each $1 \leq i \leq n - 1$, we have that $\vec{w}_{i+1} - \vec{w}_i \notin \mathbb{R}_{>0}\mathcal{D}$ and

$$|\vec{w}_{i+1} - \vec{w}_i| \geq |\vec{w}_1|, \tag{3.22}$$

so it follows that

$$n - 1 \leq \left\lfloor \frac{|\mathcal{CF}|}{|\vec{w}_1|} \right\rfloor. \tag{3.23}$$

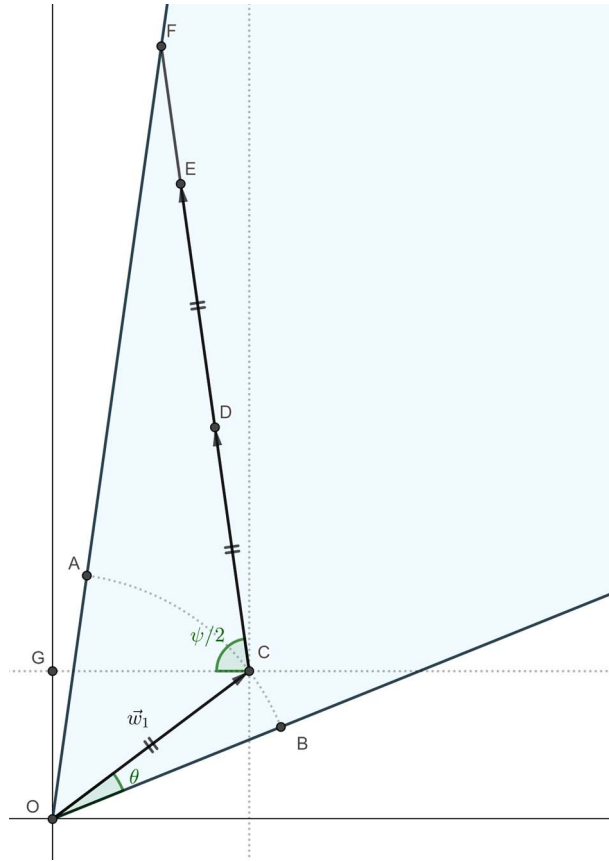


Fig. 6. Diagram of \mathcal{A}_1 in case (C3).

Line segment CF is longest when $\theta = 0$, which (using the law of sines) gives the bound

$$|CF| \leq \frac{|\vec{w}_1| \sin(\psi/2 - \pi/6)}{\sin(\pi - \psi)}. \tag{3.24}$$

Substituting $\psi = 2\pi - \tau$ gives

$$\frac{|CF|}{|\vec{w}_1|} \leq \frac{\sin(\tau/2 + \pi/6)}{\sin(\tau - \pi)}. \tag{3.25}$$

Combining this with (3.23) completes the proof of the proposition. ■

Finally, to obtain the bounds reported in some of the cases of Theorem 4, we will need to gather together a few more facts. The following proposition is an extension of

Proposition 6, for the special case when one of the vectors in the hypotheses lies in the direction determined by the symmetric set \mathcal{S} .

Proposition 13. Let $1 \leq i, j \leq K$, $i \neq j$, and let $\vec{v}_j \in \mathbb{R}_{>0}\mathcal{S}$. If

$$-1 < u_i \leq -u_j \leq 0 \quad \text{or} \quad 0 \leq -u_j \leq u_i < 1, \quad (3.26)$$

then $|\vec{v}_i| < |\vec{v}_j|$ and $i < j$.

Proof. The vector $-\vec{v}_j$ is in \mathcal{S} , and hence $(-u_j, -\vec{v}_j) \in \mathcal{Q}_{\mathcal{D}}(M)$. Proposition 6 then yields the statement. ■

Proposition 14. Let $1 \leq i, j \leq K$, and let $\vec{v}_j \in \mathbb{R}_{>0}\mathcal{S}$. Assume the angle between \vec{v}_i and $-\vec{v}_j$ is less than $\pi/3$. If

$$-1 < u_i \leq -u_j \leq -1/2 \quad \text{or} \quad 1/2 \leq -u_j \leq u_i < 1, \quad (3.27)$$

then $j = K$.

Proof. The proof is similar to that of Proposition 8, which would directly apply if we had assumed $\vec{v}_i \in \mathbb{R}_{>0}\mathcal{S}$ rather than $\vec{v}_j \in \mathbb{R}_{>0}\mathcal{S}$.

The assumption on the angle implies $i \neq j$. We consider the case $1/2 \leq -u_j \leq u_i < 1$; the proof for the alternative follows from the same argument by symmetry. By the assumption on the angle between the vectors \vec{v}_i and $-\vec{v}_j$, we have by Proposition 2 that $|\vec{v}_i + \vec{v}_j| < |\vec{v}_j|$. Since $\vec{v}_i \neq \vec{v}_j$ and $\tau \geq \pi$, we have that at least one of $\pm(\vec{v}_i + \vec{v}_j)$ is in $\mathbb{R}_{>0}\mathcal{D}$. Suppose $\vec{v}_i + \vec{v}_j \in \mathbb{R}_{>0}\mathcal{D}$.

Then, since $(-u_j, \vec{v}_j) \in \mathcal{Q}_{\mathcal{D}}(M)$ and

$$0 \leq u_i + u_j < 1/2 \leq -u_j < 1,$$

we have $(u_i + u_j, \vec{v}_i + \vec{v}_j) \in \mathcal{Q}_{\mathcal{D}}(M)$ and by Proposition 6 that $|\vec{v}_i + \vec{v}_j| \geq |\vec{v}_j|$, a contradiction. Therefore, $\vec{v}_i + \vec{v}_j \notin \mathbb{R}_{>0}\mathcal{D}$ and we must have $-(\vec{v}_i + \vec{v}_j) \in \mathbb{R}_{>0}\mathcal{D}$. This means $-(u_i + u_j, \vec{v}_i + \vec{v}_j) \in \mathcal{Q}_{\mathcal{D}}(M)$ and

$$0 \leq u_i + u_j < 1 + u_j. \quad (3.28)$$

It follows from this that, for all t with $u_i + u_j < t < 1$, we have $F_{\mathcal{D}}(M, t) \leq |\vec{v}_i + \vec{v}_j| < |\vec{v}_j|$ and for $0 < t < 1 + u_j$ (which in particular holds for all t with $0 < t \leq u_i + u_j$), we have $F_{\mathcal{D}}(M, t) \leq |\vec{v}_j|$. Therefore, $j = K$. ■

The previous proposition allows us to deduce the following simple and useful result. Recall that $\phi = \tau - \pi$, so that $\tau = \psi + 2\phi$.

Proposition 15. Let S_2 denote the number of integers i with $1 \leq i \leq K$, $\vec{v}_i \in \mathbb{R}_{>0}\mathcal{S}$, and $u_i \in (-1, -1/2] \cup [1/2, 1)$. Then

$$S_2 \leq \begin{cases} 1 + 2 \left\lceil \frac{\phi}{\pi/3} \right\rceil & \text{if } \vec{v}_K \in \mathbb{R}_{>0}\mathcal{S} \text{ and } u_K \in (-1, -1/2] \cup [1/2, 1), \\ 2 \left\lceil \frac{\phi}{\pi/3} \right\rceil & \text{otherwise.} \end{cases} \tag{3.29}$$

Proof. The quantity ϕ is the angle swept out by the part of \mathcal{S} , which lies above the x -axis. The maximum number of vectors that can be placed in this region, so that the angles between any two vectors is at least $\pi/3$, is $\lceil \phi/(\pi/3) \rceil$. The upper bound in (3.29) therefore follows from combining the results of Propositions 9 and 14. ■

4 Explicit Upper Bounds in Dimension $d = 2$, Part 1

Throughout this section, we take $d = 2$. In view of (2.14), the following statement directly implies all cases of Theorem 4, except the case when $\mathcal{D} = \mathbb{S}_1^1$ (which is handled in the next section).

Theorem 7. Let $d = 2$, and assume $\mathcal{D} \subseteq \mathbb{S}_1^1$ is a half-open interval of arclength $\tau > \pi$. Then for any $M \in \text{SL}(3, \mathbb{R})$ we have that

$$\mathcal{G}_{\mathcal{D}}(M) \leq \begin{cases} 9 & \text{if } 5\pi/3 < \tau < 2\pi, \\ 8 & \text{if } \tau = 5\pi/3, \\ 9 & \text{if } 4\pi/3 < \tau < 5\pi/3, \\ 8 & \text{if } \tau = 4\pi/3, \\ 12 + 2 \left\lceil \frac{\sin(\tau/2 + \pi/6)}{\sin(\tau - \pi)} \right\rceil & \text{if } \pi < \tau < 4\pi/3. \end{cases} \tag{4.1}$$

The remainder of this section is dedicated to the proof of this theorem. For the proof, we will apply the propositions from the previous section to each of the five cases described in (4.1). To summarize the main points of our arguments,

- (i) Let S_1 denote the number of $1 \leq i \leq K$ with $u_i \in (-1/2, 1/2)$ and $\vec{v}_i \in \mathbb{R}_{>0}\mathcal{S}$. Proposition 3 guarantees that $S_1 \leq 1$ and that if $S_1 = 1$ then the corresponding value of i equals K .
- (ii) Let S_2 denote the number of $1 \leq i \leq K$ with $u_i \in (-1, -1/2] \cup [1/2, 1)$ and $\vec{v}_i \in \mathbb{R}_{>0}\mathcal{S}$. Proposition 15 gives an upper bound for S_2 .
- (iii) Let A_1 denote the number of $1 \leq i \leq K$ with $u_i \in (-1/2, 1/2)$ and with \vec{v}_i in direction of any asymmetric subset. Propositions 4 and 10–12 give upper bounds for $A_1 + S_1$.
- (iv) Let A_2 denote the number of $1 \leq i \leq K$ with $u_i \in (-1, -1/2] \cup [1/2, 1)$ and with \vec{v}_i in direction of any asymmetric subset. Propositions 5–9 give upper bounds for $A_2 + S_2$.

In all cases, we have that $\mathcal{G}_{\mathcal{D}}(M) = K = S_1 + A_1 + S_2 + A_2$. In what follows, recall that $\psi = 2\pi - \tau$ and $\phi = \tau - \pi$.

Case (C1), $\tau = 2\pi$: this is actually not one of the cases considered in Theorem 7, but we include it as a demonstration of the proof technique and to provide an easy argument that $\mathcal{G}_{\mathcal{D}}(M) \leq 6$. This bound will be improved in the next section, by a slightly more complicated argument, to show that $\mathcal{G}_{\mathcal{D}}(M) \leq 5$.

In this case $\psi = 0$ and $\phi = \pi$, so it is clear that $A_1 = A_2 = 0$. We claim that $S_2 \leq 5$. Suppose by way of contradiction that $S_2 \geq 6$. Since $\tau = 2\pi$, we may assume without loss of generality that the vectors (u_i, \vec{v}_i) have been chosen so that $u_i \in [0, 1)$ for each i . Then we can find $1 \leq i < j \leq K$ with $1/2 \leq u_i, u_j < 1$, and for which the angle between \vec{v}_i and \vec{v}_j is less than or equal to $\pi/3$. By the 2nd part of Proposition 2, we then have that

$$|\vec{v}_i - \vec{v}_j| < |\vec{v}_j|. \quad (4.2)$$

However, since $|u_i - u_j| < 1/2$ and $\vec{v}_i - \vec{v}_j \in \mathbb{R}_{>0}\mathcal{S}$, this implies that

$$F_{\mathcal{D}}(M, t) \leq |\vec{v}_i - \vec{v}_j| < |\vec{v}_j|, \quad (4.3)$$

for all $t \in (0, 1)$, which contradicts assumption (V3). Therefore, $S_2 \leq 5$. Since $S_1 \leq 1$, this gives the bound $\mathcal{G}_{\mathcal{D}}(M) \leq 6$.

Case (C1), $5\pi/3 < \tau < 2\pi$: in this case $0 < \psi < \pi/3$ and $2\pi/3 < \phi < \pi$. There is only one asymmetric subset, $\mathcal{A}_0 = [-\psi/2, \psi/2)$.

A. Assume $S_1 = 1$. Then by Proposition 3 we must have that

$$u_K \in (-1/2, 1/2). \quad (4.4)$$

Proposition 4 implies that we cannot have i and j with $1 \leq i, j < K$, $u_i \in (-1/2, 0]$, and $u_j \in [0, 1/2)$. Therefore, by Propositions 10 and 11, we have that $A_1 \leq 1$.

Since $\lceil \frac{\phi}{\pi/3} \rceil = 3$ and (4.4) holds, Proposition 15 implies that $S_2 \leq 6$. We claim that, in this sub-case, $S_2 + A_2 \leq 7$. It is clear from Proposition 9 that, since (4.4) holds, we must have that $A_2 \leq 2$ and that if $A_2 = 2$ then one element has its 1st component in $(-1, -1/2]$ and the other in $[1/2, 1)$. In order to establish our claim, we only need to consider what happens when $S_2 \geq 5$. If $S_2 \geq 5$, then there must be at least three values of $1 \leq i < K$ with $u_i \in (-1, -1/2]$ and $\vec{v}_i \in \mathbb{R}_{>0}\mathcal{S}$ or at least three values with $u_i \in [1/2, 1)$ and $\vec{v}_i \in \mathbb{R}_{>0}\mathcal{S}$ (or possibly both, if $S_2 = 6$). The argument in both cases is the same, so suppose without loss of generality that the former condition holds. Then, there are at least two values $1 \leq i < j < K$ with $u_i, u_j \in (-1, -1/2]$, $\vec{v}_i, \vec{v}_j \in \mathbb{R}_{>0}\mathcal{S}$, and with \vec{v}_i and \vec{v}_j either both above or both below the x -axis. If there were also a value of $1 \leq k \leq K$ with $u_k \in (-1, -1/2]$ and $\vec{v}_k \in \mathcal{A}_0$ then, since $\phi + \psi = \pi$, at least one pair of the vectors \vec{v}_i, \vec{v}_j , and \vec{v}_k would be separated by an angle of less than $\pi/3$. This, together with Proposition 9, would contradict (4.4); therefore, such a k cannot exist. This means $A_2 \leq 1$, and $S_2 + A_2 \leq 6 + 1 = 7$. Combining the above bounds gives that $\mathcal{G}_{\mathcal{D}}(M) \leq 1 + 1 + 6 + 1 = 9$.

- B. Assume $S_1 = 0$. Then by Propositions 10 and 11, we have that $A_1 \leq 2$. If $A_1 = 2$, then by Proposition 4 we again have that (4.4) holds. The same argument as in the previous Case A yields $S_2 + A_2 \leq 6 + 1 = 7$, and therefore $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 2 + 6 + 1 = 9$.

Assume now $A_1 \leq 1$. Since $\lceil \frac{\phi}{\pi/3} \rceil = 3$, we have by Proposition 15 that $S_2 \leq 7$, and the case $S_2 = 7$ can only arise if $\vec{v}_K \in \mathbb{R}_{>0}\mathcal{S}$ and $u_K \in (-1, -1/2] \cup [1/2, 1)$.

- (a) Assume first $S_2 = 7$. Then there exist vectors $\vec{v}_{i_1}, \dots, \vec{v}_{i_5} \in \mathbb{R}_{>0}\mathcal{S}$ with indices

$$1 \leq i_1 < i_2 < \dots < i_5 < K \tag{4.5}$$

chosen so that the vectors have the smallest possible lengths. There must be at least two of these vectors, say \vec{v}_{i_1} and \vec{v}_{i_2} , which both lie above or below the x -axis, and with corresponding u_i values either both in $(-1, -1/2]$ or both in $[1/2, 1)$. If there were also a value of $1 \leq k \leq K$ with $u_k \in (-1, -1/2]$ and $\vec{v}_k \in \mathcal{A}_0$ then, since $\phi + \psi = \pi$, at least one pair

of the vectors \vec{v}_i, \vec{v}_j , and \vec{v}_k would be separated by an angle of less than $\pi/3$. Proposition 9 implies that one of the indices has to be equal to K . Since $i, j < K$, we have $k = K$, contradicting the fact that $\vec{v}_K \in \mathbb{R}_{>0}\mathcal{S}$. We have therefore $A_2 \leq 1$, so $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 1 + 7 + 1 = 9$.

- (b) Assume now $S_2 = 5$ or 6 . In this case, we claim that $A_2 \leq 2$. To see why this is true, suppose that $A_2 \geq 3$. Then, by Proposition 9, we have $1 \leq i < j < K$ such that $\vec{v}_i, \vec{v}_j, \vec{v}_K \in \mathcal{A}_0$ and $u_i, u_j, u_K \notin (-1/2, 1/2)$ with u_i and u_j having opposite sign. Since $S_2 \geq 5$, there are at least five values of ℓ with $1 \leq \ell < K$, $\vec{v}_\ell \in \mathbb{R}_{>0}\mathcal{S}$, and $u_\ell \notin (-1/2, 1/2)$. By the same arguments as above, at least two of these would have to lie either above or below the x -axis, and have u_ℓ values both in $(-1, -1/2]$ or both in $[1/2, 1)$. This, by Proposition 9, would then imply that one of i or j , or one of these ℓ values, equals K , which is a contradiction. Therefore, $A_2 \leq 2$, $S_2 \leq 6$ and so $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 1 + 6 + 2 = 9$.
- (c) Finally, assume $S_2 \leq 4$. By Proposition 9, we have that $A_2 \leq 3$, so $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 1 + 4 + 3 = 8$.

Case (C1), $\tau = 5\pi/3$: in this case, $\psi = \pi/3$ and $\phi = 2\pi/3$, and there is only one asymmetric subset, $\mathcal{A}_0 = [-\pi/6, \pi/6)$. In this case, the argument is similar to the previous case. The key improvement is in the application of Proposition 15, since now $\lceil \frac{\phi}{\pi/3} \rceil = 2$.

- A. If $S_1 = 1$, then (4.4) holds and we conclude as in the previous Case A that $A_1 \leq 1$, $S_2 \leq 4$. Proposition 9 and (4.4) imply that $A_2 \leq 2$, and so $\mathcal{G}_{\mathcal{D}}(M) \leq 1 + 1 + 4 + 2 = 8$.
- B. If $S_1 = 0$, then $A_1 \leq 2$ as in Case B above. If $A_1 = 2$, then (4.4) holds, so $S_2 \leq 4$ by Proposition 15 and we conclude $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 2 + 4 + 2 = 8$.
- C. Now assume $A_1 \leq 1$. Proposition 15 gives $S_2 \leq 5$. If $S_2 = 5$, then, by the argument in Case B (b) above, $A_2 \leq 2$. We conclude $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 1 + 5 + 2 = 8$. If $S_2 \leq 4$, then, by the same argument as in Case B (c) above, $A_2 \leq 3$ and $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 1 + 4 + 3 = 8$.

Case (C2), $4\pi/3 < \tau < 5\pi/3$: in this case, $\pi/3 < \psi < 2\pi/3$ and $\pi/3 < \phi < 2\pi/3$. There are two asymmetric subsets, $\mathcal{A}_{-1} = [-\psi/2, 0)$ and $\mathcal{A}_1 = [0, \psi/2)$. The argument here is similar to that given above, except that now when we use Propositions 10 and 11, they must be applied to both asymmetric subsets.

- A. Assume $S_1 = 1$. Then (4.4) holds, and Propositions 10 and 11 imply that $A_1 \leq 2$ (the same argument as in Case A above, now applied to each of the two

asymmetric cones). Furthermore, $\lceil \frac{\phi}{\pi/3} \rceil = 2$ and thus Proposition 15 yields $S_2 \leq 4$.

- (a) We claim that, if $S_2 \geq 3$, then $A_2 \leq 2$. Suppose by way of contradiction that $S_2 \geq 3$, that $1 \leq i, j, k < K$, $u_i, u_j, u_k \notin (-1/2, 1/2)$, and that $\vec{v}_i, \vec{v}_j, \vec{v}_k$ are distinct vectors in direction $\mathcal{A}_{-1} \cup \mathcal{A}_1$. It could not be the case that either $u_i, u_j, u_k \in (-1, -1/2]$ or that $u_i, u_j, u_k \in [1/2, 1)$, otherwise we would have to have by Proposition 9 that i, j , or k equals K . Therefore, two of the numbers u_i, u_j , and u_k lie in one of the intervals $(-1, -1/2]$ or $[1/2, 1)$, and the other number lies in the other interval. Without loss of generality (the argument is the same in all cases), let us suppose that $u_i, u_j \in (-1, -1/2]$ and that $u_k \in [1/2, 1)$. Then there cannot be any values of $1 \leq \ell < K$ with $u_\ell \in (-1, -1/2]$ and $\vec{v}_\ell \in \mathbb{R}_{>0}\mathcal{S}$. If there were then, again since $\psi + \phi = \pi$, at least one pair of the three vectors \vec{v}_i, \vec{v}_j , and \vec{v}_ℓ would be separated by an angle of less than $\pi/3$, giving the contradiction that i, j , or ℓ equals K . This means that there are at least three values of $1 \leq \ell < K$ for which $u_\ell \in [1/2, 1)$ and $\vec{v}_\ell \in \mathbb{R}_{>0}\mathcal{S}$. At least two of these vectors lie either above or below the x -axis. Since u_k is also in $[1/2, 1)$, this means (by the same argument just given) that either u_k , or one of these u_ℓ values, is u_K . This is also a contradiction, so we conclude that $A_1 \leq 2$. Putting this all together, we have that $\mathcal{G}_{\mathcal{D}}(M) \leq 1 + 2 + 4 + 2 = 9$.
 - (b) If $S_2 = 1$ or 2 , then we must have that $A_2 \leq 3$. To see why, suppose $A_2 \geq 4$ and choose $1 \leq i_1 < i_2 < i_3 < i_4 < K$ so that $u_{i_1}, \dots, u_{i_4} \notin (-1/2, 1/2)$ and $\vec{v}_{i_1}, \dots, \vec{v}_{i_4} \notin \mathcal{S}$. By the same argument as before, we cannot have three of these u_i values in either $(-1, -1/2]$ or in $[1/2, 1)$. Therefore, two of them must be in one of these intervals, and the other two must be in the other interval. There is at least one value of $1 \leq \ell < K$ with $u_\ell \notin (-1/2, 1/2)$ and $\vec{v}_\ell \in \mathbb{R}_{>0}\mathcal{S}$, and as before, this implies that one of the vectors we have just listed is \vec{v}_K ; a contradiction with (4.4). Therefore, $A_2 \leq 3$. This shows that $\mathcal{G}_{\mathcal{D}}(M) \leq 1 + 2 + 2 + 3 = 8$.
 - (c) Assume $S_2 = 0$. By Proposition 9, we have that $A_2 \leq 5$, and so $\mathcal{G}_{\mathcal{D}}(M) \leq 1 + 2 + 0 + 5 = 8$.
- B. Assume $S_1 = 0$. Then $A_1 \leq 4$ by Propositions 10 and 11. But $A_1 = 4$ contradicts Proposition 4, so in fact $A_1 \leq 3$. If $A_1 = 3$, then by Proposition 4 we have that (4.4) holds and, for the problem of bounding $A_2 + S_2$, we are in

the same position as we just were in Case A. By exactly the same arguments, we therefore have that $A_2 + S_2 \leq 6$, and that $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 3 + 6 = 9$.

If $A_1 \leq 2$, then $S_2 \leq 5$ by Proposition 15, and we again break the problem into cases.

- (a) If $S_2 = 5$, then $\vec{v}_K \in \mathbb{R}_{>0}\mathcal{S}$, and we claim that $A_2 \leq 2$. To see why, suppose that $1 \leq u_1 < \dots < u_4 < K$ are chosen so that $\vec{v}_{i_1}, \dots, \vec{v}_{i_4}$ are in direction \mathcal{S} . Suppose that at least three of these vectors all have their u_i values either in $(-1, -1/2]$ or in $[1/2, 1)$ and without loss of generality, suppose these values lie in $(-1, -1/2]$. Then as before, since at least two of these vectors both lie either above or below the x -axis, there cannot be a value of $1 \leq j < K$ with $u_j \in (-1, -1/2]$ and with $\vec{v}_j \notin \mathbb{R}_{>0}\mathcal{S}$. Furthermore, by Proposition 9, there can be at most two values of $1 \leq j < K$ with $u_j \in [1/2, 1)$ and $\vec{v}_j \notin \mathcal{S}$, which gives $A_2 \leq 2$. The other possibility is that two of values of u_{i_1}, \dots, u_{i_4} lie in $(-1, -1/2]$, and two lie in $[1/2, 1)$. In this case, by the same arguments as above, there cannot be two values of $1 \leq j < K$ with $\vec{v}_j \notin \mathbb{R}_{>0}\mathcal{S}$ and with $u_j \in (-1, -1/2]$, and neither can there be two values with $u_j \in [1/2, 1)$. This again gives $A_2 \leq 2$. This shows that if $A_1 \leq 2$ and $S_2 = 5$ then $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 2 + 5 + 2 = 9$.
- (b) If $S_2 = 3$ or 4 , then we claim that $A_2 \leq 3$. To see why this is true, suppose by way of contradiction that $S_2 = 3$ or 4 and that $\vec{v}_{i_1}, \dots, \vec{v}_{i_4} \notin \mathbb{R}_{>0}\mathcal{S}$ are distinct vectors with corresponding u_i values all in $(-1, -1/2] \cup [1/2, 1)$. We cannot have four of these values all in $(-1, -1/2]$ or all in $[1/2, 1)$. If three of them all lie in one of these intervals, then without loss of generality let us suppose that the interval is $(-1, -1/2]$, the corresponding indices are i_2, i_3 , and i_4 and that the largest of these indices is i_4 . We must then have that $i_4 = K$. We have that u_{i_1} lies in $[1/2, 1)$, so to avoid contradiction there can be at most two values of $1 \leq \ell < K$ with $u_\ell \in [1/2, 1)$ and $\vec{v}_\ell \in \mathbb{R}_{>0}\mathcal{S}$. Then, there must be at least one value of ℓ with $u_\ell \in (-1, -1/2]$ and $\vec{v}_\ell \in \mathbb{R}_{>0}\mathcal{S}$. However, we then conclude by previous arguments that either this u_ℓ value, or one of u_{i_1} or u_{i_2} , must equal u_K . This is a contradiction. We are left with the possibility that two of the numbers u_{i_1}, \dots, u_{i_4} lie in $(-1, -1/2]$ and that the other two lie in $[1/2, 1)$. This then implies that there is at most one value of $1 \leq \ell \leq K$ with $\vec{v}_\ell \in \mathbb{R}_{>0}\mathcal{S}$ and $u_\ell \in (-1, -1/2]$, and similarly at most one with $\vec{v}_\ell \in \mathbb{R}_{>0}\mathcal{S}$ and $u_\ell \in [1/2, 1)$. This contradicts the

assumption that $S_2 = 3$ or 4 , so we conclude that in this case $A_2 \leq 3$. This gives that $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 2 + 4 + 3 = 9$.

- (c) Finally, if $S_2 \leq 2$, we use the bound $A_2 \leq 5$ and obtain $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 2 + 2 + 5 = 9$.

Case (C2), $\tau = 4\pi/3$: in this case $\psi = 2\pi/3$ and $\phi = \pi/3$, and so $\lceil \frac{\phi}{\pi/3} \rceil = 1$. There are two asymmetric cones, $\mathcal{A}_{-1} = [-\pi/3, 0)$ and $\mathcal{A}_1 = [0, \pi/3)$.

- A. Assume $S_1 = 1$. Then (4.4) holds, and as in the previous Case A we have $A_1 \leq 2$ and $S_2 \leq 2$. If $S_2 = 2$, then choose $1 \leq i, j \leq K - 1$ with $i \neq j$ and $\vec{v}_i, \vec{v}_j \in \mathbb{R}_{>0}\mathcal{S}$. If u_i and u_j both lie in $(-1, -1/2]$, then there can be at most one value of $1 \leq k \leq K - 1$ with $\vec{v}_k \notin \mathbb{R}_{>0}\mathcal{S}$ and with $u_k \in (-1, -1/2]$, and at most two values with $u_k \in [1/2, 1)$, which gives $A_2 \leq 3$. Similarly, if u_i and u_j both lie in $[1/2, 1)$. If $u_i \in (-1, -1/2]$ and $u_j \in [1/2, 1)$, or vice-versa, then there can be at most one value of $1 \leq k \leq K - 1$ with $\vec{v}_k \notin \mathbb{R}_{>0}\mathcal{S}$ and with $u_k \in (-1, -1/2]$, and also at most one value with $u_k \in [1/2, 1)$, so in this case $A_2 \leq 2$. This gives the bound $\mathcal{G}_{\mathcal{D}}(M) \leq 1 + 2 + 2 + 3 = 8$.

If $S_2 = 0$ or 1 we use the bound $A_2 \leq 4$, which follows from Proposition 9 and (4.4). Thus, $\mathcal{G}_{\mathcal{D}}(M) \leq 1 + 2 + 1 + 4 = 8$.

- B. Assume $S_1 = 0$. Then $A_1 \leq 3$. If $A_1 = 3$, then (4.4) holds and, for the problem of bounding $A_2 + S_2$, we may follow exactly the same arguments just used in Case A to obtain the bound $A_2 + S_2 \leq 5$. Therefore, $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 3 + 5 = 8$. If $A_1 \leq 2$ we use the bound $S_2 \leq 3$ from Proposition 15. By arguments similar to those in the previous Case B (b) and (c): if $S_2 = 3$, then $A_2 \leq 3$ and $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 2 + 3 + 3 = 8$. If $S_2 = 1$ or 2 , then $A_2 \leq 4$ and $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 2 + 2 + 4 = 8$. If $S_2 = 0$, then $A_2 \leq 5$ and $\mathcal{G}_{\mathcal{D}}(M) \leq 0 + 2 + 0 + 5 = 7$.

Case (C3), $\pi < \tau < 4\pi/3$: in this case, $2\pi/3 < \psi < \pi$ and $0 < \phi < \pi/3$. Now there are three asymmetric subsets, $\mathcal{A}_{-1} = [-\psi/2, -\pi/6)$, $\mathcal{A}_0 = [-\pi/6, \pi/6)$, and $\mathcal{A}_1 = [\pi/6, \psi/2)$. The argument is similar to those given previously, except that to bound the number of vectors \vec{v}_i in the direction of $\mathcal{A}_{-1} \cup \mathcal{A}_1$ with $u_i \in (-1/2, 1/2)$, we must now use Proposition 12. Also, we do not try to optimize the argument as much, since the bound in Proposition 12 is probably already suboptimal.

- A. If $S_1 = 1$, then (4.4) holds. As before, Proposition 4 guarantees that all vectors \vec{v}_i with $i < K$ have corresponding u_i values all in $(-1/2, 0]$ or all in $[0, 1/2)$. Therefore, by Propositions 10 and 11, there is at most one such vector pointing in the direction of \mathcal{A}_0 . Similarly, by Propositions 10 and 12

(applied to each of the cones \mathcal{A}_{-1} and \mathcal{A}_1), the number of such vectors lying in the direction of $\mathcal{A}_{-1} \cup \mathcal{A}_1$ is at most

$$2 + 2 \left\lfloor \frac{\sin(\tau/2 + \pi/6)}{\sin(\tau - \pi)} \right\rfloor. \quad (4.6)$$

This gives the bound

$$A_1 \leq 3 + 2 \left\lfloor \frac{\sin(\tau/2 + \pi/6)}{\sin(\tau - \pi)} \right\rfloor. \quad (4.7)$$

Since $\lceil \frac{\phi}{\pi/3} \rceil = 1$, Proposition 15 implies that $S_2 \leq 2$. Also, Proposition 9 (applied to each of the three asymmetric sets) implies that $A_2 \leq 6$, so we have that

$$\mathcal{G}_{\mathcal{D}}(M) \leq 12 + 2 \left\lfloor \frac{\sin(\tau/2 + \pi/6)}{\sin(\tau - \pi)} \right\rfloor. \quad (4.8)$$

B. Finally, suppose that $S_1 = 0$. In this case, again by Propositions 10–12, there can be at most

$$3 + 2 \left\lfloor \frac{\sin(\tau/2 + \pi/6)}{\sin(\tau - \pi)} \right\rfloor \quad (4.9)$$

indices $1 \leq i \leq K$ with \vec{v}_i in an asymmetric set and with $u_i \in [0, 1/2)$. In addition to these vectors, if there is any other vector \vec{v}_j in an asymmetric set, with $u_j \in (-1/2, 0)$, then it would follow from Proposition 4 that $j = K$. Therefore, there can be at most one such vector \vec{v}_j . The same argument applies with the intervals $[0, 1/2)$ and $(-1/2, 0)$ replaced by $(-1/2, 0]$ and $(0, 1/2)$, respectively, and this gives the bound

$$A_1 \leq 4 + 2 \left\lfloor \frac{\sin(\tau/2 + \pi/6)}{\sin(\tau - \pi)} \right\rfloor. \quad (4.10)$$

If equality holds in this inequality, then we know that (4.4) holds, we are in the same situation just encountered in Case A, and we again use the bounds $S_2 \leq 2$ and $A_2 \leq 6$, arriving at the same bound (4.8) for $\mathcal{G}_{\mathcal{D}}(M)$.

If there is strict inequality in (4.10), then Proposition 15 implies that $S_2 \leq 3$, and it also tells us that if $S_2 = 3$ then \vec{v}_K lies in a symmetric set. Similarly, we have from Proposition 9 that $A_2 \leq 7$ and that if $A_2 = 7$ then \vec{v}_K lies in

an asymmetric set. Therefore, we cannot have both $S_2 = 3$ and $A_2 = 7$. This gives that $S_2 + A_2 \leq 9$, which again implies that (4.8) holds.

5 Explicit Upper Bounds in Dimension $d = 2$, Part 2

Throughout this section, we set $d = 2$ and $\mathcal{D} = \mathbb{S}_1^1$. In this case, the upper bound of 6 obtained in the previous section falls just short of establishing the claimed five distance theorem. We will first deduce a little more information about the possible distances which can occur in this case. The goal of this section is to prove the following theorem, which will thereby complete the proof of Theorem 4 and the $d = 2$ case of Theorem 1.

Theorem 8. For any $M \in \text{SL}_3(\mathbb{R})$, we have that

$$\mathcal{G}_{\mathbb{S}_1^1}(M) \leq 5. \tag{5.1}$$

Since we are dealing with the case $\mathcal{D} = \mathbb{S}_1^1$ we can assume, by replacing each vector (u_i, \vec{v}_i) by its negative if necessary, that $u_i \geq 0$ for $1 \leq i \leq K$. For simplicity, we make this assumption for the duration of this section. It is convenient at this point to gather together some additional properties that must be satisfied by the vectors \vec{v}_i .

Proposition 16. If $\mathcal{G}_{\mathbb{S}_1^1}(M) = K$, then, for all $1 \leq i < j \leq K - 1$,

$$|\vec{v}_i - \vec{v}_j| > |\vec{v}_j|, \tag{5.2}$$

and for all $1 \leq i < j < k \leq K - 1$,

$$|\vec{v}_i - \vec{v}_j - \vec{v}_k| \geq |\vec{v}_k|. \tag{5.3}$$

Proof. Let $1 \leq i < j \leq K - 1$. To prove (5.2) first note that by Proposition 3, together with the above mentioned convention that $u_i, u_j \geq 0$, we have

$$0 < u_i - u_j < 1/2. \tag{5.4}$$

Since $\mathcal{G}_{\mathbb{S}_1^1}(M) = K$, we must have that $u_j \geq 1/2$. Therefore, applying Proposition 6 to the vector $(u_i - u_j, \vec{v}_i - \vec{v}_j) \in \mathcal{Q}_{\mathcal{D}}(\mathbb{S}_1^1)$ gives that

$$|\vec{v}_i - \vec{v}_j| \geq |\vec{v}_j|. \tag{5.5}$$

If there were equality in this inequality then, by the argument used in the proof of Proposition 3, we would have that $j = K$, which is a contradiction. Therefore, the strict inequality (5.2) holds.

Next, to prove (5.3), let $1 \leq i < j < k \leq K-1$. We have that $1/2 \leq u_k < u_j < u_i < 1$, and therefore that

$$0 < u_k + u_j - u_i < u_k. \quad (5.6)$$

Applying Proposition 6 to the vector $(u_k + u_j - u_i, \vec{v}_k + \vec{v}_j - \vec{v}_i) \in \mathcal{Q}_{\mathcal{D}}(\mathbb{S}_1^1)$ gives that

$$|\vec{v}_k + \vec{v}_j - \vec{v}_i| \geq |\vec{v}_k|, \quad (5.7)$$

which proves the result. ■

As a corollary of Proposition 16, we also deduce the following result.

Proposition 17. If $\mathcal{G}_{\mathbb{S}_1^1}(M) = K$, then, for all $1 \leq i < j \leq K-1$, the angle between \vec{v}_i and \vec{v}_j must be greater than $\pi/3$. Also, for all $1 \leq i < j < k \leq K-1$, the vector \vec{v}_i does not lie in the positive cone determined by \vec{v}_j and \vec{v}_k .

Proof. For the 1st part of the proposition, if $1 \leq i < j \leq K-1$, then the fact that the angle between \vec{v}_i and \vec{v}_j must be greater than $\pi/3$ follows (5.2) together with Proposition 2.

For the 2nd part, suppose by way of contradiction that $1 \leq i < j < k \leq K-1$ and that the vector \vec{v}_i does lie in the positive cone determined by \vec{v}_j and \vec{v}_k . Note that $|\vec{v}_i| < |\vec{v}_j| < |\vec{v}_k|$ and that, by the 1st part of the proposition, the angle between \vec{v}_j and \vec{v}_k is greater than $2\pi/3$. With these observations in mind, consider Figure 7. The figure is rotated so that the vector \vec{v}_k is aligned with the positive x -axis. Depending on the orientation of the vectors involved, it may also be reflected about the x -axis. The vector $-\vec{v}_j - \vec{v}_k$ must lie in the sector indicated in red. Once \vec{v}_j is chosen, the vector $\vec{v}_i - \vec{v}_j - \vec{v}_k$ must lie in a sector of the circle of radius $|\vec{v}_i|$ centered at $-\vec{v}_j - \vec{v}_k$, as indicated by the blue region in the figure. However, no matter what choice is made for \vec{v}_j , this sector will lie completely within the open disk of radius $|\vec{v}_k|$ centered at the origin.

Since this contradicts (5.3), we conclude that \vec{v}_i cannot lie in the positive cone determined by \vec{v}_j and \vec{v}_k . ■

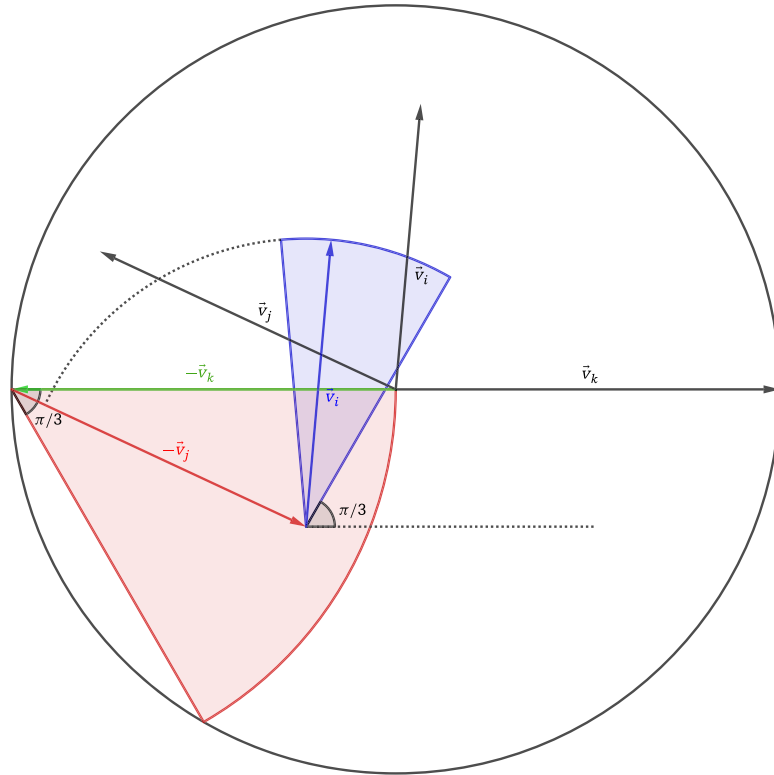


Fig. 7. Illustration corresponding to the contradictory hypothesis that \vec{v}_i lies in the positive cone determined by \vec{v}_j and \vec{v}_k .

Proof of Theorem 8. Suppose, contrary to the statement of the theorem, that $\mathcal{G}_{\mathbb{S}_1^1}(M) \geq 6$. Consider the collection of vectors \vec{v}_i , with $1 \leq i \leq 5$. We will say that two vectors from this collection are *consecutive* if there is no other vector from the collection that lies in their positive cone. Every vector in the collection is consecutive to two others. By Proposition 17, the angle between any pair of consecutive vectors is greater than $\pi/3$. Since there are five vectors in the collection, it follows that if i, j , and k are distinct indices with $1 \leq i, j, k \leq 5$ and if \vec{v}_i is consecutive to both \vec{v}_j and \vec{v}_k , then the angle between \vec{v}_j and \vec{v}_k is less than π . In other words, in the situation just described, the vector \vec{v}_i lies in the positive cone determined by \vec{v}_j and \vec{v}_k . Therefore, by Proposition 17, if i, j , and k are distinct and if \vec{v}_i is consecutive to both \vec{v}_j and \vec{v}_k , then it must be the case that $i > \min\{j, k\}$. However, the vector \vec{v}_1 is consecutive to two vectors \vec{v}_j and \vec{v}_k , with $1 < j < k$, and this gives a contradiction. Therefore, we conclude that $\mathcal{G}_{\mathbb{S}_1^1}(M) \leq 5$. ■

6 Explicit Upper Bounds in Dimension $d > 2$

Let $G = \mathrm{SL}(d+1, \mathbb{R})$ and $\Gamma = \mathrm{SL}(d+1, \mathbb{Z})$. As in the proof of Theorem 7, for each $M \in \Gamma \backslash G$ we suppose that $K \in \mathbb{N}$ and $\{(u_i, \vec{v}_i)\}_{i=1}^K \subseteq M$ are chosen so that conditions (V1)–(V3) hold. In this section, we will prove the following statement, which by (2.14) implies Theorem 1 in dimension $d \geq 3$.

Theorem 9. Let $d \geq 3$ and $\mathcal{D} = \mathbb{S}_1^{d-1}$. Then for any $M \in G$ we have that

$$\mathcal{G}_{\mathcal{D}}(M) \leq \sigma_d + 1. \quad (6.1)$$

We will use the following analogues of Propositions 3 and 9.

Proposition 18. Let $d \geq 3$ and $\mathcal{D} = \mathbb{S}_1^{d-1}$. If $(u, \vec{v}) \in \mathcal{Q}_{\mathcal{D}}(M)$ with $u \in (-1/2, 1/2)$, then $|\vec{v}_K| \leq |\vec{v}|$. It follows that if, for some integer $1 \leq i \leq K$ we have that $u_i \in (-1/2, 1/2)$, then we must have that $i = K$.

Proof. Suppose first that $u \in (-1/2, 0]$. Then $-u \in [0, 1/2)$ and $(-u, -\vec{v}) \in \mathcal{Q}_{\mathcal{D}}(M)$. Therefore, for any $t \in (0, 1)$, any shortest vector in $\mathcal{Q}_{\mathcal{D}}(M, t)$ can have length at most $|\vec{v}|$. If $u \in [0, 1/2)$ the argument is symmetric, so this verifies the 1st claim of the proposition.

For the 2nd claim, apply the first with $(u, \vec{v}) = (u_i, \vec{v}_i)$. Then it follows from properties (V1)–(V3) that $i = K$. ■

Proposition 19. Let $d \geq 3$ and $\mathcal{D} = \mathbb{S}_1^{d-1}$. If $1 \leq i, j \leq K$ and

$$-1 < u_i < u_j \leq -1/2 \quad \text{or} \quad 1/2 \leq u_j < u_i < 1, \quad (6.2)$$

then the angle between \vec{v}_i and \vec{v}_j is greater than $\pi/3$.

Proof. Suppose the hypotheses of the proposition are satisfied and that $u_i, u_j \in (-1, -1/2]$ with $u_i < u_j$. Then conditions (V1) and (V3) imply that $i < j$ and that $|\vec{v}_i| < |\vec{v}_j|$ (this follows, e.g., from the argument used in the proof of Proposition 6). If the angle between \vec{v}_i and \vec{v}_j were less than or equal to $\pi/3$ then by Proposition 2 we would have that

$$|\vec{v}_i - \vec{v}_j| < |\vec{v}_j|. \quad (6.3)$$

Since $(u_i - u_j, \vec{v}_i - \vec{v}_j) \in \mathcal{Q}_{\mathcal{D}}(M)$ satisfies $u_i - u_j \in (-1/2, 1/2)$, we could then deduce from Proposition 18 that

$$|\vec{v}_K| \leq |\vec{v}_i - \vec{v}_j| < |\vec{v}_j|, \tag{6.4}$$

which contradicts (V1). Therefore, the angle between \vec{v}_i and \vec{v}_j is greater than $\pi/3$. The argument is symmetric if $u_i, u_j \in [1/2, 1)$ with $u_i > u_j$. ■

Proof of Theorem 9. By Proposition 18, there is at most one value of $1 \leq i \leq K$ with $u_i \in (-1/2, 1/2)$. If such a value exists, then it must be K .

For each $1 \leq i \leq K - 1$, let

$$\vec{x}_i = \frac{\vec{v}_i}{|\vec{v}_i|} \in \mathbb{S}_1^{d-1}. \tag{6.5}$$

By Proposition 19, any points \vec{x}_i and \vec{x}_j with $i \neq j$ are separated by an angle greater than $\pi/3$. Therefore, the collection of spheres of radius $1/2$ centered at the points \vec{x}_i , for $1 \leq i \leq K - 1$, do not overlap, and they are all tangent to the sphere of radius $1/2$ centered at the origin. It follows that

$$K - 1 \leq \sigma_d, \tag{6.6}$$

and this completes the proof of Theorem 9. ■

7 Continuity and Local Upper/Lower Bounds

We now turn to the case of general $\mathcal{D} \subseteq \mathbb{S}_1^{d-1}$. We will show in this section that there are choices of \mathcal{D} for which $F_{\mathcal{D}}(M, t)$ is unbounded. First, we establish local upper bounds (i.e., upper bounds for M on compacta) that hold for general \mathcal{D} .

Proposition 20. Suppose that $\mathcal{D} \subseteq \mathbb{S}_1^{d-1}$ has non-empty interior and that $\mathcal{C} \subset \Gamma \backslash G \times (0, 1)$ is compact. Then the following must hold:

- (i) There exists a number $\kappa(\mathcal{C}) > 0$ such that $F_{\mathcal{D}}(M, t) < \kappa(\mathcal{C})$ if $(\Gamma M, t) \in \mathcal{C}$, and
- (ii) F is continuous at every point $(\Gamma M, t) \in \mathcal{C}$ with

$$(\mathbb{Z}^{d+1}M \setminus \{0\}) \cap \partial((-t, 1 - t) \times (0, \kappa(\mathcal{C}])\mathcal{D}) = \emptyset. \tag{7.1}$$

We emphasize that in (ii), relation (7.1) needs to be verified only for one specific but arbitrary $\kappa(\mathcal{C}) > F_{\mathcal{D}}(M, t)$.

Proof. It follows from the proof of Proposition 1 above that $F(M, t)$ is finite, for any choice of M and t . The actual bound obtained by that argument depends on the choice

of ϵ in the proof. By Mahler's compactness criterion, since \mathcal{C} is compact, it is possible to choose a single value of $\epsilon > 0$ that works for every $(M, t) \in \mathcal{C}$. This implies the existence of a constant $\kappa(\mathcal{C})$ satisfying the condition in (i).

The proof of (ii) is then analogous to the proof of [27, Proposition 2]. \blacksquare

Let us now extend the above uniform upper bound to all $t \in (0, 1)$, with M in a compact set. Given a bounded subset $\mathcal{A} \subset \mathbb{R}^{d+1}$ with non-empty interior, and $M \in G$, we define the *covering radius* (also called *inhomogeneous minimum*)

$$\rho(M, \mathcal{A}) = \inf\{\theta > 0 \mid \theta\mathcal{A} + \mathbb{Z}^{d+1}M = \mathbb{R}^{d+1}\}. \quad (7.2)$$

Because \mathcal{A} has non-empty interior, $\rho(M, \mathcal{A}) < \infty$. We will in the following take \mathcal{A} to be of the form $\mathcal{A} = (0, 1) \times (0, r]D$. Then $\mathcal{A} \subset \lambda\mathcal{A}$ for any $\lambda > 1$, and thus $\theta\mathcal{A} + \mathbb{Z}^{d+1}M = \mathbb{R}^{d+1}$ for every $\theta > \rho(M, \mathcal{A})$. Therefore, for such θ , the set $\theta\mathcal{A} + \vec{x}$ intersects $\mathbb{Z}^{d+1}M$ in at least one point, for every $\vec{x} \in \mathbb{R}^{d+1}$.

For a given set $\mathcal{C} \subset \Gamma \backslash G$, we define

$$\bar{\rho}(\mathcal{C}, \mathcal{A}) = \sup_{\Gamma M \in \mathcal{C}} \rho(M, \mathcal{A}). \quad (7.3)$$

It is well known that $\bar{\rho}(\mathcal{C}, \mathcal{A}) < \infty$ for every compact $\mathcal{C} \subset \Gamma \backslash G$. This follows, for example, from the comments about finiteness and continuity of inhomogeneous minima of balls at the tops of [25, pp. 231 and 234] (an upper bound for $\bar{\rho}(\mathcal{C}, \mathcal{A})$ is obtained from an upper bound with \mathcal{A} replaced by a ball contained in \mathcal{A}). For $\theta > 0$, set

$$D(\theta) = \begin{pmatrix} \theta^d & 0 \\ 0 & \theta^{-1}\mathbf{1}_d \end{pmatrix} \in G. \quad (7.4)$$

Proposition 21. Let $\mathcal{D} \subseteq \mathbb{S}_1^{d-1}$ with non-empty interior. Assume $\mathcal{C} \subset \Gamma \backslash G$ is compact, and $\theta > \bar{\rho}(\mathcal{C}, (0, 1) \times (0, 1]D)$. Then

$$F_{\mathcal{D}}(M, t) \leq \theta^{d+1} \quad (7.5)$$

for $\Gamma M \in \mathcal{C}D(\theta)^{-1}$ and $t \in (0, 1)$.

Proof. For each $t \in (0, 1)$, the set

$$\mathcal{A}_{t,\theta} = (-t, 1-t) \times (0, \theta^{d+1}]D \subset \mathbb{R}^{d+1} \quad (7.6)$$

has non-empty interior. For any $\Gamma M \in \mathcal{C}D(\theta)^{-1}$ and $t \in (0, 1)$, it follows from the definition of the function $F_{\mathcal{D}}$ that, if $\mathcal{A}_{t,\theta}$ intersects $\mathbb{Z}^{d+1}M$ in at least one point, then (7.5) holds. Now $\mathcal{A}_{t,\theta} \cap \mathbb{Z}^{d+1}M \neq \emptyset$ is equivalent to $\theta^d \mathcal{A}_{t,1} \cap \mathbb{Z}^{d+1}MD(\theta) \neq \emptyset$. The latter

holds because the assumption that $\theta > \bar{\rho}(\mathcal{C}, (0, 1) \times (0, 1] \mathcal{D})$ implies that $\theta \mathcal{A}_{t,1} \cap \mathbb{Z}^{d+1} M' \neq \emptyset$ for every $\Gamma M' \in \mathcal{C}$. Now choose $M' = MD(\theta)$ and note that $\Gamma MD(\theta) \in \mathcal{C}$ by assumption. ■

As a consequence of the previous proposition, we have the following result.

Proposition 22. Let $\mathcal{D} \subseteq \mathbb{S}_1^{d-1}$ have non-empty interior. Assume $\mathcal{C} \subset \Gamma \backslash G$ is compact, and $\theta > \bar{\rho}(\mathcal{C}, (0, 1) \times (0, 1] \mathcal{D})$. Then there is a constant $C_{\theta, \mathcal{D}} < \infty$ such that

$$\mathcal{G}_{\mathcal{D}}(M) \leq C_{\theta, \mathcal{D}} \tag{7.7}$$

for $\Gamma M \in \mathcal{CD}(\theta)^{-1}$.

Proof. It follows from Proposition 21, together with the definition of the function $\mathcal{G}_{\mathcal{D}}$, that for any $\Gamma M \in \mathcal{CD}(\theta)^{-1}$, the quantity $\mathcal{G}_{\mathcal{D}}(M)$ is bounded above by the number of lattice points in $\mathbb{Z}^{d+1} M$, which lie in the region

$$(-1, 1) \times [0, \theta^{d+1}] \mathcal{D} \subseteq \mathbb{R}^{d+1}. \tag{7.8}$$

In view of Mahler’s criterion, the number of such lattice points is uniformly bounded above for all ΓM in the compact subset $\mathcal{CD}(\theta)^{-1}$ of $\Gamma \backslash G$. ■

The key point is now that, in addition to the above upper bounds, we can find open sets $\mathcal{U} \subset \Gamma \backslash G$, on which $\mathcal{G}_{\mathcal{D}, N}(M)$ can exceed any given value. This requires however that \mathcal{D} is contained in a hemisphere. Let $\mathcal{H} \subset \mathbb{S}_1^{d-1}$ be an (arbitrary) open hemisphere, and $\mathcal{D} \subset \mathbb{S}_1^{d-1}$ with non-empty interior so that $\mathcal{D}^{\text{cl}} \subset \mathcal{H}$. Choose $d + 1$ row vectors $\vec{e}_0, \vec{e}_1, \dots, \vec{e}_d \in \mathbb{S}_1^{d-1}$ with the properties

- (i) $\vec{e}_1 \in \mathcal{D}^\circ$ and $\vec{e}_0 \in \mathcal{H} \setminus \mathcal{D}$ such that $\vec{e}_0 \cdot \vec{e}_1 > 0$;
- (ii) $\vec{e}_2, \dots, \vec{e}_d \notin \mathcal{D}$ such that $(\vec{e}_1, \dots, \vec{e}_d)$ forms an orthonormal basis of \mathbb{R}^d with

$$\det \begin{pmatrix} \vec{e}_1 \\ \vdots \\ \vec{e}_d \end{pmatrix} = 1.$$

Given $\epsilon > 0$, define the matrix

$$M_\epsilon = \begin{pmatrix} \epsilon & -\epsilon \vec{e}_0 \\ 0 & \vec{e}_1 \\ 0 & \epsilon^{-1/(d-1)} \vec{e}_2 \\ \vdots & \vdots \\ 0 & \epsilon^{-1/(d-1)} \vec{e}_d \end{pmatrix}. \tag{7.9}$$

Note that $\det M_\epsilon = 1$, and thus the vectors

$$\vec{b}_0 = (\epsilon, -\epsilon\vec{e}_0), \vec{b}_1 = (0, \vec{e}_1), \vec{b}_2 = (0, \epsilon^{-1/(d-1)}\vec{e}_2), \dots, \vec{b}_d = (0, \epsilon^{-1/(d-1)}\vec{e}_d)$$

form a basis of the unimodular lattice $\mathcal{L}_\epsilon = \mathbb{Z}^{d+1}M_\epsilon$.

Let $L(x)$ denote the largest integer strictly less than x . That is, in terms of the floor function $L(x) = \lfloor x \rfloor$ if $x \notin \mathbb{Z}$ and $L(x) = x - 1$ if $x \in \mathbb{Z}$.

Proposition 23. Let $\mathcal{D} \subset \mathcal{H}$ and M_ϵ be as above. Then there exist $\lambda \in (0, 1)$ and $\epsilon_0 > 0$ such that, for any $\epsilon \in (0, \epsilon_0]$ and $t \in (\lambda, 1)$,

- (i) $F_{\mathcal{D}}(M_\epsilon, t) = |\vec{e}_1 - \epsilon L(\epsilon^{-1}(1-t))\vec{e}_0|$ and
- (ii) $F_{\mathcal{D}}$ is continuous at $(\Gamma M_\epsilon, t) \in \Gamma \backslash G \times (0, 1)$ if $t \notin 1 + \epsilon\mathbb{Z}$.

Proof. Fix $s_0 \in (0, \vec{e}_0 \cdot \vec{e}_1)$, and denote by $s_- \leq 0 \leq s_+$ the infimum and supremum of all s such that $\vec{e}_1 - s\vec{e}_0 \in \mathbb{R}_{>0}\mathcal{D}$; since $e_1 \in \mathcal{D}^\circ$ we have $s_- < 0 < s_+$. Note also that

$$\frac{d}{ds} |\vec{e}_1 - s\vec{e}_0| = \frac{s - \vec{e}_0 \cdot \vec{e}_1}{|\vec{e}_1 - s\vec{e}_0|} < 0 \quad (7.10)$$

if $s \leq s_0$.

Proof of (i): we are interested in the lattice points from $\mathbb{Z}^{d+1}M_\epsilon$ contributing to (2.4), that is,

$$\mathcal{Q}_{\mathcal{D}}(M_\epsilon, t) = \{(u, \vec{v}) \in \mathbb{Z}^{d+1}M_\epsilon \mid -t < u < 1-t, \vec{v} \in \mathbb{R}_{>0}\mathcal{D}\}, \quad (7.11)$$

and in particular those with minimal $|\vec{v}|$. We begin with those elements of the form

$$(u, \vec{v}) = m_0\vec{b}_0 + m_1\vec{b}_1 = (\epsilon m_0, m_1\vec{e}_1 - \epsilon m_0\vec{e}_0), \quad m_0 \in \mathbb{Z}, m_1 \in \mathbb{Z}_{\geq 1}. \quad (7.12)$$

By construction, we have $m_1\vec{e}_1 - \epsilon m_0\vec{e}_0 \in \mathbb{R}_{>0}\mathcal{D}^\circ$ if and only if $s_- < \epsilon m_0/m_1 < s_+$; and $m_1\vec{e}_1 - \epsilon m_0\vec{e}_0 \in \mathbb{R}_{>0}\mathcal{D}^{\text{cl}}$ if and only if $s_- \leq \epsilon m_0/m_1 \leq s_+$. In view of (7.10), the length $|\vec{e}_1 - \epsilon m_0/m_1\vec{e}_0|$ is strictly decreasing (as a function of m_0/m_1) if $\epsilon m_0/m_1 \leq s_0$. Let us restrict our attention to those t for which $1-t < \min\{s_0, s_+\}$. Then the condition $\epsilon m_0 < 1-t$ implies $\epsilon m_0/m_1 < s_+$ and $\epsilon m_0/m_1 \leq s_0$ for all $m_1 \geq 1$. Hence, the smallest value of $|m_1\vec{e}_1 - \epsilon m_0\vec{e}_0|$ is obtained for $m_0 = L(\epsilon^{-1}(1-t))$ and $m_1 = 1$. In summary, we have shown thus far that for $t > 1 - \min\{s_0, s_+\}$,

$$F_{\mathcal{D}}(M_\epsilon, t) \leq |\vec{e}_1 - \epsilon L(\epsilon^{-1}(1-t))\vec{e}_0|. \quad (7.13)$$

Note that

$$|\vec{e}_1 - s\vec{e}_0| = \sqrt{1 - 2s\vec{e}_0 \cdot \vec{e}_1 + s^2} < 1 \tag{7.14}$$

for $0 < s \leq s_0$ and $\vec{e}_0 \cdot \vec{e}_1 > s_0$, and hence $F_{\mathcal{D}}(M_\epsilon, t) < 1$.

What we need to establish now is that all other elements in $\mathcal{Q}_{\mathcal{D}}(M_\epsilon, t)$ that are not of the form (7.12) have larger $|\vec{v}|$. Consider first the set of vectors

$$(u, \vec{v}) = m_0\vec{b}_0 + m_1\vec{b}_1 = (\epsilon m_0, m_1\vec{e}_1 - \epsilon m_0\vec{e}_0), \quad m_0 \in \mathbb{Z}, m_1 \in \mathbb{Z}_{\leq 0}, \tag{7.15}$$

Since $\vec{e}_0 \in \mathcal{H} \setminus \mathcal{D}$ and $\vec{e}_1 \in \mathcal{D}^\circ$, we have $m_1\vec{e}_1 - \epsilon m_0\vec{e}_0 \notin \mathbb{R}_{>0}\mathcal{D}$ for all $m_1 \leq 0$, and hence the corresponding vectors are not in $\mathcal{Q}_{\mathcal{D}}(M_\epsilon, t)$.

Next consider the remaining cases

$$(u, \vec{v}) = m_0\vec{b}_0 + \dots + m_d\vec{b}_d, \quad m_0, m_1 \in \mathbb{Z}, (m_2, \dots, m_d) \in \mathbb{Z}^{d-1} \setminus \{0\}. \tag{7.16}$$

We need to understand whether any of these vectors can lie in $\mathcal{Q}_{\mathcal{D}}(M_\epsilon, t)$ and satisfy $|\vec{v}| < 1$. We make the following observations:

- (a) The domain $(-1, 1) \times (0, 1)\mathcal{D}$ is bounded.
- (b) The vector $m_0\vec{b}_0$ has bounded length $|m_0\vec{b}_0| = \sqrt{2}|\epsilon m_0| < \sqrt{2}$ (since $-1 < \epsilon m_0 < 1$).
- (c) The vector $m_1\vec{b}_1 + \dots + m_d\vec{b}_d$ has length at least $\epsilon^{-1/(d-1)}$ since $(m_2, \dots, m_d) \in \mathbb{Z}^{d-1} \setminus \{0\}$.

Therefore, as long as ϵ is sufficiently small, $(-1, 1) \times (0, 1)\mathcal{D}$ will not contain any vectors of the form (7.16). Since we have now considered all vectors for our restricted values of t , this establishes claim (i) with $\lambda = 1 - \min\{s_0, s_+\}$.

Proof of (ii): we need to establish that, for $\lambda < t < 1$, $t \notin 1 + \epsilon\mathbb{Z}$, the function $F_{\mathcal{D}}$ is continuous at $(\Gamma M_\epsilon, t)$. By Proposition 20 (with $\mathcal{C} = \{(\Gamma M_\epsilon, t)\}$), it is sufficient to check that

$$(\mathbb{Z}^{d+1}M_\epsilon \setminus \{0\}) \cap \partial((-t, 1 - t) \times (0, \kappa]\mathcal{D}) = \emptyset, \tag{7.17}$$

for any fixed choice of $\kappa > F_{\mathcal{D}}(\Gamma M_\epsilon, t)$. We fix κ so that $F_{\mathcal{D}}(\Gamma M_\epsilon, t) < \kappa < 1$ and

$$\kappa \notin \{|m_1\vec{e}_1 - \epsilon m_0\vec{e}_0| \mid (m_0, m_1) \in \mathbb{Z}_{\geq 1}^2\}. \tag{7.18}$$

Since vectors with $(m_2, \dots, m_d) \in \mathbb{Z}^{d-1} \setminus \{0\}$ are outside the bounded domain $((-t, 1-t) \times (0, \kappa] \mathcal{D})^{\text{cl}}$ for ϵ sufficiently small (by the argument in the proof of fact (i) above), what we are aiming to show is equivalent to

$$\{(\epsilon m_0, m_1 \vec{e}_1 - \epsilon m_0 \vec{e}_0) \mid (m_0, m_1) \in (\mathbb{Z}^2 \setminus \{0\}) \cap \partial((-t, 1-t) \times (0, \kappa] \mathcal{D})\} = \emptyset. \quad (7.19)$$

By the same argument as above, for $m_1 \leq 0$ we have $m_1 \vec{e}_1 - \epsilon m_0 \vec{e}_0 \notin \mathbb{R}_{\geq 0} \mathcal{D}^{\text{cl}}$ (unless $(m_0, m_1) = 0$, which is excluded). So we can assume $m_1 \geq 1$ from now on. Then, for $m_0 \leq 0$, we have by the monotonicity (7.10) that $|m_1 \vec{e}_1 - \epsilon m_0 \vec{e}_0| \geq m_1 |\vec{e}_1| \geq |\vec{e}_1| = 1$. Therefore, $m_1 \vec{e}_1 - \epsilon m_0 \vec{e}_0 \notin [0, \kappa] \mathcal{D}^{\text{cl}}$. What remains is to check that

$$\{(\epsilon m_0, m_1 \vec{e}_1 - \epsilon m_0 \vec{e}_0) \mid (m_0, m_1) \in \mathbb{Z}_{\geq 1}^2 \cap \partial((-t, 1-t) \times (0, \kappa] \mathcal{D})\} = \emptyset. \quad (7.20)$$

The truth of relation (7.20) is equivalent to the truth of both

$$\{(\epsilon m_0, m_1 \vec{e}_1 - \epsilon m_0 \vec{e}_0) \mid (m_0, m_1) \in \mathbb{Z}_{\geq 1}^2 \cap ((-t, 1-t) \times [0, \kappa] \mathcal{D}^{\text{cl}})\} = \emptyset \quad (7.21)$$

and

$$\{(\epsilon m_0, m_1 \vec{e}_1 - \epsilon m_0 \vec{e}_0) \mid (m_0, m_1) \in \mathbb{Z}_{\geq 1}^2 \cap ([-t, 1-t] \times \partial((0, \kappa] \mathcal{D}))\} = \emptyset. \quad (7.22)$$

The 1st relation (7.21) is automatically satisfied since (1) by assumption $\epsilon m_0 \neq 1-t$ for any integer m_0 , and (2) $\epsilon m_0 \neq -t$ because $t > 0$ and $m_0 > 0$.

As to the 2nd relation (7.22), the statement $m_1 \vec{e}_1 - \epsilon m_0 \vec{e}_0 \in \partial((0, \kappa] \mathcal{D})$ implies $s_- = \epsilon m_0 / m_1$ or $s_+ = \epsilon m_0 / m_1$ or $|m_1 \vec{e}_1 - \epsilon m_0 \vec{e}_0| = \kappa$. The 1st option is not possible since $s_- < 0$, and 3rd is excluded by assumption. If the 2nd option holds, then, since $\epsilon m_0 \in [-t, 1-t]$, we have $m_1 s_+ \leq 1-t$ and thus $s_+ \leq 1-t$. But this contradicts our assumption $1-t < s_+$. Hence, (7.22) holds and the proof is complete. ■

The following lower bound on the number of distinct values of $t \mapsto F_{\mathcal{D}}(M, t)$ is a corollary of the previous proposition.

Proposition 24. Let $\mathcal{H} \subset \mathbb{S}_1^{d-1}$ be an arbitrary open hemisphere, and suppose that $\mathcal{D} \subset \mathbb{S}_1^{d-1}$ has non-empty interior and satisfies $\mathcal{D}^{\text{cl}} \subset \mathcal{H}$. Then there is a constant $c_{\mathcal{D}} > 0$ such that, for any $\epsilon > 0$, there exists an open subset $\mathcal{U}_{\epsilon} \subset \Gamma \setminus G$ and integer N_{ϵ} with the property that, for all $\Gamma M \in \mathcal{U}_{\epsilon}$ and $N \geq N_{\epsilon}$,

$$\mathcal{G}_{\mathcal{D}, N}(M) \geq c_{\mathcal{D}} \epsilon^{-1}. \quad (7.23)$$

Proof. Proposition 23 (i) shows that $\mathcal{G}_{\mathcal{D}}(M_\epsilon) \geq c_{\mathcal{D}}\epsilon^{-1}$ for a sufficiently small $c_{\mathcal{D}} > 0$. Denote the distinct elements of the set $\{F_{\mathcal{D}}(M_\epsilon, t) \mid t \in (\lambda, 1)\}$ by $0 < \varphi_1 < \dots < \varphi_{\mathcal{G}_{\mathcal{D}}(M_\epsilon)} < 1$. Let $\delta = \max_i(\varphi_{i+1} - \varphi_i)$. Then by the continuity established in Proposition 23 (ii), there exists a neighborhood $\mathcal{U}_\epsilon \subset \Gamma \backslash G$ of ΓM_ϵ and an $\eta_\epsilon > 0$ such that for $t \notin 1 + \epsilon\mathbb{Z}$, we have that

$$|F_{\mathcal{D}}(M, t') - F_{\mathcal{D}}(M_\epsilon, t)| < \delta/2, \tag{7.24}$$

whenever $\Gamma M \in \mathcal{U}_\epsilon$ and $t' \in (t - \eta_\epsilon, t + \eta_\epsilon)$. For $N \geq \eta_\epsilon^{-1}$, we can find an integer n so that $\frac{n}{N} \in (t - \eta_\epsilon, t + \eta_\epsilon)$. This implies $\mathcal{G}_{\mathcal{D},N}(M) \geq \mathcal{G}_{\mathcal{D}}(M_\epsilon) \geq c_{\mathcal{D}}\epsilon^{-1}$ for all $\Gamma M \in \mathcal{U}_\epsilon$ and $N \geq \eta_\epsilon^{-1}$. ■

Proof of Theorem 5. The proof of Theorem 5 now follows from the same argument as the proof of [27, Theorem 1]. For $\vec{\alpha} \in P$, we have that the set $\{\Gamma A_{N_i + \frac{1}{2}}(\vec{\alpha}) \mid i \in \mathbb{N}\}$ is dense in $\Gamma \backslash G$; see [27, Section 2] for details. The claim on the limit inferior then follows from Proposition 21, since by density we have infinite returns to a given compact subset. The claim on the limit superior follows from Proposition 24, since by density the above set intersects any given open neighborhood \mathcal{U}_ϵ . ■

Proof of Theorem 6. This is analogous to the proof of to the proof of [27, Theorem 2]. Let

$$\Phi^s = \begin{pmatrix} e^{-s} & 0 \\ 0 & e^{s/d} \mathbf{1}_d \end{pmatrix} \in G. \tag{7.25}$$

A special case of Dani’s correspondence [15, Theorem 2.20] states that, for any $\vec{\alpha} \in \mathbb{R}^d$, the orbit

$$\left\{ \Gamma \begin{pmatrix} 1 & \vec{\alpha} \\ 0 & \mathbf{1}_d \end{pmatrix} \Phi^s \mid s \in \mathbb{R}_{\geq 0} \right\} \tag{7.26}$$

is bounded in $\Gamma \backslash G$ if and only if $\vec{\alpha}$ is badly approximable by \mathbb{Q}^d .

Note that for $\mathbb{Z}^d M_0 = \mathbb{Z}^d M_0$ and $\vec{\alpha} = \vec{\alpha}_0 M_0$

$$A_N(\vec{\alpha}, \mathcal{L}) = \begin{pmatrix} 1 & \vec{\alpha}_0 \\ 0 & \mathbf{1}_d \end{pmatrix} \begin{pmatrix} N^{-1} & 0 \\ 0 & N^{1/d} \mathbf{1}_d \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & M_0 \end{pmatrix}. \tag{7.27}$$

By assumption, $\vec{\alpha}$ is badly approximable by $\mathbb{Q}\mathcal{L}$, that is, $\vec{\alpha}_0$ is badly approximable by \mathbb{Q}^d . It follows from Dani’s correspondence that the set $\{\Gamma A_{N_i}(\vec{\alpha}_0 M_0, \mathbb{Z}^d M_0) \mid N \in \mathbb{N}\}$ is contained in a compact subset of $\Gamma \backslash G$. The claim then follows from Proposition 21. ■

We now return to the special case $\mathcal{D} = \mathbb{S}_1^{d-1}$ and provide the remaining ingredients for the proof of Theorem 2.

Proposition 25. Let $\mathcal{D} = \mathbb{S}_1^{d-1}$, and fix a matrix $A_{N_+}(\vec{\alpha})$ as in (2.2) with $N_+ := N + \frac{1}{2}$, $N \in \mathbb{N}$. Then the following hold.

- (i) For given $n = 1, \dots, N$, the function $t \mapsto F_{\mathcal{D}}(A_{N_+}(\vec{\alpha}), t)$ is constant on the interval $I_n = (N_+^{-1}(n - \frac{1}{2}), N_+^{-1}n]$.
- (ii) $F_{\mathcal{D}}$ is continuous at $(\Gamma A_{N_+}(\vec{\alpha}), t) \in \Gamma \backslash G \times (0, 1)$ if $t, 1 - t \notin N_+^{-1}\mathbb{Z}$.

Proof. Throughout this proof, set $\mathcal{D} = \mathbb{S}_1^{d-1}$. Then

$$F_{\mathcal{D}}(A_{N_+}(\vec{\alpha}), t) = N_+^{1/d} \min \{ |k\vec{\alpha} + \vec{\ell}| > 0 \mid -N_+t < k < N_+(1-t), k \in \mathbb{Z}, \vec{\ell} \in \mathbb{Z}^d \mathcal{M}_0 \}. \quad (7.28)$$

The set $(-N_+t, N_+(1-t)) \cap \mathbb{Z}$ is independent of the choice of $t \in I_n$; this proves (i). In view of Proposition 20, claim (ii) holds if

$$(\mathbb{Z}^{d+1} A_{N_+}(\vec{\alpha}) \setminus \{0\}) \cap \partial((-t, 1-t) \times (0, \kappa] \mathcal{D}) = \emptyset, \quad (7.29)$$

for a fixed choice of $\kappa > \sup_{t \in (0,1)} F_{\mathcal{D}}(A_{N_+}(\vec{\alpha}), t)$. The set

$$\tilde{\mathcal{M}}(M) = \{ |\vec{v}| > 0 \mid (u, \vec{v}) \in \mathbb{Z}^{d+1} M, |u| \leq 1 \} \quad (7.30)$$

is discrete for every fixed $M \in G$ (cf. (2.11)), so clearly we can choose $\kappa \notin \tilde{\mathcal{M}}(A_{N_+}(\vec{\alpha}))$. This means that the lattice $\mathbb{Z}^{d+1} A_{N_+}(\vec{\alpha})$ does not intersect the set $[-1, 1] \times \kappa \mathcal{D}$. Furthermore, by the assumption $t, 1 - t \notin N_+^{-1}\mathbb{Z}$, we have

$$(\mathbb{Z}^{d+1} A_{N_+}(\vec{\alpha}) \setminus \{0\}) \cap ((-t, 1-t) \times (0, \kappa] \mathcal{D}) = \emptyset, \quad (7.31)$$

which establishes (7.29) and hence completes the proof of claim (ii). ■

Proof of Theorem 2. In the following, $\mathcal{D} = \mathbb{S}_1^{d-1}$. We fix $N \in \mathbb{N}$ until the last step of the proof. By (2.6) and Proposition 25 (i), we have

$$\delta_{n,N}(\mathcal{D}) = N_+^{-1/d} F_{\mathcal{D}}(A_{N_+}(\vec{\alpha}_0, \mathcal{L}_0), t_n), \quad (7.32)$$

for any $t_n \in I_n$, and hence

$$g_N(\vec{\alpha}_0, \mathcal{L}_0) = |\{F_{\mathcal{D}}(A_{N_+}(\vec{\alpha}_0, \mathcal{L}_0), t_n) \mid n = 1, \dots, N\}|. \quad (7.33)$$

Choose $\delta > 0$ sufficiently small so that the elements of the set $\{F_{\mathcal{D}}(A_{N_+}(\vec{\alpha}_0, \mathcal{L}_0), t_n) \mid n = 1, \dots, N\}$ are separated by at least δ . Fix any $t_n \in I_n$ such that $t_n, 1 - t_n \notin N_+^{-1}\mathbb{Z}$. Proposition 25 (ii) implies that $F_{\mathcal{D}}$ is continuous at $(\Gamma A_{N_+}(\vec{\alpha}_0, \mathcal{L}_0), t_n)$, for $n = 1, \dots, N$. That is, there exists a neighborhood $\mathcal{U} \subset \Gamma \setminus G$ of the point $\Gamma A_{N_+}(\vec{\alpha}_0, \mathcal{L}_0)$ and an $\eta > 0$ such that

$$|F_{\mathcal{D}}(M, t') - F_{\mathcal{D}}(A_{N_+}(\vec{\alpha}_0, \mathcal{L}_0), t_n)| < \delta/2, \quad (7.34)$$

whenever $\Gamma M \in \mathcal{U}$ and $t' \in (t_n - \eta, t_n + \eta)$. For every integer $\tilde{N} \geq \eta^{-1}$ and $n = 1, \dots, N$, we can find a positive integer $m_n \leq \tilde{N}$ so that $\frac{m_n}{\tilde{N}_+} \in (t_n - \eta, t_n + \eta)$. This implies that $\mathcal{G}_{\mathcal{D}, \tilde{N}}(M) \geq \mathcal{G}_{\mathcal{D}}(A_{N_+}(\vec{\alpha}_0, \mathcal{L}_0)) = g_N(\vec{\alpha}_0, \mathcal{L}_0)$ for all $\Gamma M \in \mathcal{U}$ and $\tilde{N} \geq \eta^{-1}$.

We can now conclude the proof as for Theorem 5. Let $\vec{\alpha} \in P$. The density of the orbit $\{\Gamma A_{N_i + \frac{1}{2}}(\vec{\alpha}, \mathcal{L}) \mid i \in \mathbb{N}\}$ implies

$$\limsup_{i \rightarrow \infty} g_{N_i}(\vec{\alpha}, \mathcal{L}) \geq g_N(\vec{\alpha}_0, \mathcal{L}_0). \quad (7.35)$$

Theorem 2 now follows by taking the supremum over $N \in \mathbb{N}$. ■

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